Robust Mixture Regression Estimation Based on least trimmed sum of absolute Method by using Several Models

Batool Shaaban^{*}, Nahed Helmy^{*}, Mervat Elgohary^{*}

Abstract

The present study deals with one of the most important methods of the robust mixture regression estimators, least trimmed sum of absolute deviations LTA method. It is known that mixture regression models are used to investigate the relationship between variables that come from unknown latent groups and to model heterogenous datasets. In general, the error terms are assumed to be normal in the mixture regression model. However, the estimators under normality assumption are sensitive to the outliers. Therefore, we introduce a robust mixture regression procedure based on the LTA-estimation method to combat with the outliers in the data. In this paper, we handle LTA method by using three mixture regression models; Laplace, t and normal distributions. We give a simulation study to illustrate the performance of the proposed estimators over the counterparts in terms of dealing with outliers.

Keywords: *EM algorithm, LTA-estimation method, Mixture regression model, Robust regression.*

1. Introduction

Bassett (1991) and Tableman (1994 *a*, *b*) proposed the *least trimmed sum* of absolute(LTA) deviations through minimizing the sum of the smallest absolute residuals:

$min\sum_{i=1}^{h}|r_i|_{j:n},\qquad (1)$

where r shows the residuals which $r_i = y_j - x'_j \beta$ and $|r_i|_{1:n} \leq \cdots \leq |r_i|_{n:n}$ are the ordered absolute residuals, $h = (n(1 - \alpha) + 1)$, is the number of observations after trimming, and α is the trimming proportion (Dogru and Arslan 2017). It is worth noting that we will use this criterion as a robust criterion. Hawkins and Olive (1999) proved that LTA is an attractive alternative toLeast Median of SquaresLMS and Least Trimmed Squares LTS, particularly for large data sets. It has a statistical efficiency that is not much below that of LTS for outlier-free normal data and better than LTS for more peaked error distributions. They proved that its computational complexity is of a lower order than LMS and LTS. They used very simple calculations for finding exact evaluation of the LTA to outline a "feasible solution algorithm" for sample too large, which provide excellent approximations to the exact LTA solution. Several authors have examined the LTA estimator in the location model (a model including an intercept, but no nontrivial predictors). For the location model, Bassett (1991) gives an algorithm, and Tableman (1994 **a**, **b**) derives the influence function and asymptotic. In the regression model, LTA is a special case of the R-estimators of H⁻ossjer (1991, 1994). LTA (γ) have breakdown value at **min(1 - \gamma, \gamma)** [See H⁻ossjer (1994)]. Croux, *et al.* (1996) showed that the maxbias curve of LTA is lower than that of LTS.

* Al- Azhar Universit Faculty of Commerce - Girls' Branch Department of Statistics.

This paper is organized as follows: Section (2) presents LTA method by using Laplace mixture regression model and EM algorithm for parameters estimation. Section (3) presents LTA method by using t mixture regression model and EM algorithm for parameters estimation. Section (4) shows the LTA method by using normal mixture regression model and EM algorithm for parameters estimation. Section (5) presents a simulation study with the comparisons which are made with some existing procedures in the literature. Conclusions are discussed in Section (6).

2. LTA Method by using Laplace Distribution

2.1 Definition

Let **Y** is an $n \times 1$ vector of dependent variables, **X** is an $n \times p$ matrix of predictors, and $\boldsymbol{\epsilon}_i$ is an $n \times 1$ vector of errors. The relationship between **Y** and **X** is often investigated through a linear regression model. In the mixture linear regression procedure, we assume that with probability π_i , i = 1, 2, ..., g, (X^T, Y) comes from one of the following $g \ge 2$ linear regression models:

$$Y = X^T \beta_i + \sigma_i \epsilon_i, i = 1, 2, \dots, g, g \ge 2$$
⁽²⁾

where $\sum_{i=1}^{q} \pi_i = 1, \beta_i$ s' are unknown *p*-dimensional vectors of regression coefficients, $\sigma_i s'$ are unknown positive scalars. The random errors $\varepsilon_i s'$ are assumed to be independent of X_i s'. It is commonly assumed that the density functions of **E**_is' are members in a location-scale family with mean 0 and variance 1. Song et al. (2014) proposed a robust estimation procedure for the mixture linear regression models based on Laplacedistribution by usingleast absolute deviation(LAD) method. This research deals with the same equations as in Song et al. (2014), but at using trimmed version, the LTA technique, instead of the less robustly LAD, for achieving robustness. Therefore, we assume that E follows a Laplace or a double exponential distribution with location 0 and scale parameter $\frac{1}{\sqrt{2}}$, which makes the variance of $\boldsymbol{\varepsilon}_i$ being 1, $i = 1, 2, \dots, g$. Then it is easily seen that for а sample $S = \{ (X_i^T, Y_j), j = 1, 2, ..., n \}$ from the model (2), the log-likelihood function of $\boldsymbol{\theta} = \left(\beta_1, \sigma_1^2, \pi_1, \beta_2, \sigma_2^2, \pi_2, \dots, \beta_g, \sigma_g^2, \pi_g\right) \text{ can be written as:}$ $L(\boldsymbol{\theta}; \boldsymbol{S}) = \sum_{i=1}^{n} \log \sum_{i=1}^{g} \frac{\pi_i}{\sqrt{2}\sigma_i} \exp\left(-\frac{\sqrt{2}|Y_j - X_j^T \boldsymbol{\beta}_i|}{\sigma_i}\right)$

The maximum likelihood estimators of θ can be obtained by maximizing $L(\theta; S)$ by taking the derivative of $L(\theta; S)$ with respect to θ , and set it equal to 0. Usually, no explicit solution can be obtained, and some numerical methods will be applied. Andrews and Mallows (1974) showed that a Laplace distribution in fact can be expressed as a mixture of normal distribution and another distribution related to exponential distribution. If we assume Z and V be two random variables, V has a distribution with density function:

(3)

$$f(v) = \frac{1}{v^3} \exp(-\frac{1}{2v^2}), \ v > 0 \quad (4)$$

and given V = v, the conditional distribution of Z is normal with mean 0 and variance $\frac{\sigma^2}{2v^2}$. Denote f(z; v) the joint density function of Z and V, that is;

$$f(z,v) = \frac{v}{\sqrt{\pi}\sigma} \exp(-\frac{v^2 z^2}{\sigma^2}) \frac{1}{v^5} \exp(-\frac{1}{2v^2})$$
(5)

Then the marginal distribution of \mathbb{Z} will be a Laplace distribution with density function:

$$h_{\varepsilon}(z) = \exp(-\sqrt{2}|z|/\sigma) / \sqrt{2}\sigma$$

Consider *V* as a latent variable. If *V* could be observed, then it is easy to see that the log-likelihood function of $\theta = (\beta; \sigma^2)$, based on the sample $P = (X_j, Y_j, V_j)_{j=1}^n$ is:

$$L(\boldsymbol{\theta}; \boldsymbol{P}) = -\frac{1}{2}\log \pi \sigma^2 - \frac{1}{\sigma^2} \sum_{j=1}^n V_j^2 (Y_j - \boldsymbol{X}_j^T \boldsymbol{\beta})^2 - \sum_{j=1}^n \log V_j^2 - \frac{1}{2} \sum_{j=1}^n \frac{1}{V_j^2}$$
(6)

2.2 EM Algorithm for the mixture regression based on the LTA estimation method.

Assume that $\epsilon_j s'$ follows a Laplace distribution with mean 0 and scale parameter $\sigma_i / \sqrt{2}$. For i = 1, 2, ..., g, j = 1, 2, ..., n, G_{ij} are latent Bernoulli variables such that

$G_{ij} = \begin{cases} 1 \text{ if } j \text{th observation } (X_j, Y_j) \text{ is from } i \text{th component} \\ 0 \text{ otherwise.} \end{cases}$

