

Common Best Proximity Results for Several Generalized Non-Self Alpha-Conjoint Proximal Beta-Quasi Contraction Mappings

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Abstract: Fixed point theory is a fundamental concept in mathematics, which ensures the existence and uniqueness of fixed points for self-mappings in complete metric spaces. The Banach contraction principle, explicitly stated in Banach's 1922 thesis, laid the groundwork for this field. However, for non-self mappings $H : F \rightarrow K$, where F and K are subsets of a metric space E , fixed points may not exist. This led to the development of best proximity point theory, which seeks to find elements f in F where $d(f, Hf) = d(F, K)$. This study introduces new concepts in the field of best proximity point theory, extending the existing framework with the formulation of *conjoint proximal β -quasi contraction*, *α -generalized conjoint proximal β -quasi contraction*, and *generalized conjoint β -quasi contraction*. These innovative constructs are utilized to investigate the existence of common best proximity points on metric spaces for both double and multiple non-self mappings. The research also presents a concrete example involving two non-self mappings, thereby illustrating the practical application of these theoretical concepts. Furthermore, the study explores various implications and consequences arising from these new formulations.

Keywords: Best proximity point, non-self mapping, P-property, approximately compact and special generalized proximal beta-quasi contraction

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1 Introduction

The evolution of this field has been marked by significant contributions from various mathematicians. Fan's 1969 best approximation theorem [1] acted as a catalyst, stimulating extensive subsequent research. S. Reich's 1972 [2] work extended Fan's theorem to set-valued inward functions. Between 1988 and 1989, Sehgal and colleagues [3]- [4] investigated best proximity points for non-self contractions, furthering the field's scope.

Kirk and colleagues (2003) [5] investigated proximality and best proximity point theorems in hyperconvex metric spaces within Hilbert spaces, offering optimal approximate solutions for mappings without fixed points. Sadiq Basha [6] established important existence conditions for proximal contractions of both first and second kinds. Jleli and collaborators [7] introduced a new category of non-self contractive mappings and examined the existence and uniqueness of best proximity points for these mappings.

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Recent advancements include Almeida et al.'s 2014 [8] application of P-property to locate best proximity points, and M. Ayari et al.'s findings on best proximity points for special generalized proximal beta-quasi contraction [9]. The field continues to expand, with ongoing research exploring concepts such as conjoint proximal β -quasi contraction, α -generalized conjoint β -quasi contraction, and their applications to finite numbers of non-self mappings on metric spaces.

This paper has led to a deeper understanding of fixed point theory and its extensions, providing powerful tools for analyzing diverse mathematical structures and their properties.

2 Preliminaries

This passage provides important definitions and notations. Let me summarize the key points:

Notation 1 For F and K nonempty subsets of a metric space (E, d) :

$$d(F, K) := \inf\{d(f, k) : f \in F, k \in K\},$$

$$F_0 := \{f \in F : \text{there exists } k \in K \text{ such that } d(f, k) = d(F, K)\},$$

$$K_0 := \{k \in K : \text{there exists } f \in F \text{ such that } d(f, k) = d(F, K)\}.$$

Definition 1. [6] For $H : F \rightarrow K$, an element f^* is a best proximity point of H if $d(f^*, Hf^*) = d(F, K)$.

Definition 2. [9] For $\chi : [0, +\infty) \rightarrow [0, +\infty)$ such that

1. χ is non-decreasing,
2. The $\lim_{n \rightarrow \infty} \chi_\beta^n(t) = 0$ such that $t > 0$ where χ_β^n the n -th iterate of χ_β and $\chi_\beta(t) = \chi(\beta t)$,
3. $s \in (0, +\infty)$ as $\sum_{n=1}^{\infty} \chi_\beta^n(s) < \infty$ exists.

For some $\beta \in (0, +\infty)$ and χ is called β -comparison function and denoted by Ξ_β .

Example 1. [9] For $\chi : [0, +\infty) \rightarrow [0, +\infty)$ where $\chi(t) = at$, $a \in (0, \beta^{-1})$ and $\beta > 0$ then $\chi \in \Xi_\beta$. Remark that, if $a > 1$ then $\chi(t) > t$ and so $\sum_{n=1}^{\infty} \chi^n(t) = \infty$

Lemma 1. [9] For $\chi \in \Xi_\beta$. We have

1. χ_β is non decreasing,
2. $\chi_\beta(t) < t$ for all $t > 0$,
3. $\sum_{n=1}^{\infty} \chi_\beta^n(t) < \infty$ for all $t > 0$.

Definition 3. [10] For nonempty subsets F and K of a metric space (E, d) . The nonempty subsets F and K of a metric space (E, d) will have P-property if

$$d(\xi_1, \eta_1) = d(\xi_2, \eta_2) = d(F, K) \implies d(\xi_1, \xi_2) = d(\eta_1, \eta_2)$$

such that $\xi_1, \xi_2 \in F$ and $\eta_1, \eta_2 \in K$.

Definition 4. [11] Approximately compact with respect to a nonempty subset F of a metric space (E, d) for a subset K of a metric space (E, d) iff

$$\lim_{n \rightarrow +\infty} d(\xi, \eta_n) = d(\xi, K).$$

3 Main Consequences

3.1 Best Proximity Point for Two Mappings

Definition 5. Consider F and K nonempty subsets of a metric space (E, d) . If

$$d(H\xi, G\eta) \leq \chi(M_{H,G}(\xi, \eta)), \quad \forall \xi, \eta \in F, \quad (1)$$

and

$$M_{H,G}(\xi, \eta) = \max\{\alpha_0 d(\xi, \eta), \alpha_1 (d(\xi, H\xi) - d(F, K)), \\ \alpha_2 (d(\eta, S\eta) - d(F, K)), \alpha_3 (d(\eta, H\xi) - d(F, K)), \\ \alpha_4 (d(\xi, G\eta) - d(F, K))\}.$$

whenever $\chi \in \Xi_\beta$ and positive numbers α_i , $i = 0, 1, 2, 3, 4$, $\beta \in (0, +\infty)$. So, $H, G : F \rightarrow K$ are called α -conjoint proximal β -quasi contraction mappings.