Then, if the full data set $T = \{(X_j, Y_j, G_j)\}_{i=1,2,...,g_j}$ are observable, then the log likelihood function of $\theta = (\beta_1, \sigma_1^2, \pi_1, \beta_2, \sigma_2^2, \pi_2, ..., \beta_g, \sigma_g^2, \pi_g)$ can be written as:

$$L(\boldsymbol{\theta}; \boldsymbol{T}) = \sum_{j=1}^{n} \sum_{i=1}^{\mathcal{G}} G_{ij} \log \frac{\pi_i}{\sqrt{2\sigma_i}} \exp\left(-\frac{\sqrt{2}|Y_j - X_j^T \beta_i|}{\sigma_i}\right)$$
(7)

From Andrews and Mallows (1974), we know that a Laplace distributed random variable is a scale mixture of a normal random variable and another variable related to exponential distribution. Denote V_j , coupled with $(X_j; Y_j)$, as the latent scale variable, j = 1, 2, ..., n and it will be regarded as missing

observations because they cannot be observable. Then, the complete data loglikelihood function of θ , based on $D = \{X_j, Y_j, V_j, G_{ij}\}_{i=1,2,...,g_i,j=1,2,...,g_i}$, has the form

$$L_{\boldsymbol{c}}(\boldsymbol{\theta}_{i}\boldsymbol{D}) = \sum_{j=1}^{n} \sum_{i=1}^{g} G_{ij} \log \frac{V_{j}}{\sqrt{\pi\sigma_{i}}} \exp\left(-\frac{V_{j}^{2}(Y_{j}-X_{j}^{T}\boldsymbol{\beta}_{i})^{2}}{\sigma_{i}^{2}}\right) \frac{1}{V_{j}^{3}} \exp\left(-\frac{1}{2V_{j}^{2}}\right)$$
$$= \sum_{j=1}^{n} \sum_{i=1}^{g} G_{ij} \log \pi_{i} - \frac{1}{2} \sum_{j=1}^{n} \sum_{i=1}^{g} G_{ij} \log \pi_{i} \sigma_{i}^{2} - \sum_{j=1}^{n} \sum_{i=1}^{g} \frac{G_{ij} V_{j}^{2} (Y_{j}-X_{j}^{T} \boldsymbol{\beta}_{i})^{2}}{\sigma_{i}^{3}} - \sum_{j=1}^{n} \sum_{i=1}^{g} G_{ij} \log V_{j}^{2} - \frac{1}{2} \sum_{j=1}^{n} \sum_{i=1}^{g} \frac{G_{ij}}{V_{j}^{2}}$$
(8)

From Equation (8), we find that the third part of the right-hand side like a least square criterion which can be replaced by the robust criterion LTA Equation (1) and then we can apply EM steps (Dogru and Arslan 2017). As the last two terms in Equation (8) do not involve the unknown regression parameters, we can simply drop them from the analysis. Based on EM algorithm principle, in E-step, we have to calculate the conditional expectation $E[L(\theta; D)|S, \theta^{(0)}]$, where

$$\begin{split} &S = \{ \left(X_j, Y_j \right) \}_{j=1}^h, \ h = \left(n(1 - \alpha) + 1 \right), \ \text{is the number of observations after} \\ &\text{trimming, and } \alpha \quad \text{is the trimming proportion and} \\ &\boldsymbol{\theta}^{(0)} = \left(\beta_1^{(0)}, \sigma_1^{2(0)}, \pi_1^{(0)}, \beta_2^{(0)}, \sigma_2^{2(0)}, \pi_2^{(0)}, \dots, \beta_g^{(0)}, \sigma_g^{2(0)}, \pi_g^{(0)} \right) \\ &\text{are initial values for } \boldsymbol{\theta}. \ \text{Thus, to find } E[L(\boldsymbol{\theta}; \boldsymbol{D}) | \boldsymbol{S}, \boldsymbol{\theta}^{(0)}] \ \text{we only have to} \end{split}$$

$$\tau_{ij} = E[G_{ij}|S, \boldsymbol{\theta}^{(0)}], \delta_{ij} = E[V_j^2|S, \boldsymbol{\theta}^{(0)}, G_{ij} = 1]$$

One can show that

$$\tau_{ij} = \frac{\pi_i^{(0)} \sigma_i^{-1(0)} \exp\left(-\frac{|Y_j - X_j^T \beta_i^{(0)}|}{\sigma_i^{(0)}}\right)}{\sum_{m=1}^g \pi_m^{(0)} \sigma_m^{-1(0)} \exp\left(-\frac{|Y_j - X_j^T \beta_m^{(0)}|}{\sigma_m^{(0)}}\right)}, \quad \delta_{ij} = \frac{\sigma_i^{(0)}}{\sqrt{2}|Y_j - X_j^T \beta_i^{(0)}|} \tag{9}$$

The calculation for δ_{ij} follows the same thread as in Phillips (2002). In Mstep, the following expression will be maximized with respect to $\pi_i s$, $\beta_i s$ and $\sigma_i^2 s$,

$$\sum_{j=1}^{n} \sum_{i=1}^{g} \tau_{ij} \log \pi_{i} - \frac{1}{2} \sum_{j=1}^{n} \sum_{i=1}^{g} \tau_{ij} \log \sigma_{i}^{2} - \sum_{j=1}^{n} \sum_{i=1}^{g} \frac{\tau_{ij} \delta_{ij} (Y_{j} - X_{j}^{T} \beta_{i})^{2}}{\sigma_{i}^{2}}$$
(10)

and the maximizer will be used for the next iteration We propose the following EM algorithm to maximize (3).

• EM Algorithm:

- 1. Choose initial values for $\boldsymbol{\theta} = (\beta_1, \sigma_1^2, \pi_1, ..., \beta_g, \sigma_g^2, \pi_g),$
- 2. E-Step: at the $(k + 1)^{th}$ iteration, calculate $\tau_{ij}^{(k+1)}$ and $\delta_{ij}^{(k+1)}$ from Equation (9) with (0) replaced by (k).
- M-Step: at the (k + 1)th iteration, use the following formulas to calculate the maximizer of (10):

$$\pi_i^{(k+1)} = \frac{1}{n} \sum_{j=1}^n \tau_{ij}^{(k)}, (11)$$

$$\beta_i^{(k+1)} = \left(\sum_{j=1}^h \tau_{ij}^{(k+1)} \delta_{ij}^{(k+1)} X_j X_j^T\right) \ (12)$$

$$\sigma_i^{2(k+1)} = \frac{2\sum_{j=1}^{h} \tau_{ij}^{(k+1)} \delta_{ij}^{(k+1)} |Y_j - X_j^T \beta_i^{(k+1)}|}{\sum_{j=1}^{h} \tau_{ij}^{(k+1)}} \quad (13)$$

4. Repeat steps (2), (3) until the convergence is obtained.

We also assume that all σ_i^2 are equal, and the above EM algorithm, a common initial value for σ_i^2 are used, but σ^2 can be updated in M-step by

$$\sigma^{2(k+1)} = \frac{2\sum_{j=1}^{h} \sum_{i=1}^{g} \tau_{ij}^{(k+1)} \delta_{ij}^{(k+1)} |Y_j - X_j^T \beta_i^{(k+1)}|}{n}$$
(14)

The robustness of the above EM procedure is resulted from the adoption of LTA regression; it is also obvious from the formulae of the updated β_i s' in each iteration.

Note that the factor $\delta_{ij}^{(k+1)}$ is reversely related to the term $|Y_j - X_j^T \beta_i^{(k)}|$, meaning that larger residuals give smaller values of $\delta_{ij}^{(k+1)}$, hence down weight the corresponding observations when calculating the estimates.

3. LTA Method by using *t* Distribution

In this section we assume that as Wei (2012), the error density $f_i(\epsilon)$ is a *t*-distribution with degrees of freedom v_i and scale parameter σ_i . Hence, given x_i , density function of y_i is:

$$f(y_j; \boldsymbol{x}_j^T, \boldsymbol{\theta}) = \sum_{i=1}^{\theta} \pi_i f(y_j; \boldsymbol{x}_j^T \beta_i, \sigma_i^2, v_i),$$
(15)

where

$$f(y_j; \boldsymbol{x}_j^T, \beta_i, \sigma_i^2, v_i) = \frac{\Gamma(\frac{V_i + 2}{2}) |\sigma_i|^{-1}}{(\pi_i v_i)^{\frac{1}{2}} \Gamma(\frac{V_i}{2}) (1 + \delta(y_j, x_j^T \beta_i, \sigma_i^2) / v_i)^{\frac{1}{2}(V_i + 1)}}$$
(16)
and $\delta(y_j, \boldsymbol{x}_j^T \beta_i; \sigma_i^2) = (y_j - \boldsymbol{x}_j^T \beta_i)^2 / \sigma_i^2$

Let's assume that v_i are known. The unknown parameter θ can be estimated by maximizing the log likelihood

$$\sum_{j=1}^{n} \log\{\sum_{i=1}^{g} \pi_i f(\gamma_j; \mathbf{x}_j^T \beta_i, \sigma_i^2, \nu_i)\}$$
(17)

Note that the complete log likelihood function for (X, y, z) is

$$\log L_{\mathcal{L}}(\boldsymbol{\theta}; \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{z}) = \sum_{j=1}^{n} \sum_{i=1}^{g} z_{ij} \log\{\pi_i f(\boldsymbol{y}_j; \boldsymbol{x}_j^T \boldsymbol{\beta}_i, \boldsymbol{\sigma}_i^2, \boldsymbol{v}_i)\},\tag{18}$$

where $\mathbf{X} = (X_1, X_2, ..., X_n)^T$; $\mathbf{y} = (y_1, y_2, ..., y_n)$; $\mathbf{z} = (z_{11}, ..., z_{ng})$. Based on the theory of EM algorithm, in E-step, given the current estimate $\boldsymbol{\theta}^k$ at k^{th} iterative M-step, we calculate conditional expectation of the complete log likelihood $E(\log L_c(\boldsymbol{\theta}; \mathbf{X}, \mathbf{y}, \mathbf{z}) | \mathbf{X}, \mathbf{y}, \boldsymbol{\theta}^k)$, which is simplified to the calculation of $E(z_{ij} | \mathbf{X}, \mathbf{y}, \boldsymbol{\theta}^k)$ [See Wei (2012)]. In addition, at M-step, we compute the parameters which maximize

$$E(\log L_{c}(\boldsymbol{\theta}; \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{z}) | \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{\theta}^{k}) = \sum_{j=1}^{n} \sum_{i=1}^{\theta} E(z_{ij} | \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{\theta}^{k}) \log\{\pi_{i} f(y_{j}; \boldsymbol{x}_{j}^{\mathrm{T}}, \beta_{i}, \sigma_{i}^{2}, v_{i})\}$$
(19)

We note that there is no explicit solution for β_i and σ_i^2 .

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Because the t-distribution can be considered as a scale mixture of normal distributions, we use the method of EM algorithm so that we can estimate unknown parameters and follow the following steps:

Let **u** be the latent variable such that

$$\epsilon | u \sim N\left(0, \frac{\sigma^2}{u}\right), u \sim gamma\left(\frac{1}{2}\nu, \frac{1}{2}\nu\right),$$

where gamma (α, γ) has density

$$f(u; \alpha, \gamma) = \frac{1}{\Gamma \alpha} \gamma^{\alpha} u^{\alpha-1} e^{-\gamma u}, \quad u > 0$$

Then, marginally ϵ has a *t*-distribution with degrees of freedom v and scale parameter σ . Therefore, Wei (2012) introduced another latent variable u to simplify the computation of M-step of EM algorithm.

Note that the complete likelihood for (X; y; u; z) is

$$\begin{split} &\log L_{\sigma}(\theta; X, y, z, u) \\ &= \sum_{j=1}^{n} \sum_{i=1}^{g} z_{ij} \log\{\pi_{i} \phi\left(y_{i}; x_{j}^{T} \beta_{i'} \frac{\sigma_{i}^{2}}{u_{i}}\right) f(u_{i}; \frac{1}{2} v_{i'} \frac{1}{2} v_{i})\} \\ &= \sum_{j=1}^{n} \sum_{i=1}^{g} z_{ij} \log(\pi_{i}) + \sum_{j=1}^{n} \sum_{i=1}^{g} z_{ij} \log\left\{f\left(u_{i}; \frac{1}{2} v_{i'} \frac{1}{2} v_{i}\right)\right\} \\ &+ \sum_{j=1}^{n} \sum_{i=1}^{g} z_{ij} \left\{-\frac{1}{2} \log(2\pi\sigma_{i}^{2}) + \frac{1}{2} \log(u_{i}) - \frac{u_{i}}{2\sigma_{i}^{2}} (y_{i} - x_{j}^{T} \beta_{i})^{2}\right\} (21) \end{split}$$

where $u = (u_1, u_2, ..., u_n)$ is independent of z.

In order to use our proposed method, we can replace the last part of Equation (21) with LTA's robust criterion. In addition, the above second term doesn't involve unknown parameters. Therefore, based on the theory of EM algorithm, in E step, given the current estimate θ^{k} at $k^{\epsilon \hbar}$ step, the calculation of $E(\log L_c(\theta; X, y, u, z) | X, y, \theta^{(k)})$ is simplified to the calculation of $E(z_{ij} | X, y, \theta^{(k)})$ and of $E(u_{ij} | X, y, \theta^{(k)}, z_{ij} = 1)$. Then in M-step, we find the maximizer of

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$$E\left(\log L_{c}(\theta; \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{u}, \boldsymbol{z}) | \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{\theta}^{(k)}\right) \propto \sum_{j=1}^{h} \sum_{i=1}^{g} E(z_{ij} | \boldsymbol{x}, \boldsymbol{\theta}^{(k)}) [\log(\pi_{i}) - \frac{1}{2} \log(2\pi\sigma_{i}^{2}) - \frac{E(u_{ij} | \boldsymbol{x}, \boldsymbol{\theta}^{(k)}, z_{ij} = 1)}{2\sigma_{i}^{2}} | \boldsymbol{y}_{i} - \boldsymbol{x}_{j}^{i} \boldsymbol{\beta}_{i} | \right] (22)$$

which has explicit solution for $\boldsymbol{\theta}$, where *h* is defined before.

Wei (2012) proposed the following EM algorithm to maximize (17). The steps of EM algorithm as:

• EM Algorithm:

- 1- Input initial values: $\pi_i^{(0)}, \beta_i^{(0)}$ and $\sigma_i^{2(0)}$.
- 2- E- step: at the (k+1)th iteration

$$E(z_{ij}|\mathbf{X}, \mathbf{y}, \boldsymbol{\theta}^{(k)}) = \tau_{ij}^{(k+1)} = \frac{\pi_i^{(k)} f(y_j; \mathbf{x}_j^T, \beta_i^{(k)}, \sigma_i^{2(k)}, v_i^{(k)})}{\sum_{i=1}^{g} \pi_i^{(k)} f(y_j; \mathbf{x}_j^T, \beta_i^{(k)}, \sigma_i^{2(k)}, v_i^{(k)})},$$
(23)

and

$$E(u_{ij}|\mathbf{X}, \mathbf{y}, \boldsymbol{\theta}^{(k)}, Z_{ij} = 1) = u_{ij}^{(k+1)} = \frac{v_i^{(k)} + 1}{v_i^{(k)} + \delta\left(y_j; \mathbf{x}_j^T, \beta_i^{(k)}, \sigma_i^{2(k)}, v_i^{(k)}\right)}.$$
(24)

3- M- step: At the (k + 1)th iteration, the estimator of parameterscan be computed $(\pi_i, \beta_i, \sigma_i^2, v_i)$ can be computing which maximize the expected complete log likelihood

$$\pi_i^{(k+1)} = \sum_{j=1}^n \tau_{ij}^{(k+1)} / n, \tag{25}$$

$$\beta_i^{(k+1)} = \left(\sum_{j=1}^n x_j x_j^T w_{ij}^{(k+1)}\right)^{-1} \sum_{j=1}^n x_j y_j w_{ij}^{(k+1)},\tag{26}$$

and

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$$\sigma_i^{2(k+1)} = \frac{\sum_{j=1}^h \tau_{ij}^{(k+1)} u_{ij}^{(k+1)} (y_i - x_j^T \beta_i^{(k+1)})^2}{\sum_{j=1}^h \tau_{ij}^{(k+1)}}, \quad (27)$$

where $w_{ij}^{(k+1)} = \tau_{ij}^{(k+1)} u_{ij}^{(k+1)}$. If we further assume that all σ_i^2 are equal, and the above EM algorithm, a common initial value for σ_i^2 are used, but σ^2 can be updated in M-step by

$$\sigma^{2(k+1)} = \frac{\sum_{j=1}^{h} \sum_{i=1}^{g} \tau_{ij}^{(k+1)} u_{ij}^{(k+1)} |y_j - x_j^T \beta_i^{(k+1)}|}{n}$$
(28)

4- Repeat E-step and M-step until the result can pass certain criterion.