Let us give an example on definition 5

Example 2. Let $E = \mathbb{R}$ with $d(\xi, \eta) = |\xi - \eta|$ and $F = [0, 1]$ and $K = [0, 4]$. Since K is compact, then $K = [0, 4]$ is approximately compact with respect to $F = [0, 1]$. Moreover, For $H, G : F \rightarrow K$ define by $H(\xi) = \frac{\xi}{2}$ and $G(\xi) = \frac{\xi}{2} + 2$. Then $d(F, K) = 1$ and $F_0 = 1$, $K_0 = 2$. Thus, $H(F_0) = H(\{1\}) = \{2\} = K_0$ and $G(F_0) = G(\{1\}) = \{2\} = K_0$. H is conjoint proximal β -quasi contraction with $\chi(\xi) = \frac{1}{2}\xi$, $\beta = 2$, $\alpha_0 = 2$ and $\alpha_i = 0$ for $i = 1, 2, 3, 4$.

Now, since

$$L.H.S = d(H\xi, G\eta) = \left| \frac{\xi}{2} - \frac{\eta}{2} - 2 \right| \quad (2)$$

Also,

$$M_{H,G}(\xi, \eta) = \max\{\alpha_0 d(\xi, \eta), \alpha_1 (d(\xi, H\xi) - d(F, K)), \\ \alpha_2 (d(\eta, S\eta) - d(F, K)), \alpha_3 (d(\eta, H\xi) - d(F, K)), \\ \alpha_4 (d(\xi, G\eta) - d(F, K))\} \\ = \max\{2|\xi - \eta|, 0, 0, 0, 0\} = 2|\xi - \eta|$$

Moreover,

$$R.H.S = \chi(M_{H,G}(\xi, \eta)) = \chi(2|\xi - \eta|) = \frac{2|\xi - \eta|}{2} = |\xi - \eta| \quad (3)$$

Then, from equations (2) and (3), we get

$$L.H.S = d(H\xi, G\eta) = \left| \frac{\xi}{2} - \frac{\eta}{2} - 2 \right| = \frac{1}{2}|\xi - \eta - 4| \leq |\xi - \eta - 4| \leq |\xi - \eta| = \chi(M_{H,G}(\xi, \eta)) = R.H.S.$$

Theorem 2. For mappings H and G on nonempty closed subsets F and K of a complete metric space (E, d) where F_0 is nonempty. Let's break down the key components of this theorem:

1. The pair (F, K) satisfies P -property and $H(F_0) \subset K_0$, $G(F_0) \subset K_0$.

2. K is approximately compact with respect to F .

3. Occurring $\xi_1, \xi_2, \xi_3 \in F$ such that

$$d(\xi_2, H\xi_1) = d(\xi_3, G\xi_2) = d(F, K).$$

4. There occurs $\beta \geq \max_{0 \leq r \leq 3} \{\alpha_r, 2\alpha_4\}$ whereas H and G are α -conjoint proximal β -quasi contraction mappings.

In Addition, either χ is continuous, or $\beta > \max\{\alpha_2, \alpha_4\}$

Then under these conditions, either $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$ or H and G have a unique common best proximity point $\xi \in F$.

Proof . There exists $\xi_1 \in F_0$ such that $H(\xi_1) \in K_0$ because $H(F_0) \subseteq K_0$. As a result of condition 3, we obtain $\xi_2 \in F_0$ such that

$$d(\xi_2, H\xi_1) = d(F, K) \quad (4)$$

From condition 3 and $G(F_0) \subseteq K_0$, we deduce that there exists $\xi_3 \in F_0$ such that

$$d(\xi_3, G\xi_2) = d(F, K) \quad (5)$$

We derive from equations (4) and (5) that:

$$d(\xi_2, H\xi_1) = d(\xi_3, G\xi_2) = d(F, K).$$

We consider a sequence $\{\xi_n\} \subseteq F_0$ by repeating this procedure where

$$d(\xi_{n+2}, H\xi_{n+1}) = d(\xi_{n+3}, G\xi_{n+2}) = d(F, K), \quad n \in \{0\} \cup \mathbb{N}. \quad (6)$$

By using P -property condition, we get

$$d(\xi_{n+2}, \xi_{n+3}) = d(H\xi_{n+1}, G\xi_{n+2}), \quad n \in \{0\} \cup \mathbb{N}. \quad (7)$$

We'll now demonstrate that $\{\xi_n\}$ is a Cauchy sequence.

Since H and G are α -conjoint proximal β -quasi contraction, then

$$d(\xi_{n+2}, \xi_{n+3}) = d(H\xi_{n+1}, G\xi_{n+2}) \leq \chi(M_{H,G}(\xi_{n+1}, \xi_{n+2})) \quad (8)$$