From (24) in E-step, the weights $u_{ij}^{(k+1)}$ decrease if the standardized residuals increase and thus decrease the effects of the outliers to generate the robust estimate for mixture regression parameters. In addition, from (27) in M-step, we can see that larger residuals also have smaller effects on $\sigma_i^{2(k+1)}$ due to the weights $u_{ij}^{(k+1)}$.

4. LTA Method by using Normal Distribution

Let $\{(x_1, y_1), (x_2, y_2), ..., (x_n, y_n)\}$ be a sample. If it is assumed that the error terms have the normal distribution with 0 mean and σ^2 variance in the mixture regression model, the estimator of θ can be found by maximizing the following log-likelihood function:

$$l(\boldsymbol{\theta}) = \sum_{j=1}^{n} log\left(\sum_{i=1}^{g} \pi_i \phi(\mathbf{y}_j; \boldsymbol{x}_j^T \boldsymbol{\beta}_i, \sigma_i^2)\right),$$
(29)

However, since the direct maximization of (29) cannot be usually possible, in general, the EM algorithm is used to find the ML estimate of θ . Let \mathbb{Z}_{ij} be the latent variables with

$$Z_{ij} = \begin{cases} 1 & \text{if } j \text{th observation is coming from } i \text{th componen} \\ 0 & otherwise \end{cases}$$
(30)

where j = 1, ..., n and i = 1, ..., g. Here, $Z_j = (Z_{1j}, ..., Z_{gj})$ will be regarded as missing observations because they cannot be observable. Then, the complete data log-likelihood function for (y, Z_j) given X is obtained as

$$L_{c}(\boldsymbol{\theta}; \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{Z}_{j}) = (\sum_{j=1}^{n} \sum_{i=1}^{g} Z_{ij} (\log(\pi_{i}) - \frac{1}{2} \log(2\pi) - \frac{1}{2} \log(\sigma_{i}^{2})) - \sum_{j=1}^{n} \sum_{i=1}^{g} Z_{ij} \frac{(y_{j} - x_{j}^{T} \beta_{i})^{2}}{2\sigma_{i}^{2}},$$
(31)

where $X = (X_1, X_2, ..., X_n)^T$ and $y = (y_1, y_2, ..., y_n)^T$.

The estimator based on the normal distribution in the mixture regression model will not be robust against the outliers because of the second term of the complete data log-likelihood function given in (31). This term is basically the least-squares (LS) criterion and it is known that the LS method is sensitive to the outliers. To obtain robust estimators, this term should be robustified. Therefore, we will take the complete data log-likelihood function given in (29) and use the LTA criterion given in (1) in this equation (Dogru and Arslan 2017). This results the following adapted complete data log-likelihood function

$$L_{c}(\theta_{i}X, y, Z_{j}) = (\sum_{j=1}^{n} \sum_{i=1}^{g} Z_{ij}(\log(\pi_{i}) - \frac{1}{2}\log(2\pi) - \frac{1}{2}\log(\sigma_{i}^{2})) - \sum_{j=1}^{h} \sum_{i=1}^{g} Z_{ij}\frac{|r_{i}|_{jm}}{2\sigma_{i}^{2}}.$$
(32)

where r_i and h are defined before. To run the EM algorithm, we will take the conditional expectation of the complete data log-likelihood function to get rid of the latency of Z_{ij}

$$\begin{split} E\left(l_{c}\left(\boldsymbol{\theta};\boldsymbol{y},\boldsymbol{Z}_{j}\right)|\boldsymbol{y}_{i}\right) &= \sum_{j=1}^{n} \sum_{i=1}^{g} E(\boldsymbol{Z}_{ij}|\boldsymbol{y}_{i})(\log(\pi_{i}) - \frac{1}{2}\log(2\pi) - \frac{1}{2}\log(\sigma_{i}^{2})) - \\ &\sum_{j=1}^{h} \sum_{i=1}^{g} E(\boldsymbol{Z}_{ij}|\boldsymbol{y}_{i}) \frac{|\boldsymbol{v}_{i}|_{j\pi}}{2\sigma_{i}^{2}}, \end{split}$$

(33)

Note that the conditional expectation $E(Z_{ij}|y_i)$ can be calculated using the classical theory of the mixture modeling. Then, the steps of the EM algorithm for the mixture regression based on the LTA estimation method will be as follows:

• EM Algorithm:

1. Take initial estimate for the parameters, say $\theta^{(0)}$ and fix a stopping rule Δ .

2. E-step: Compute the following conditional expectation when y and the current parameter value $\hat{\theta}^{(k)}$ are given

$$\hat{z}_{ij}^{(k)} = E\left(Z_{ij} \middle| y_j, \hat{\boldsymbol{\theta}}^{(k)}\right) = \frac{\hat{\pi}_i^{(k)} \phi(y_j; \boldsymbol{x}_j^T \hat{\beta}_i, \hat{\sigma}_i^2)}{\sum_{=1}^{g} \hat{\pi}_i^{(k)} \phi(y_j; \boldsymbol{x}_j^T \hat{\beta}_i, \hat{\sigma}_i^2)}.$$
(34)

3. M step: Compute the following estimates:

$$\hat{\pi}_{i}^{(k+1)} = \frac{1}{n} \sum_{j=1}^{n} \hat{z}_{ij}^{(k)}, \tag{35}$$

$$\hat{\beta}_{i}^{(k+1)} = \left(\sum_{j=1}^{h} \hat{z}_{ij}^{(k)} \boldsymbol{x}_{j} \boldsymbol{x}_{j}^{T}\right)^{-1} \left(\sum_{j=1}^{h} \hat{z}_{ij}^{(k)} \boldsymbol{x}_{j} \boldsymbol{y}_{j}\right), \tag{36}$$

and

$$\hat{\sigma}_{i}^{2(k+1)} = c_{\alpha} \frac{\sum_{j=1}^{h} \hat{z}_{ij}^{(k)} |y_{j} - x_{j}^{T} \hat{\beta}_{i}^{(k)}|}{\sum_{j=1}^{h} \hat{z}_{ij}^{(k)} - p}, \qquad (37)$$

where c_{α} is a consistency constant. For the normal errors, c_{α} will be $(1-\alpha)/F_{x_{\alpha}^{2}}(q_{\alpha})$ with

 $q_{\alpha} = x_{1,1-\alpha}^2$ [See Agulló *et al.*, (2008)] for the case multivariate normal errors. Here, $F_{x_{3}^{2}}$ shows the cumulative distribution function of the χ^{2} distribution with 3 degrees of freedom and q_{α} is the upper α percent point of the χ^{2} distribution with 1 degree of freedom.

4. Repeat E and M steps until the convergence criterion $\|\hat{\theta}^{(k+1)} - \hat{\theta}^{(k)}\| \le \Delta$ is satisfied. Moreover, the absolute difference of the actual log-likelihood $\||\ell(\hat{\theta}^{(k+1)}) - \ell(\hat{\theta}^{(k)})\|| \le \Delta$ or $\||\ell(\hat{\theta}^{(k+1)})/\ell(\hat{\theta}^{(k)}) - 1\|| \le \Delta$ can be used [See Dias and Wedel, (2004)] for the convergence.

5. Simulation Study

In this section, we will evaluate the performance of the proposed robust mixture regression method based on LTA method for the three different distributions through a simulation study. The comparison will also be made among different estimation methods using the estimated *mean squared errors* (MSE's) and bias of the parameter estimates for each estimation method. It is known that the estimate with the least sum of squares error and the least bias is the best. There have been great research efforts in dealing with the unbounded likelihood issue. See, for example, Hathaway (1985,1986), Chen *et al.* (2008), and Yao (2010).

The estimated mean squared errors (MSE's) is given by

$$\widehat{MSE}(\widehat{\theta}) = \sum_{j=1}^{M} \frac{(\widehat{\theta}_j - \theta)^2}{M},$$

where M is the number of samples.

In our simulation study, we compare our method with some existing estimation procedures by generating sample data $(X_{j1}, X_{j2}, Y_j)_{j=1}^n$ from the following two-component mixture regression models which are also used in Wei (2012):

 $\mathbf{Y} = \begin{cases} 0 + X_1 + X_2 + \varepsilon_1 & \text{if } Z = 1; \\ 0 - X_1 - X_2 + \varepsilon_1 & \text{if } Z = 2. \end{cases}$

where Z is a component indicator of Y with P(Z = 1) = 0.25. That is, the data are generated from a two-component mixture linear regression models with $\beta_1 = (\beta_{10}, \beta_{11}, \beta_{12})' = (0, 1, 1)$ and $\beta_2 = (\beta_{20}, \beta_{21}, \beta_{22})' = (0, -1, -1)$

The predictors $X_1 \sim N(0; 1)$, $X_2 \sim N(0; 1)$ are independent, the random error ϵ_1 and ϵ_2 are independent and have the same distribution as ϵ . The following error distributions will be considered:

Case I: €~ N(0,1)

Case II: $\mathbf{\varepsilon} \sim$ Laplacewith mean 0 and variance 1

Case III: $\varepsilon \sim t_1$, *t*-distribution with degree of freedom 1

Case IV: $\varepsilon \sim t_3$, *t*-distribution with degree of freedom 3

Case V: €~ lognormal (0,1) Case VI: €~ 0:95N(0; 1) + 0:05N(0; 52).

Case VII: e^{N} (0; 1) with 5% of high leverage outliers being X1 = X2 = 20 and Y = 100.

In Case I, the error is exactly normally distributed and there are no outliers. It is often used to evaluate the efficiency of different estimation methods compared to the traditional MLE. For Case II, the estimation methods proposed by Song *et al.* 2014 which, as in the first Case, would serve a reference line to evaluate the performance of other estimation procedures. Both Case III and IV are heavy tailed distributions. In Case V we use lognormal distribution for random error as a skewed distribution to know whether the skewed distribution gave better results or not. In Case VI, the 5% data from N(0; 25) are likely to be low leverage outliers. In Case VII, 5% observations are replicated high leverage outliers, which will be used to check the robustness of estimation procedures against the outliers in the *x*-direction. The following algorithm will be compared:

- MLE based on normality assumption
- Trimmed likelihood estimator (TLE) proposed by Neykov *et al.* (2007)
- The robust EM mixture regression based on *t*-distribution (Mixregt)
- MLE based on Laplace distribution (MixregL)
- The proposed robust EM mixture regression based on least trimmed sum of absolute deviations method (MixrigLTA) with using three cases of distribution for y. In case I we assume that error has Laplace distribution, case II; error has t distribution. Finally, case III; error has normal distribution.

From the simulation studies, we can see that if the true distribution of $\boldsymbol{\epsilon}$ is normal or have Laplace distribution the MSEs of MLE procedure are slightly bigger than our proposed method MixregLTA_L and better than MixregLTA_t and MixregLTA_N when the sample size is 100.The larger the sample size, the better the results for all, but with the preference of the proposed method MixregLTA_L. While for other cases when the distribution of $\boldsymbol{\epsilon}$ has a heavier tail, contaminated by some outliers, or there are high leverage outliers in the data set or skewed, then MLE fails to provide reasonable estimates. It is clear that the performance of LTA_L method is the best in all cases, with some slight differences in preference between it and TLE, Mixregt and MixregL methods in some cases. For LTA_t we can say that it is in the fourth place after LTA_L , MixregL and TLE. But LTA_N is after them in preference. The overall performance of the Mixregt proposed by Wei (2012) is also satisfying when sample size gets bigger except for the Case VI when high leverage points present in the data set.

Tables (5.1), (5.2) and (5.3) show the estimated (*MSE's*) and bias (Bias) of the parameter estimates for each estimation method for the sample sizes n = 100, 200 and 400 respectively. The number of replicates is 200. Based on Tables (5.1), (5.2) and (5.3), we can see that MixrigLTA_Lhas overall better or comparable performance than other six methods considered for Cases I to VII.

Table 5.1: The estimated (MSE's) and bias (Bias) of the parameter estimates for each estimation methods MLE, TLE, Mixregt, MixregL, $MixrigLTA_L$, $MixrigLTA_t$ and $MixrigLTA_N$ for n = 100 العدد السادس والعشرون يونية ٢٠٢١

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parat	neter	M LE		TLE		Mixrigt.		MinregL		MinrigL TA.		MinrigL.T.A.		MinnigL TA.	
		MSE	Bias	MSE	Bias	MSE	Bias	MSE	Bias	MSE	Bias	MSE	Bias	MSE	Bias
\$10		0.093	0.019	0.139	0.033	0.109	-0.014	0.09	0.028	0.028	0.097	0.104	0.03	0.019	-0.011
β_{11}		0.074	0.015	0.212	-0.195	0.126	-0.023	0.095	-0.047	0.051	-0.084	0.146	-0.042	2.141	-1.448
β ₁₂	E = 0	0.134	-0.019	0.248	-0.195	0.133	-0.044	0.09	-0.023	0.042	-0.063	0.141	0.015	2.169	-1.46
β ₂₀		0.018	-0.002	0.038	-0.004	0.019	-0.014	0.026	-0.017	0.012	-0.045	0.021	0.019	0.019	-0.011
β ₂₁		0.02	-0.012	0.03	0.011	0.02	-0.004	0.026	0.007	0.014	0.012	0.025	-0.019	0.349	0.552
β ₂₂		0.018	-0.012	0.024	0.034	0.02	-0.008	0.025	-0.001	0.012	0.005	0.02	-0.024	0.33	0.54
π		0.093	0.019	0.007	0.025	0.109	-0.014	0.004	0.011	0.006	0.031	0.006	0.015	0.062	0.25
0															
P10	•	0.004	0.013	0.075	-0.007	0.005	0.009	0.052	0.019	0.006	0.031	0.125	-0.021	0.019	0
β11	antec	0.121	0.024	0.097	-0.107	0.103	0.022	0.054	-0.012	0.014	0.074	0.131	-0.004	2.137	-1.45
P 12	÷	0.127	0.012	0.084	-0.077	0.135	-0.05	0.051	-0.012	0.021	-0.077	0.139	0.002	2.188	-1.467
\$20	Ë	0.15	0.01	0.013	0.004	0.102	-0.028	0.011	-0.006	0.019	-0.067	0.014	0.003	0.019	0
β ₂₁	Cose	0.101	-0.025	0.013	0.007	0.013	-0.009	0.012	0.007	0.007	-0.061	0.013	-0.008	0.338	0.55
β ₂₂		0.023	-0.002	0.013	0.019	0.013	0.002	0.012	0	0.005	0.033	0.014	0.004	0.322	0.533
π		0.043	-0.016	0.004	0.019	0.012	-0.006	0.052	0.019	0.008	0.04	0.005	0.008	0.062	0.25
\$10		0.006	0.009	3.2	-0.15	0.004	0.01	0.004	0.007	0.005	0.027	0.541	0.106	0.068	-0.004
β11	_	13741.2	-7.49	1.886	-0.17	0.74	0.041	0.125	0.103	0.018	0.096	1.018	-0.451	2.315	-1.49
β ₁₂	4 4	5478.51	5.183	1.797	-0.033	1.263	-0.65	0.416	-0.327	0.069	-0.186	0.916	-0.509	2.361	-1.505
\$20	E e E	9085.99	5.619	1.526	0.065	1.215	-0.525	0.472	-0.322	0.077	-0.192	0.185	-0.006	0.068	-0.004
β ₂₁	G	13738.3	-7.14	0.774	-0.129	0.144	0.014	0.028	-0.022	0.011	-0.079	0.088	-0.008	0.355	0.51
β ₂₂		5499.32	5.266	0.773	-0.065	0.111	-0.057	0.026	0.059	0.013	0.051	0.106	-0.043	0.341	0.495
π_1		9119.33	6.31	0.039	0.06	0.082	-0.023	0.042	0.069	0.01	0.046	0.022	0.096	0.062	0.25
\$ 10		0.116	0.249	0.238	0.007	0.029	0.111	0.024	0.072	0.034	0.177	0.749	0.167	0.028	-0.006
β11		1.542	-0.006	0.264	-0.135	0.451	-0.033	0.15	0.024	0.085	0.099	0.481	-0.034	2.203	-1.469
β ₁₂	f	1.09	-0.076	0.239	-0.096	0.477	-0.136	0.155	-0.034	0.145	-0.077	0.413	-0.022	2.222	-1.475
\$20	e IV	1.526	-0.337	0.038	-0.008	0.599	-0.006	0.187	-0.013	0.185	0.01	0.065	-0.015	0.028	-0.006
\$21	Cos	0.446	-0.067	0.034	0.01	0.631	-0.068	0.032	0.008	0.022	-0.019	0.048	-0.007	0.328	0.531
β ₂₂		0.159	0.071	0.026	0.01	0.139	0.022	0.038	0.004	0.04	-0.019	0.105	-0.041	0.321	0.525
π_1		0.229	0.026	0.007	0.037	0.256	-0.074	0.034	-0.022	0.026	-0.01	0.012	0.027	0.062	0.25