And

$$\begin{aligned} M_{H,G}(\xi_{n+1}, \xi_{n+2}) &= \max\{\alpha_0 d(\xi_{n+1}, \xi_{n+2}), \alpha_1 (d(\xi_{n+1}, H\xi_{n+1}) - d(F, K)), \\ &\quad \alpha_2 (d(\xi_{n+2}, G\xi_{n+2}) - d(F, K)), \alpha_3 (d(\xi_{n+2}, H\xi_{n+1}) - d(F, K)), \\ &\quad \alpha_4 (d(\xi_{n+1}, G\xi_{n+2}) - d(F, K))\} \\ &= \max\{\alpha_0 d(\xi_{n+1}, \xi_{n+2}), \alpha_1 (d(\xi_{n+1}, H\xi_{n+1}) - d(F, K)), \\ &\quad \alpha_2 (d(\xi_{n+2}, G\xi_{n+2}) - d(F, K)), \alpha_4 (d(\xi_{n+1}, G\xi_{n+2}) - d(F, K))\} \\ &\leq \max\{\alpha_0 d(\xi_{n+1}, \xi_{n+2}), \alpha_1 d(\xi_{n+1}, \xi_{n+2}), \alpha_2 d(\xi_{n+2}, \xi_{n+3}), \\ &\quad \alpha_4 (d(\xi_{n+1}, \xi_{n+2}) + d(\xi_{n+2}, \xi_{n+3}))\} \\ &\leq \beta \max\{d(\xi_{n+1}, \xi_{n+2}), d(\xi_{n+2}, \xi_{n+3})\} \end{aligned}$$

By utilizing equations (6), (7), (8) as well as triangle inequality. As a result,

$$M_{H,G}(\xi_{n+1}, \xi_{n+2}) \leq \beta \max\{d(\xi_{n+1}, \xi_{n+2}), d(\xi_{n+2}, \xi_{n+3})\} \quad (9)$$

whereas $\beta \geq \max_{0 \leq r \leq 3} \{\alpha_r, 2\alpha_4\}$. From equations (8) and (9), we deduce

$$d(\xi_{n+2}, \xi_{n+3}) \leq \chi(\beta \max\{d(\xi_{n+1}, \xi_{n+2}), d(\xi_{n+2}, \xi_{n+3})\}) = \chi_\beta(\max\{d(\xi_{n+1}, \xi_{n+2}), d(\xi_{n+2}, \xi_{n+3})\})$$

If for some n , we have $d(\xi_{n+1}, \xi_{n+2}) \leq d(\xi_{n+2}, \xi_{n+3})$ and from lemma 1. It follows that $d(\xi_{n+2}, \xi_{n+3}) \leq \chi_\beta(d(\xi_{n+2}, \xi_{n+3})) < d(\xi_{n+2}, \xi_{n+3})$ which gives a contradiction.

Then for all $n \in \{0\} \cup \mathbb{N}$, we have $d(\xi_{n+2}, \xi_{n+3}) < d(\xi_{n+1}, \xi_{n+2})$ and it follows that

$$d(\xi_{n+2}, \xi_{n+3}) \leq \chi_\beta(d(\xi_{n+1}, \xi_{n+2})) \quad n \in \{0\} \cup \mathbb{N} \quad (10)$$

Then, by establishing an inductive relationship for the distances between successive terms of a sequence ξ_n :

$$d(\xi_{n+2}, \xi_{n+3}) \leq \chi_\beta^n(d(\xi_2, \xi_1)) \quad n \in \{0\} \cup \mathbb{N} \quad (11)$$

Let $\varepsilon > 0$ be fixed. Since $\sum_{n=1}^{+\infty} \chi_{\beta}^n(d(\xi_2, \xi_1))$ converges, occurs $n_0 \in \mathbb{Z}^+$ whereas $\sum_{n \geq n_0} \chi_{\beta}^n(d(\xi_2, \xi_1)) < \varepsilon$. For $m > n > n_0$ and equation (11), we obtain

$$\begin{aligned} d(\xi_n, \xi_m) &\leq \sum_{k=n}^{m-1} d(\xi_k, \xi_{k+1}) \\ &\leq \sum_{k=n}^{m-1} \chi_{\beta}^k(d(\xi_2, \xi_1)). \end{aligned}$$

Since $\sum_{n=1}^{+\infty} \chi_{\beta}^n(t)$ converges for all $t \geq 0$; as a result

$$\sum_{k=n}^{m-1} \chi_{\beta}^k(d(\xi_2, \xi_1)) \rightarrow 0 \quad \text{as } n, m \rightarrow +\infty.$$

It then proves that $\{\xi_n\}$ is Cauchy using F is closed in a complete metric (E, d) , so the sequence $\{\xi_n\}$ converges to some element $\xi \in F$.

Moreover,

$$\begin{aligned} d(\xi, K) &\leq d(\xi, H\xi_{n+1}) \\ &\leq d(\xi, \xi_{n+2}) + d(\xi_{n+2}, H\xi_{n+1}) \\ &= d(\xi, \xi_{n+2}) + d(F, K) \\ &\leq d(\xi, \xi_{n+2}) + d(\xi, K). \end{aligned}$$

If $n \rightarrow \infty$, so $d(\xi, H\xi_{n+1})$ converges to $d(\xi, K)$. According to condition (2), then there exists a sub sequence $\{\xi_{n(k)}\}$ of $\{\xi_n\}$ for which $\{H\xi_{n(k)}\}$ converges to some $\eta \in K$. Similarly, we may deduce that $\{\xi_{n(k)}\}$ is a sub sequence of $\{\xi_n\}$ such that $\{G\xi_{n(k)}\}$ converges to $\eta^* \in K$.

So,

$$\begin{aligned} d(F, K) &\leq d(\xi, \eta) \\ &\leq d(\xi, \xi_{n_k+1}) + d(\xi_{n_k+1}, H\xi_{n_k}) + d(H\xi_{n_k}, \eta) \\ &= d(\xi, \xi_{n_k+1}) + d(F, K) + d(H\xi_{n_k}, \eta). \end{aligned}$$

While $n \rightarrow \infty$, so $d(\xi, \eta) = d(F, K)$ and $\xi \in F_0$.

Since $G(F_0) \subset K_0$, there exists $u \in F$ where $d(u, G\xi) = d(F, K)$. Therefore, we find $d(u, G\xi) = d(\xi_{n+2}, H\xi_{n+1}) = d(F, K)$. According to P -property, we conclude that $d(u, \xi_{n+2}) = d(G\xi, H\xi_{n+1})$.

Since H, G are α -conjoint proximal β -quasi contraction mappings, we find

$$\begin{aligned} d(u, \xi_{n+2}) &= d(H\xi_{n+1}, G\xi) \\ &\leq \chi(M_{H,G}(\xi_{n+1}, \xi)) \quad \forall n \in \{0\} \cup \mathbb{N}, \end{aligned} \tag{12}$$

where

$$\begin{aligned} M_{H,G}(\xi_{n+1}, \xi) &= \max\{\alpha_0 d(\xi_{n+1}, \xi), \alpha_1 (d(\xi_{n+1}, H\xi_{n+1}) - d(F, K)), \\ &\quad \alpha_2 (d(\xi, G\xi) - d(F, K)), \alpha_3 (d(\xi, H\xi_{n+1}) - d(F, K)), \\ &\quad \alpha_4 (d(\xi_{n+1}, G\xi) - d(F, K))\}. \end{aligned} \tag{13}$$

Further, from (6),

$$\begin{aligned} M_{H,G}(\xi_{n+1}, \xi) &= \max\{\alpha_0 d(\xi_{n+1}, \xi), \alpha_1 d(\xi_{n+1}, \xi_{n+2}), \\ &\quad \alpha_2 (d(\xi, G\xi) - d(F, K)), \alpha_3 d(\xi, \xi_{n+2}), \\ &\quad \alpha_4 (d(\xi_{n+1}, \xi) + d(\xi, G\xi) - d(F, K))\}. \end{aligned} \tag{14}$$

From triangle inequality and equation (6), we get

$$\begin{aligned} d(\xi, G\xi) &\leq d(\xi, \xi_{n+2}) + d(\xi_{n+2}, H\xi_{n+1}) + d(H\xi_{n+1}, G\xi) \\ &= d(\xi, \xi_{n+2}) + d(F, K) + d(H\xi_{n+1}, G\xi) \quad \forall n \in \{0\} \cup \mathbb{N}. \end{aligned} \tag{15}$$

From (15) and (12), then

$$d(\xi, G\xi) - d(\xi, \xi_{n+2}) - d(F, K) \leq \chi(M_{H,G}(\xi_{n+1}, \xi)), \quad \forall n \in \{0\} \cup \mathbb{N}. \quad (16)$$

The proof then considers $f = d(\xi, G\xi) - d(F, K)$, and let $n \rightarrow +\infty$ in (14), we find

$$\lim_{n \rightarrow +\infty} M_{H,G}(\xi_{n+1}, \xi) \leq \max\{\alpha_2, \alpha_4\}f \quad (17)$$

Say $f \geq 0$, χ continuous and non decreasing. Also, $n \rightarrow +\infty$ in (16), we get

$$f \leq \chi(\max\{\alpha_2, \alpha_4\}f) \leq \chi(\beta f) = \chi_\beta(f) < f,$$

when $\beta > \max\{\alpha_2, \alpha_4\}$ a contradiction occurs. We further argue $f = 0$. Suppose that $f > 0$.

From (17) then, there exist $\varepsilon > 0$ and $N > 0$ such that, for all $n > N$, we have $M_{H,G}(\xi_{n+1}, \xi) < (\max\{\alpha_2, \alpha_4\} + \varepsilon)f$. Since χ is non decreasing, from (17), resulting

$$\begin{aligned} d(\xi, G\xi) - d(\xi, \xi_{n+2}) - d(F, K) &\leq \chi(M_{H,G}(\xi_{n+1}, \xi)) \\ &\leq \chi((\max\{\alpha_2, \alpha_4\} + \varepsilon)f) \\ &= \chi_\beta\left(\frac{\max\{\alpha_2, \alpha_4\} + \varepsilon}{\beta}f\right) \\ &< \frac{\max\{\alpha_2, \alpha_4\} + \varepsilon}{\beta}f < f \end{aligned} \quad (18)$$

For $n \rightarrow +\infty$ in (18), we have

$$f < \frac{\max\{\alpha_2, \alpha_4\} + \varepsilon}{\beta}f < f$$

This result causes a contradiction. Wherefore, f must be zero or $d(\xi, G\xi) - d(F, K) = 0$. As a response $d(\xi, G\xi) = d(F, K)$, proving that ξ is the best proximity point of G .

Similarly, we can get that ξ is the best proximity point of H or $d(\xi, G\xi) = d(\xi, H\xi) = d(F, G)$. In another word, H and G have a common best proximity point $\xi \in F$. Whereas $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$.

This rigorous proof establishes the existence of a best proximity point for the mapping G under the given conditions. The approach could likely be adapted to prove a similar result for H , leading to the conclusion of a common best proximity point for both H and G .

To prove the uniqueness, let ξ and θ two separate best proximity points such that $d(\xi, H\xi) = d(\xi, G\xi) = d(\theta, H\theta) = d(\theta, G\theta) = d(F, K)$. From P -property condition, we found $d(\xi, \theta) = d(H\xi, G\theta)$.

Further, since H and G are α -conjoint proximal β -quasi contraction mappings, thus we conclude that

$$d(\xi, \theta) = d(H\xi, G\theta) \leq \chi(M_{H,G}(\xi, \theta)),$$

Where

$$M_{H,G}(\xi, \theta) = \max\{\alpha_0 d(\xi, \theta), \alpha_3 (d(\theta, H\xi) - d(F, K)), \alpha_4 (d(\xi, G\theta) - d(F, K))\}.$$

We drive from triangular inequalities in $M_{H,G}(\xi, \theta)$ and ξ and θ are best proximity points for H and G that:

$$M_{H,G}(\xi, \theta) \leq \max\{\alpha_0, \alpha_3, \alpha_4\}d(\xi, \theta).$$

Let's say $r = d(\xi, \theta)$. Since χ is non decreasing, we observe

$$r \leq \chi(\max\{\alpha_0, \alpha_3, \alpha_4\}r) \leq \chi(\beta r) = \chi_\beta(r) < r,$$

That make a discrepancy. So, $\xi = \theta$. Then H and G have a unique common best proximity point $\xi \in F$ such that $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$.