<u>a</u>

Table 5.1: MSE and Bias of Point Estimates for n = 100

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β ₁₀	0	12.628	2.764	1.515	1.176	3.399	1.53	1.527	1.134	1.116	0.991	2.379	1.307	1.47	1.198
β_{11}	ē	2.295	-0.4	0.117	-0.048	0.776	-0.304	0.19	-0.011	0.141	-0.028	0.537	-0.08	2.736	-1.635
β_{12}	E	2.946	-0.379	0.147	-0.056	0.627	-0.27	0.185	-0.026	0.146	-0.071	0.491	-0.084	2.664	-1.613
β ₂₀	-Bog	9.765	2.221	1.085	1.032	1.487	1.014	0.986	0.978	0.865	0.914	2.081	1.029	1.47	1.198
β ₂₁	-	0.863	0.056	0.013	0.003	0.041	-0.004	0.026	0.008	0.032	-0.031	0.033	-0.018	0.196	0.365
β ₂₂	2	2.051	-0.144	0.013	0.016	0.03	0.001	0.02	-0.002	0.03	-0.006	0.184	-0.037	0.214	0.387
π_1	5	0.075	0.075	0.005	0.033	0.017	0.045	0.005	0.002	0.006	0.024	0.013	0.041	1.47	1.198
		0.025	0.022	0.124	0.046	0.013	0.025	0.006	0.01	0.007	0.024	0.195	0.091	0.022	0
F 25)		2.316	0.061	0.282	-0.209	0.342	0.008	0.156	0.07	0.046	0.095	0.431	-0.045	2.323	-1.509
	5	1.089	-0.096	0.221	-0.19	0.422	-0.111	0.119	-0.036	0.074	-0.071	0.336	-0.045	2.311	-1.505
	336	4.86	0.098	0.03	0.013	0.741	0.044	0.202	0.01	0.086	-0.081	0.033	0	0.022	0
	•	2.294	0.098	0.034	0.001	0.031	0.014	0.029	0.003	0.02	-0.033	0.027	-0.023	0.288	0.491
		1.267	-0.08	0.027	0.011	0.022	0.009	0.025	0.01	0.02	0.016	0.033	0.001	0.29	0.495
		1.534	-0.172	0.01	0.034	0.02	-0.01	0.028	0	0.025	0.008	0.008	0.019	0.062	0.25
	δ 🖪	0.052	0.037	0.173	0.002	0.007	0.008	0.006	0	0.007	0.018	0.152	-0.057	0.024	0.006
		22.01	-3.086	0.248	-0.209	2.581	0.017	0.034	0.055	0.033	0.091	0.135	-0.016	2.473	-1.556
	1)	6.353	1.398	0.219	-0.168	3.488	1.483	0.043	-0.033	0.051	-0.094	0.153	0.003	2.526	-1.574
		7.191	1.677	0.036	-0.002	3.61	1.514	0.041	-0.048	0.072	-0.101	0.024	0.003	0.024	0.006
	1	12.41	2.394	0.028	0	0.018	0.002	0.014	-0.05	0.016	-0.044	0.02	-0.004	0.251	0.444
	Į.	12.77	3.324	0.022	0.025	0.042	0.13	0.014	0.034	0.017	0.027	0.021	0.002	0.228	0.426
	Γ	11.91	3.206	0.007	0.017	0.04	0.128	0.013	0.029	0.019	0.025	0.005	0.003	0.062	0.25

Table 5.2: The estimated (MSE's) and bias (Bias) of the parameter estimates for each estimation methods MLE,

TLE, Mixregt, MixregL, MixrigLTAL, MixrigLTAt and MixrigLTAN for

parameter MLE TLE Mixrigt MixregL. MixrigLTA. MixrigLTA. MixrigLTA₈ Bias MSE -0.02 0.042 -0.003 0.073 -0.002 0.052 -0.002 0.063 0.037 0.018 0.079 0.046 0.017 0.01 β₁₀ Cas e I β_{11} 0.036 0.001 0.129 -0.162 0.048 -0.007 0.049 -0.03 0.021 -0.077 0.046 -0.022 2.12 -1.449 £ β_{12} $i \sim N$ 0.05 0.009 0.048 -0.011 0.174 -0.199 0.047 -0.04 0.062 -0.046 0.021 -0.081 2.144 -1.457 β₂₀ β₂₁ 0.01 -0.011 0.018 -0.016 0.008 -0.008 0.013 -0.019 0.007 -0.058 0.01 -0.002 0.01 -0.02 0.009 -0.004 0.012 0.02 0.008 0.004 0.011 0.016 0.006 0.026 0.01 -0.01 0.323 0.551 β₂₂ 0.009 0 0.017 0 0.009 0.001 0.013 0.006 0.007 0.04 0.01 -0.002 0.314 0.543 π_1 0.002 0.002 0.25 0.005 0.004 0.019 0.002 0.008 0.003 0.008 0.002 0.021 0.002 0.062 β₁₀ 0.047 0.008 0.039 0.003 0.026 -0.006 0.022 0.025 0.009 0.075 0.041 0.001 0.008 -0.011 β_{11} Cas eII: e~ Lapl ace 0.042 0.025 0.033 0.009 0.036 -0.01 2.141 -1.458 -0.064 0.027 -0.019 0.023 -0.018 -0.07 β_{12} β_{20} 0.042 -0.004 -1.457 0.028 -0.058 0.033 0.001 0.009 -0.061 0.037 0.002 2.14 0.028 0.022 0.006 -0.011 -0.002 0.007 -0.007 0.005 -0.003 0.005 -0.009 0.005 -0.062 0.005 0.003 0.008 β₂₁ 0.006 -0.011 0.542 0.007 0.007 0.005 -0.004 0.005 -0.001 0.003 0.043 0.007 -0.007 0.311 β₂₂ 0.007 0.002 0.006 0.007 0.005 -0.004 0.005 -0.002 0.003 0.04 0.006 -0.004 0.311 0.543 π_1 0.002 0.002 0.002 0.019 0.026 -0.006 0.022 0.025 0.009 0.075 0.002 0.006 0.062 0.25