Remark. If we put in the contraction $G = H$ in the last theorem, we get the results in Mohamed Jleli and Ayari [[7], [11]] as a spacial case.

Example 3. Let $E = \mathbb{R}$ with $d(\xi, \eta) = |\xi - \eta|$ and $F = [0, 1]$ and $K = [0, 4]$. Since K is compact, then $K = [0, 4]$ is approximately compact with respect to $F = [0, 1]$. Moreover, For $H, G : F \rightarrow K$ define by $H(\xi) = \frac{\xi}{2}$ and $G(\xi) = \frac{\xi}{2} + 2$. Then $d(F, K) = 1$ and $F_0 = 1, K_0 = 2$. Thus, $H(F_0) = H(\{1\}) = \{2\} = K_0$ and $G(F_0) = G(\{1\}) = \{2\} = K_0$. H is conjoint proximal β -quasi contraction with $\chi(\xi) = \frac{1}{2}\xi, \beta = 2, \alpha_0 = 2$ and $\alpha_i = 0$ for $i = 1, 2, 3, 4$.

Since

$$d(H\xi, G\eta) = \left| \frac{\xi}{2} - \frac{\eta}{2} - 2 \right|$$

Also,

$$\begin{aligned} M_{H,G}(\xi, \eta) &= \max\{\alpha_0 d(\xi, \eta), \alpha_1 (d(\xi, H\xi) - d(F, K)), \\ &\quad \alpha_2 (d(\eta, S\eta) - d(F, K)), \alpha_3 (d(\eta, H\xi) - d(F, K)), \\ &\quad \alpha_4 (d(\xi, G\eta) - d(F, K))\} \\ &= \max\{2|\xi - \eta|, 0, 0, 0, 0\} = 2|\xi - \eta| \end{aligned}$$

And

$$\chi(M_{H,G}(\xi, \eta)) = \chi(2|\xi - \eta|) = \frac{2|\xi - \eta|}{2} = |\xi - \eta|$$

So,

$$d(H\xi, G\eta) = \left| \frac{\xi}{2} - \frac{\eta}{2} - 2 \right| = \frac{1}{2}|\xi - \eta - 4| \leq |\xi - \eta| = M_{H,G}(\xi, \eta) = \frac{1}{2}\max\{2d(\xi, \eta), 0, 0, 0, 0\}$$

Since $\chi(\xi)$ is continuous mapping and $\beta = 2 \geq \max\{\alpha_2, \alpha_4\} = 0$. Also, by Theorem 2, we deduce that H and G have a unique common best proximity point which is $\xi^* = 1$. That is,

$$d(\xi^*, H\xi^*) = d(1, H(1)) = d(1, 2) = d(\xi^*, G\xi^*) = d(1, G(1)) = d(1, 2) = d(F, K) = 1.$$

3.2 Best Proximity Point for Several Mappings

Theorem 3. For of nonempty closed subsets F and K of a complete metric space (E, d) be whereas F_0 is nonempty. For which the system of non-self-mappings $H_i : F \rightarrow K$ and $i = 1, 2, \dots, n$ where:

1. $H_i(F_0) \subset K_0$ for each $i = 1, 2, \dots, n$ and (F, K) structure the P -property,
2. K is approximately compact with respect to F ,
3. occurring $\xi_i, \xi_{i+1}, \xi_{i+2} \in F$ whereas

$$d(\xi_{i+1}, H_i \xi_i) = d(\xi_{i+2}, H_{i+1} \xi_{i+1}) = d(F, K)$$

for each $i = 1, 2, \dots, n$,

4. There $\beta \geq \max_{0 \leq h \leq 3} \{\alpha_h, 2\alpha_4\}$ whereas H_i and H_{i+1} are conjoint proximal β -quasi contraction for each $i = 1, 2, \dots, n$.

Moreover, either one χ is continuous or $\beta > \max\{\alpha_2, \alpha_4\}$.

Then the mappings $H_1, H_2, \dots, H_n$ have a unique common best proximity point $\xi \in F$ whereas $d(\xi, H_1 \xi) = d(\xi, H_2 \xi) = \dots = d(\xi, H_n \xi) = d(F, K)$.

Proof . If we start with $i = 1$ then all conditions in theorem 2 are hold. So, there exists $\theta_1 \in F_0$ such that θ_1 is a unique common best proximity point between H_1 and H_2 . i.e

$$d(\theta_1, H_1 \theta_1) = d(\theta_1, H_2 \theta_1) = d(F, K). \quad (19)$$

Similarly, if we but $i = 2$ then there exists $\theta_2 \in F_0$ such that θ_2 is a unique common best proximity point between H_2 and H_3 , i.e

$$d(\theta_2, H_2\theta_2) = d(\theta_2, H_3\theta_2) = d(F, K). \quad (20)$$

Now, we want to prove that $\theta_1 = \theta_2$. From (19), (20) and using P-property, we get

$$d(\theta_1, \theta_2) = d(H_1\theta_1, H_2\theta_2) \quad (21)$$

So, from (19)-(21), triangle inequality, condition (4) in theorem 3 and the definition of α -conjoint proximal β -quasi contraction mappings for H_1 and H_2 , we have

$$\begin{aligned} d(\theta_1, \theta_2) &= d(H_1\theta_1, H_2\theta_2) \\ &\leq \chi(M_{H_1, H_2}(\theta_1, \theta_2)) \\ &= \chi(\max\{\alpha_0 d(\theta_1, \theta_2), \alpha_1(d(\theta_1, H_1\theta_1) - d(F, K)), \\ &\quad \alpha_2(d(\theta_2, H_2\theta_2) - d(F, K)), \alpha_3(d(\theta_2, H_1\theta_1) - d(F, K)), \\ &\quad \alpha_4(d(\theta_1, H_2\theta_2) - d(F, K))\}) \\ &\leq \chi(\max\{\alpha_0 d(\theta_1, \theta_2), \alpha_3 d(\theta_1, \theta_2), \alpha_4 d(\theta_1, \theta_2)\}) \\ &\leq \chi(d(\theta_1, \theta_2) \max\{\alpha_0, \alpha_3, \alpha_4\}) \\ &\leq \chi(\beta d(\theta_1, \theta_2)) = \chi_\beta(d(\theta_1, \theta_2)) \leq d(\theta_1, \theta_2). \end{aligned}$$

which gives a contradiction. Then $\theta_1 = \theta_2 = \theta$. i.e

$$d(\theta, H_1\theta) = d(\theta, H_2\theta) = d(\theta, H_3\theta) = d(F, K).$$

So, occurs a unique common best proximity point θ between H_1, H_2 and H_3 .

By repeating this manner for $i=3$. We will find θ_3 such that:

$$d(\theta_3, H_3\theta_3) = d(\theta_3, H_4\theta_3) = d(H, K).$$

and $\theta_3 = \theta_2 = \theta$.

Hence,

$$d(\theta, H_1\theta) = d(\theta, H_2\theta) = d(\theta, H_3\theta) = d(\theta, H_4\theta) = d(F, K).$$

Then occurs a unique common best proximity point θ between H_1, H_2, H_3 and H_4 .

Hence, for finite number n . We reach to, occurs a unique common best proximity point θ between $H_1, H_2, H_3, \dots, H_n$.

4 Repercussions

Many of the repercussions of section 3 examined in this section.

We suggest the following results in the situation of two functions.

Definition 6. Let F and K be two nonempty subsets of a metric space (E, d) . Two non-self-mappings $H, G : F \rightarrow K$ are said to be conjoint proximal β -quasi contraction mappings iff there exist $\chi \in \Xi_\beta$ such that:

$$d(H\xi, G\eta) \leq \chi(M_{H,G}^*(\xi, \eta)), \quad \forall \xi, \eta \in F, \quad (22)$$

where

$$\begin{aligned} M_{H,G}^*(\xi, \eta) &= \max\{d(\xi, \eta), (d(\xi, H\xi) - d(F, K)), \\ &\quad (d(\eta, G\eta) - d(F, K)), (\frac{(d(\eta, H\xi) + d(\xi, G\eta))}{2} - d(F, K))\}. \end{aligned}$$

whenever $\beta \in (0, +\infty)$.

In the next corollary, we investigate the presence of a common best proximity point in the case of *conjoint proximal β -quasi-contraction mappings* in our main theorem 2 and $\alpha_i = 1$ for each $i = 0, 1, 2, 3, 4$ as:

Corollary 1. For non empty closed subsets F, K of a complete metric space (E, d) and F_0 is nonempty. For non-self mappings $H, G : F \rightarrow K$ whereas:

1. Let (F, K) have P -property and $H(F_0) \subset K_0, G(F_0) \subset K_0$,
2. K is approximately compact with respect to F ,
3. Occurring $\xi_1, \xi_2, \xi_3 \in F$ whereas

$$d(\xi_2, H\xi_1) = d(\xi_3, G\xi_2) = d(F, K).$$

4. Occurs $\chi \in \Xi_2$ whereas

$$d(H\xi, G\eta) \leq \chi(M_{H,G}^*(\xi, \eta)), \quad \forall \xi, \eta \in F. \quad (23)$$

Then H, G a unique best proximity point $\xi \in F$ such that $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$.

Proof . Since

$$\begin{aligned} M_{H,G}^*(\xi, \eta) &= \max\{d(\xi, \eta), (d(\xi, H\xi) - d(F, K)), \\ &\quad (d(\eta, G\eta) - d(F, K)), (\frac{(d(\eta, H\xi) + d(\xi, G\eta))}{2} - d(F, K))\} \\ &\leq \max\{d(\xi, \eta), (d(\xi, H\xi) - d(F, K)), \\ &\quad (d(\eta, G\eta) - d(F, K)), (d(\eta, H\xi) - d(F, K)), \\ &\quad d(\xi, H\eta) - d(F, K)\} \\ &= M_{H,G}(\xi, \eta). \end{aligned}$$

Also, the comparison function $\chi \in \Xi_2$ where $\beta \geq 2 > \max\{\alpha_2, \alpha_4\} = 1$. From theorem 2, H and G a unique common proximity point in F .

When we put $\alpha_i = 1$ in theorem 2 for each $i = 0, 1, 2, 3, 4$ and replace χ by some $q \in [0, 1)$ by some way we found that:

Corollary 2. For a nonempty closed subsets F, K of a complete metric space (E, d) whereas F_0 is nonempty. And $H, G : F \rightarrow K$ where:

1. $H(F_0) \subset K_0, G(F_0) \subset K_0$ and (F, K) holds the P -property,
2. K is approximately compact with respect to F ,
3. occurring $\xi_1, \xi_2, \xi_3 \in F$ whereas

$$d(\xi_2, H\xi_1) = d(\xi_3, G\xi_2) = d(F, K).$$

4. occurs $q \in [0, 1)$ whereas

$$d(H\xi, G\eta) \leq qM_{H,G}^-(\xi, \eta) \quad \forall \xi, \eta \in F,$$

where

$$\begin{aligned} M_{H,G}^-(\xi, \eta) &= \max\{d(\xi, \eta), (d(\xi, H\xi) - d(F, K)), \\ &\quad (d(\eta, G\eta) - d(F, K)), (d(\eta, H\xi) - d(F, K)), (d(\xi, G\eta) - d(F, K))\}. \end{aligned}$$

Then H, G have a unique best proximity point $\xi \in F$ whereas $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$.