n = 200

parameter		MLE		TLE		Missiat		Miscerk		Missial. T.S.		MissigLT&		MissiaLT&s	
β ₁₀		49.98	0.073	1.026	-0.123	0.002	0.002	0.002	0	0.002	0.026	0.23	-0.009	0.03	-0.004
β11		39.74	-1.465	0.906	0.103	0.264	-0.015	0.052	0.063	0.012	0.09	0.728	-0.381	2.324	-1.509
β ₁₂	Cas	77.11	-1.162	0.904	-0.024	0.971	-0.502	0.361	-0.414	0.088	-0.243	0.706	-0.338	2.277	-1.496
β ₂₀	c	43.17	0.118	0.774	0.128	0.903	-0.445	0.362	-0.408	0.079	-0.237	0.035	-0.006	0.03	-0.004
\$p_21	III:	15.66	0.637	0.201	0.052	0.034	0.008	0.014	-0.043	0.008	-0.083	0.033	-0.033	0.29	0.491
\$ 22	4	11.57	0.253	0.253	-0.032	0.043	-0.017	0.015	0.077	0.007	0.066	0.029	0.018	0.294	0.504
πi		0.058	0.231	0.02	0.031	0.039	-0.001	0.018	0.088	0.008	0.075	0.015	0.064	0.062	0.25
B10		0.206	.0.038	1.026	.0.123	0.010	0.078	0.020	0.003	0.04	0.102	0.102	0.016	0.016	0.004
β ₁₁	Cas	0.579	.0.065	0.906	0.103	0.094	0.041	0.06	0.06	0.062	0.049	0.116	-0.04	2 251	-1.492
β ₁₂	e IV:	0.429	-0.109	0.904	-0.024	0.086	-0.031	0.054	-0.021	0.049	-0.04	0.095	0.04	2.215	-1.479
\$ 20	e -	2.946	.0.124	0.774	0.128	0.129	.0.033	0.054	.0.029	0.05	.0.027	0.014	0.006	0.016	0.004
\$ 21	6	0.47	0.009	0.201	0.052	0.02	0	0.016	-0.002	0.013	-0.024	0.017	-0.003	0.285	0.508
\$ 22		0.324	0.004	0.253	.0.032	0.015	-0.009	0.014	-0.004	0.015	-0.009	0.019	-0.006	0.3	0.521
π1		0.02	0.002	0.02	0.031	0.015	-0.005	0.016	0	0.017	-0.005	0.003	0.011	0.062	0.25
P10	Cas	17.05	3.119	0.061	0.006	2.664	1.457	1.729	1.252	1.134	1.019	1.7	1.187	1.442	1.193
P11	e V:	2.515	-0.488	0.078	-0.093	0.46	-0.268	0.087	-0.038	0.078	-0.011	0.157	-0.037	2.778	-1.656
\$ ₁₂	logn	2.491	-0.527	0.087	-0.132	0.384	-0.21	0.109	-0.01	0.077	-0.033	0.239	-0.062	2.742	-1.644
β ₂₀	arm al	10.54	2.3	0.012	-0.013	0.969	0.912	0.956	0.97	0.85	0.915	1.111	0.952	1.442	1.193
β ₂₁	(0;	0.72	0.123	0.01	0.015	0.007	0.003	0.012	0.003	0.013	-0.006	0.009	0.005	0.154	0.344
\$22	1)	0.671	0.112	0.016	-0.004	0.017	-0.01	0.012	-0.008	0.014	-0.009	0.011	-0.002	0.167	0.356
"1		0.076	0.049	0.003	0.013	0.005	0.02	0.003	-0.002	0.014	0.007	0.005	0.018	0.062	0.25
0		0.851	-0.008	0.08	0.02	0.004	0.008	0.003	0.001	0.003	0.021	0.06	0.004	0.011	-0.004
β ₁₁		0.93	0.004	0.082	-0.082	0.076	-0.013	0.054	0.013	0.032	0.062	0.066	0.025	2.334	-1.519
\$ 12		1.369	0.097	0.082	-0.095	0.069	-0.008	0.055	-0.017	0.044	-0.024	0.075	0.005	2.331	-1.518
\$ 20	Can	0.024	0.003	0.019	-0.008	0.072	-0.022	0.073	-0.028	0.044	-0.047	0.011	-0.006	0.011	-0.004
β ₂₁	VI	0.092	0.056	0.017	0.014	0.013	0.004	0.016	-0.007	0.011	-0.037	0.012	0.002	0.258	0.481
\$ 22	£~ 0;	0.105	0.087	0.014	-0.009	0.011	0.006	0.014	0.008	0.014	0.01	0.015	0.001	0.259	0.482
π ₁		0.01	-0.032	0.004	0.035	0.01	0.012	0.012	0.016	0.016	0.009	0.002	0.002	0.062	0.25
β10	Cas	12.42	-2.059	0.072	0.029	0.003	0.003	0.003	0	0.003	0.007	0.051	0.007	0.012	-0.013
β_{11}	vII	4.272	1.347	0.095	-0.142	1.878	0.273	0.027	0.069	0.022	0.067	0.055	0.004	2.63	-1.613
β_{12}	e -	5.16	1.656	0.097	-0.125	2.862	1.488	0.022	-0.041	0.034	-0.103	0.044	-0.005	2.636	-1.614
β ₂₀	(W)	14.75	2.618	0.013	0.007	2.891	1.497	0.023	-0.056	0.035	-0.105	0.01	-0.014	0.012	-0.013
β ₂₁	with 5%	12.37	3.316	0.011	0.014	0.011	-0.005	0.009	-0.054	0.009	-0.05	0.012	-0.004	0.179	0.387
\$ 22	high	12.28	3.289	0.012	0.016	0.034	0.146	0.008	0.042	0.009	0.028	0.011	0	0.179	0.386
π1	iere rage outli era	0.149	0.213	0.003	0.02	0.035	0.143	0.007	0.032	0.009	0.043	0.002	-0.004	0.062	0.25

Table 5.3: The estimated (MSE's)	and bias	(Bias) c	of the	parameter	estimates
for each estimation methods MLE,	,				