Proof . Let $\chi = qt$ which is continuous. From theorem 2, then H, G have a unique best proximity point $\xi \in F$ whereas $d(\xi, H\xi) = d(\xi, G\xi) = d(F, K)$.

Let's look at the common best proximity point for two self mappings for α -conjoint β -quasi contraction as follows:

Definition 7. For a nonempty subset F of a metric space (E, d) the two self-mappings $H, G : F \rightarrow F$ are called α -generalized conjoint β -quasi contraction if occurring $\chi \in \Xi_\beta$ and $\alpha_i \geq 0$ for $i = 0, 1, 2, 3, 4$, such that:

$$d(H\xi, G\eta) \leq \chi(\mu_{H,G}(\xi, \eta)), \quad \forall \xi, \eta \in F, \quad (24)$$

where

$$\mu_{H,G}(\xi, \eta) = \max\{\alpha_0 d(\xi, \eta), \alpha_1 d(\xi, H\xi), \alpha_2 d(\eta, G\eta), \alpha_3 d(\eta, H\xi), \alpha_4 d(\xi, G\eta)\}.$$

whenever $\beta \in (0, +\infty)$.

Corollary 3. For a α -generalized conjoint β -quasi contraction between H and G on a complete metric space (E, d) . Moreover, for any one of:

- χ is continuous;
- $\beta > \max\{\alpha_2, \alpha_4\}$

Then H and G have a unique common fixed point in E .

Proof. If we put $F = K$ in the definition of α -conjoint β -quasi contraction mappings then $\mu_{H,G}(\xi, \eta) = M_{H,G}(\xi, \eta)$ and $d(F, K) = 0$. So, since all conditions of theorem 2 are satisfied, then H, G have a unique common fixed point in E .

Now we will discuss a common fixed point for two self mappings for generalized conjoint β -quasi contraction as:

Definition 8. Two self-mappings $H, G : F \rightarrow F$ over a nonempty subset F of a metric space (E, d) are called generalized conjoint β -quasi contraction if it occurs $\chi \in \Xi_\beta$ whereas

$$d(H\xi, G\eta) \leq \chi(\mu_{H,G}^*(\xi, \eta)), \quad \forall \xi, \eta \in F,$$

where

$$\mu_{H,G}^*(\xi, \eta) = \max\{d(\xi, \eta), d(\xi, H\xi), d(\eta, G\eta), d(\eta, H\xi), d(\xi, G\eta)\}.$$

whenever $\beta \in (0, +\infty)$.

Corollary 4. Assume that, the two mappings H and G are generalized conjoint β -quasi contraction on a complete metric space (E, d) and χ is continuous. So, H and G have a unique common fixed point in E .

Proof. Since $F = K = E$ and any set is approximately compact with itself, this is an obvious consequence of our fundamental theorem 2 where $\mu_{H,G}^*(\xi, \eta) = M_{H,G}(\xi, \eta)$ in theorem 2. Furthermore, on the self-mapping situation, the idea of generalized conjoint β -quasi contraction is a β -quasi contraction one. Then H, G have a unique common fixed point in E .

If for $H = G$ in the last definition we recall generalized conjoint β -quasi contraction by generalized β -quasi contraction then we will find the next corollary:

Corollary 5. Let (E, d) be a complete metric space. Suppose that H is a generalized β -quasi contraction and χ is continuous. Then H has a unique fixed point in E .

Proof. If we put $H = G$ in corollary 4. Then, we get that H has a unique fixed point in E .

5 Application

Around this part, we discuss an application of Theorem 2 in Volterra type integral equations. Consider the following integrals

$$r(m) = \int_0^m \Lambda_1(m, s, r(s)) ds + f(m), \quad (25)$$

$$\sigma(m) = \int_0^m \Lambda_2(m, s, \sigma(s)) ds + g(m), \quad (26)$$

for all $m \in [0, a]$. Let $\mathcal{C}[0, a]$ be the set of all continuous functions defined on $[0, a]$. For $r \in \mathcal{C}[0, a]$ with the norm

$$\|r\|_\infty = \max_{m \in [0, 1]} |r(m)|$$

with metric

$$d(r, \sigma) = \|(r - \sigma)\|_\infty = \max_{m \in [0, 1]} |r(m) - \sigma(m)|$$

for all $r, \sigma \in \mathcal{C}[0, a]$. With these setting $(\mathcal{C}[0, 1], \|\cdot\|_\infty)$ becomes Banach space. Now we prove the following theorem to ensure the existence of solution of the system of integral equations (25), (26).

Now for $F = \mathcal{C}[0, a]$, $K = \mathcal{C}[0, b]$ and $d(F, K) = \inf\{d(x, k) \mid x \in \mathcal{C}[0, a] \text{ and } k \in \mathcal{C}[0, b]\}$.

Hence,

$$F_0 = \{x \in \mathcal{C}[0, a] \mid \text{there exists } k \in \mathcal{C}[0, b] \text{ s.t. } d(x, k) = d(\mathcal{C}[0, a], \mathcal{C}[0, b])\}$$

$$K_0 = \{k \in \mathcal{C}[0, b] \mid \text{there exists } x \in \mathcal{C}[0, a] \text{ s.t. } d(x, k) = d(\mathcal{C}[0, a], \mathcal{C}[0, b])\}$$

Theorem 4. Consider $\Lambda_1, \Lambda_2 : [0, a] \times [0, a] \times \mathbb{R} \rightarrow \mathbb{R}$, $f, g : [0, a] \rightarrow \mathbb{R}$ are continuous and $H, G : \mathcal{C}[0, a] \rightarrow \mathcal{C}[0, b]$ as

$$Hr(m) = \int_0^m \Lambda_1(m, s, r(s)) ds + f(m), \quad (27)$$

$$G\sigma(m) = \int_0^m \Lambda_2(m, s, \sigma(s)) ds + g(m), \quad (28)$$

1. $\mathcal{C}[0, a]$ and $\mathcal{C}[0, b]$ satisfies P-property in addition $H(F_0) \subset K_0, G(F_0) \subset K_0$,
2. $\mathcal{C}[0, b]$ is approximately compact with respect to $\mathcal{C}[0, a]$,
3. Occurring $\xi_1, \xi_2, \xi_3 \in \mathcal{C}[0, a]$ such that

$$d(\xi_2, H\xi_1) = d(\xi_3, G\xi_2) = d(\mathcal{C}[0, a], \mathcal{C}[0, b]),$$

4. Occurs $\beta \geq \max_{0 \leq h \leq 3} \{\alpha_h, 2\alpha_4\}$ whereas H and G are α -conjoint proximal β -quasi contraction mappings.

In Addition, either χ is continuous, or $\beta > \max\{\alpha_2, \alpha_4\}$

Also, If we have

$$|\Lambda_1(m, s, r(s)) - \Lambda_2(m, s, \sigma(s))| + |f(m) - g(m)| \leq \frac{\beta}{m} (|M(H, G)(r(m), \sigma(m))|) \quad (29)$$

for some $m \in [0, a]$, and $r, \sigma \in \mathcal{C}[0, a]$ then the system of integral equations (25) and (26) has a solution (a unique common best proximity point $\xi \in \mathcal{C}[0, a]$).

Proof . Choosing x^* and k^* to be among the best approximations of $G\sigma$ and Hr , we have

$$\begin{aligned}
 d(Hr, G\sigma) &= \max_{t \in [0,1]} |(Hr(m) - G\sigma(m))| \\
 &= \max_{m \in [0,1]} (|\Lambda_1(m, s, r(s)) - \Lambda_2(m, s, \sigma(s))| ds + |f(m) - g(m)|) \\
 &\leq \frac{\beta}{m} \left(\int_0^m \max_{m \in [0,1]} |M(H, G)(r(s), \sigma(s))| ds \right) \\
 &= \frac{\beta}{m} \int_0^m \|M(H, G)(r, \sigma)\|_\infty ds \\
 &= \frac{\beta}{m} \|M(H, G)(r, \sigma)\|_\infty \int_0^m ds \\
 &= \frac{\beta}{m} \|M(H, G)(r, \sigma)\|_\infty m \\
 &= \beta \|M(H, G)(r, \sigma)\|_\infty
 \end{aligned}$$

So, from theorem 2. Hence occurs $\theta \in \mathfrak{C}[0, a]$ whereas

$$\begin{aligned}
 d(H\theta(m), \theta(m)) &= d(G\theta(m), \theta(m)) \\
 &= d(\mathfrak{C}[0, a], \mathfrak{C}[0, b]) \\
 &= \inf_{x \in \mathfrak{C}[0, a], k \in \mathfrak{C}[0, b]} d(x, k)
 \end{aligned}$$

whereas $\theta(m)$ is a solution of equations (25) and (26).

On the other hand, There are several applications in nonlinear Volterra integral equation. For example, application on Abel-type nonlinear Volterra integral equation in Heat Radiation in a Semi-Infinite Solid, which is given by

$$u(r) = \frac{1}{\sqrt{\pi}} \int_0^r \frac{f(s) - u^n(s)}{\sqrt{r-s}} ds$$

where $u(x)$ gives the temperature at the surface for all time.

6 Main text

A non-self mapping $H : F \rightarrow K$, where F and K are subsets of a metric space E , does not have in general a fixed point. As a result, many people try to locate an element f that is closest to Hf in some way which is called *best proximity* point. Ayari achieved the best proximity point findings for a non-self mapping $H : F \rightarrow K$ known as special generalized proximal β -quasi contraction in 2019. The field continues to expand, with ongoing research exploring concepts such as conjoint proximal β -quasi contraction, α -generalized conjoint β -quasi contraction, and their applications to finite numbers of non-self mappings on metric spaces. This paper has led to a deeper understanding of fixed point theory and its extensions, providing powerful tools for analyzing diverse mathematical structures and their properties as follows:

6.1 Common best proximity point for two non-self mappings.

First, we defined the concept of α conjoint proximal β -quasi contraction. Also, we proved a unique common best proximity point between two mappings using this concept. Moreover, we enhanced our result by inserting an example.

6.2 Common best proximity point for several non-self mappings.

Second, we proved a unique common best proximity point results between several mappings.

6.3 Repercussions

Third, we inserted some new definitions *conjoint proximal β -quasi contraction mappings*, *α -generalized conjoint β -quasi contraction*, *generalized conjoint β -quasi contraction* and *generalized β -quasi contraction*. Also, we used these new concepts to derive some repercussions.

6.4 Application

Fourth, we gave an application in integral equations.

7 List of abbreviations

$d(F, K)$, F_0 , K_0 , β -Quasi contraction, α conjoint proximal β -quasi contraction, conjoint proximal β -quasi contraction mappings, α -generalized conjoint β -quasi contraction, generalized conjoint β -quasi contraction and generalized β -quasi contraction.

Availability of data and material

Data sharing is not applicable to this article as no datasets were generated or analyzed during the current study.

Conflict of interest

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