TLE, Mixregt, MixregL, MixrigLTA_L, MixrigLTA_t and MixrigLTA_N for n = 400

para	meter	M	LE	T	Æ	Mi	xvigt	Mia	regi.	Mixi	elta.	Mixe	igLTA.	Mixi	el TA.
\vdash		MSE	Bias												
β_{10}		0.02	-0.001	0.041	0.012	0.010	0.004	0.028	0.014	0.000	0.082	0.02	0.007	0.006	-0.008
R		0.02	0.006	0.108	-0.178	0.016	0.000	0.020	-0.017	0.003	-0.092	0.02	-0.006	2.13	-1.457
P11 0	eI	0.017	0.00	0.006	0.170	0.020	0.002	0.022	0.027	0.011	0.000	0.021	0.000	2.10	1.454
P12	E	0.015	0.01	0.090	-0.1/1	0.021	-0.009	0.020	-0.023	0.012	-0.061	0.023	-0.003	2.12	-1.454
P20	1 ~ 14	0.004	-0.001	0.009	0.002	0.005	-0.004	0.000	-0.004	0.000	-0.008	0.004	-0.003	0.000	-0.008
p ₂₁		0.005	-0.004	0.007	0.02	0.004	-0.001	0.006	0	0.004	0.041	0.005	-0.001	0.304	0.543
P22		0.004	0.003	0.006	0.013	0.005	-0.004	0.007	0.003	0.004	0.041	0.006	-0.007	0.306	0.546
π1		0.001	0	0.002	-0.001	0.001	0.004	0.001	0.003	0.002	0.025	0.001	0.003	0.062	0.25
β10		0.019	-0.006	0.012	0.012	0.012	0.001	0.011	0.011	0.007	0.074	0.015	-0.009	0.006	-0.005
β11	Ca	0.015	-0.002	0.013	-0.041	0.009	0.002	0.008	-0.001	0.007	-0.073	0.014	-0.007	2.131	1.457
ßı	Se II.	0.016	0.006	0.017	-0.05	0.01	-0.01	0.008	-0.012	0.007	-0.07	0.013	0.003	2.116	-1.452
β20	E *	0.004	-0.001	0.003	-0.003	0.002	0.002	0.002	0	0.004	-0.063	0.002	0	0.006	-0.005
β ₂₁	La	0.003	-0.013	0.003	0.005	0.002	-0.004	0.002	-0.001	0.003	0.047	0.003	-0.006	0.302	0.543
β22	Çê Çê	0.005	-0.011	0.004	0.012	0.003	0.001	0.002	0.005	0.003	0.048	0.002	0	0.308	0.548
π _i		0.001	0.004	0.001	0.016	0.001	0.005	0.001	0.003	0.002	0.026	0.001	0.004	0.062	0.25
β ₁₀		2213	0.942	0.735	-0.04	0.169	0	0.017	0.075	0.01	0.089	0.119	0.034	0.017	-0.008
β ₁₁	Cas	3461	-0.021	0.398	0.097	0.478	-0.244	0.205	-0.35	0.078	-0.247	0.37	-0.16	2.311	-1.514
β_{12}	e TΠ·	362.7	-3.15	0.399	0.059	0.445	-0.259	0.193	-0.338	0.081	-0.252	0.315	-0.178	2.332	-1.52
β ₂₀	Е «	2213	0.942	0.021	-0.001	0.022	0	0.008	-0.062	0.008	-0.086	0.012	-0.011	0.017	-0.008
β_{21}	t,	350.0	1.978	0.032	0.003	0.014	0.015	0.012	0.09	0.008	0.085	0.017	0.002	0.254	0.486
β ₂₂		3541	-1.15	0.093	-0.009	0.011	0.003	0.011	0.086	0.008	0.086	0.014	-0.002	0.251	0.48
π_1		0.061	0.246	0.008	0.003	0.009	0.035	0.034	0.145	0.044	0.207	0.008	0.034	0.062	0.25
β ₁₀		0.525	0.082	0.037	-0.008	0.034	-0.008	0.033	0.02	0.022	0.06	0.038	0.011	0.007	-0.01
β_{11}		0.366	-0.081	0.039	-0.07	0.04	-0.008	0.034	-0.017	0.028	-0.043	0.042	0	2.279	-1.504
β ₁₂	Cas e	0.438	-0.091	0.037	-0.081	0.039	0.005	0.037	0.004	0.033	-0.039	0.04	0.003	2.291	-1.507
β ₂₀	ĪV: € ~	0.029	-0.004	0.008	-0.017	0.006	-0.007	0.007	-0.011	0.006	-0.022	0.006	0.003	0.007	-0.01
β_{21}	t,	0.116	0.051	0.007	0.001	0.006	0.007	0.007	0.016	0.007	-0.007	0.006	-0.004	0.264	0.496
β_{22}		0.033	0.066	0.009	0.006	0.009	0.002	0.009	0.01	0.007	0	0.007	0.005	0.263	0.493
π_1		0.011	-0.008	0.002	0.023	0.002	0.004	0.002	-0.001	0.002	0.013	0.002	0.003	0.062	0.25

para	meter	MLE		TLE		Mixrigt		Mix	regi.	MixngLTA.		MixogLTA.		Mixn	el ta.
β ₁₀		21.68	3.468	1.235	1.102	1.384	1.115	1.429	1.166	1.036	0.99	1.192	1.057	1.42	1.186
β ₁₁	Cas e V:	1.761	-0.521	0.012	-0.022	0.067	-0.022	0.04	0.017	0.035	0	0.053	0.002	2.725	-1.642
β ₁₂	E ~	2.36	-0.381	0.017	-0.023	0.067	-0.017	0.038	0.008	0.034	-0.004	0.043	-0.003	2.684	-1.628
β ₂₀	om	12.96	2.499	1.07	1.032	0.888	0.937	0.967	0.979	0.845	0.914	0.866	0.924	1.42	1.186
β ₂₁	al	0.373	0.212	0.003	-0.006	0.004	-0.006	0.006	-0.004	0.007	-0.012	0.004	-0.006	0.159	0.358
β ₂₂	1)	0.292	0.208	0.003	-0.001	0.003	0	0.006	0.005	0.007	-0.004	0.004	-0.004	0.171	0.372
π_1	· ·	0.089	0.053	0.002	0.027	0.001	0.005	0.001	-0.008	0.002	-0.004	0.001	0.005	0.062	0.25
β ₁₀		1.047	0.051	0.041	0.005	0.026	-0.017	0.031	0	0.017	0.058	0.029	-0.001	0.006	-0.002
β ₁₁		0.387	0.036	0.048	-0.095	0.026	-0.003	0.028	-0.008	0.022	-0.021	0.027	0.023	2.401	-1.543
β ₁₂	e	0.822	0.034	0.051	-0.119	0.02	0.011	0.024	0.001	0.027	-0.043	0.035	-0.007	2.394	-1.541
β ₂₀	VI	0.043	0.013	0.006	0.003	0.006	-0.005	0.007	-0.009	0.006	-0.029	0.005	0.003	0.006	-0.002
β ₂₁	¢ ~ 0:	0.087	0.048	0.006	0.01	0.006	0.007	0.007	0.011	0.008	0.027	0.006	0.001	0.229	0.457
β ₂₂		0.137	0.052	0.007	0.024	0.004	-0.01	0.006	-0.006	0.008	0.025	0.007	0.015	0.23	0.459
π_1		0.007	-0.032	0.001	0.003	0.001	-0.001	0.001	-0.004	0.002	-0.004	0.001	-0.006	0.062	0.25
	Car	1101	1 152	0.022	0.01	1.206	0.205	0.012	0.050	0.012	0.000	0.006	0.000	0.005	0.005
β ₁₀	e	12.01	-2.1/5	0.000	0.01	1.200	0.200	0.013	0.009	0.012	0.0/1	0.020	-0.005	0.007	-0.005
β ₁₁	VII	4.656	1.49	0.049	-0.102	2.642	1.485	0.013	-0.037	0.02	-0.088	0.02	-0.012	2.76	-1.657
β ₁₂	N(0)	4.657	1.513	0.039	-0.098	2.699	1.503	0.015	-0.042	0.017	-0.09	0.022	-0.002	2.746	-1.653
β ₂₀	mith	10.79	2.284	0.005	0.002	0.006	0.003	0.006	-0.044	0.005	-0.052	0.005	0.005	0.007	-0.005
β ₂₁	5%	11.86	3.384	0.006	0.011	0.023	0.133	0.004	0.028	0.005	0.035	0.005	0.004	0.131	0.343
β ₂₂	high	1151	3.332	0.006	0.003	0.024	0.13	0.005	0.029	0.005	0.041	0.006	-0.006	0.134	0.347
π1	rage outli ers	0.133	0.191	0.002	0.004	0.008	-0.088	0.004	0.023	0.002	0.003	0.001	0.001	0.062	0.25

6.Conclusion

In this paper, we propose a new robust estimation procedure for the mixture linear regression models by assuming the random error has a Laplace distribution or t distribution or normal distribution. The robustness is achieved essentially by LTA procedure, and implemented by the EM algorithm. The efficiency and effectiveness of the proposed EM algorithm depends upon the fact that the Laplace or t distribution is a scale mixture of a normal distribution and a distribution of a function of exponentially distributed random variable. The simulation study shows that the proposed method LTA_L is superior to and comparable to existing robust estimation procedures in all simulation conditions, but LTA_t and LTA_N are less preferred, and some other methods are preferred over them, such as Mixrigt and MixrigL in some cases.Specifically, we have the following findings:

- 1. The MLE works the best for Case I $\epsilon \sim N(0,1)$ and Case II: $\epsilon \sim Laplace$ with mean 0 and variance 1, but fails to provide reasonable estimates for Case III, VI and VII. And in the rest of the cases its results are not bad.
- 2. TLE has relatively better performance than Mixregt for Case IV, V and VII when n = 100, but have close performance to Mixregt in Case II and VI. But for Case I and III we find that Mixrigt is preferred. The results we obtained did not differ at the sample size of 200 except in the fourth Case; in this Case we find that Mixrigt is better than TLE. At n = 400, TLE has close performance to Mixregt, except for the last Case where Mixregt works better than TLE.
- 3. MixregL has better performance than TLE and Mixregt in most Cases whether n = 100 or 200 or 400. Otherwise, their performance is comparable.
- 4. MixrigLTA_L have overall better performance than others.

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