# Analytical Solution of a System of Ordinary 

 Differential EquationsE. A. A. Ziada<br>Nile Higher Institute for Engineering and Technology, Mansoura, Egypt. eng_emanziada@yahoo.com


#### Abstract

In this paper, we apply the Adomian decomposition method (ADM) for solving linear and nonlinear system of ordinary differential equations (ODEs). The existence and uniqueness of the solution are proved. The convergence of the series solution and the error analysis are discussed. Some numerical examples are solved.


Keywords: Adomian Method; existence; uniqueness; error analysis.

## 1 Introduction

Differential equations have many applications in engineering and science, including electrical networks, fluid flow, control theory, fractals theory, electromagnetic theory, viscoelasticity, potential theory, chemistry, biology, optical and neural network systems [1]-[11]. In this paper, Adomian decomposition method (ADM) [12]-[19] is used to solve these type of equations. This method has many advantages, it is efficiently works with different types of linear and nonlinear equations in deterministic or stochastic fields and gives an analytic solution for all these types of equations without linearization or discretization. The convergence of the series solution and the error analysis are discussed. Some numerical examples are solved.

## 2 Problem solving

### 2.1 The solution algorithm

Let us consider the system of nonlinear ODEs,

$$
\begin{align*}
\mathrm{L} y_{i}(t)+f_{i}(y) & =x_{i}(t), \quad i=1,2, \ldots, m \\
y_{i}^{(j)} & =0, \quad j=0,1,2, \ldots, n-1 . \tag{1}
\end{align*}
$$

Where

$$
\begin{align*}
& \mathrm{L}=L+R,  \tag{2}\\
& L=\frac{d^{n}}{d t^{n}}, \quad \text { and } \quad R=\sum_{k=0}^{n-1} a_{k}(t) \frac{d^{k}}{d t^{k}} . \tag{3}
\end{align*}
$$

And $f_{i}(y)$ are the nonlinear terms expanded in terms of Adomian polynomials,

$$
\begin{align*}
& f_{i}(y)=\sum_{n=0}^{\infty} A_{i, n},  \tag{4}\\
& A_{i, n}=\left(\frac{1}{n!}\right) \frac{d^{n}}{d \lambda^{n}}\left[f_{i}\left(\sum_{j=0}^{\infty} \lambda^{j} y_{j}\right)\right]_{\lambda=0}, \tag{5}
\end{align*}
$$

And the linear operator $L$ as defined before in equations (2) and (3). Substitute from (3) and (2) into (1) we get,

$$
\begin{align*}
& (L+R) y_{i}(t)+\sum_{n=0}^{\infty} A_{i, n}=x_{i}(t),  \tag{6}\\
& L y_{i}(t)=x_{i}(t)-R y_{i}(t)-\sum_{n=0}^{\infty} A_{i, n}, \tag{7}
\end{align*}
$$

Applying $L^{-1}$ to both sides of equation (7) we have,

$$
\begin{equation*}
y_{i}(t)=L^{-1} x_{i}(t)-L^{-1} R y_{i}(t)-L^{-1}\left(\sum_{n=0}^{\infty} A_{i, n}\right) \tag{8}
\end{equation*}
$$

$$
y_{i}(t)=\sum^{\infty} y_{i, n}(t)
$$

Decompose and substitute in equation (8), we get the following recursive relations,

$$
\begin{align*}
y_{i, 0}(t) & =L^{-1} x_{i}(t)  \tag{9}\\
y_{i, n}(t) & =-L^{-1} R y_{i, n-1}(t)-L^{-1} A_{i, n-1} \tag{10}
\end{align*}
$$

Finally, the solution of (1) is

$$
\begin{equation*}
y_{i}(t)=\sum_{n=0}^{\infty} y_{i, n}(t) . \tag{11}
\end{equation*}
$$

## 3 Convergence analysis

### 3.1. Existence and uniqueness of the solution

Define the mapping $F: E \rightarrow E$ where $E$ is the Banach space ( $C[I,\|\cdot\|$ ), the space of all continuous functions on 1 with the norm $\|f(t)\|=\max _{t \in I}|f(t)|, \quad\left|\sum_{k=0}^{n-1} a_{k}(t)\right| \prec M$ $\forall 0 \leq \tau \leq t \leq 7, M$ is finite constant and $f_{i}(y)$ satisfy Lipschitz condition with Lipschitz constants $C_{i}$ such as, constants $C_{i}$ such as,

$$
\left|f_{i}(y)-f_{i}(z)\right| \leq C_{i}\left|y_{i}-z_{i}\right|
$$

## Theorem 1:

The problem (1) has a unique solution whenever $0<\beta<1$ where, $\beta=T^{n}[M+C]$.

## Proof:

The mapping $F: E \rightarrow E$ is defined as,

$$
F y_{i}(t)=L^{-1} x_{i}(t)-L^{-1} R y_{i}(t)-L^{-1}\left(f_{i}\left(y_{i}\right)\right)
$$

Let $y(t), \Delta(t) \in E$ :

$$
\begin{aligned}
\left\|F y_{i}-F z_{i}\right\| & =\max _{t \in I}\left|-L^{-1} R y_{i}(t)-L^{-1}\left(f\left(y_{i}\right)\right)+L^{-1} R z_{i}(t)+L^{-1}\left(f_{i}\left(z_{i}\right)\right) d \tau\right| \\
& =\max _{t \in I}\left|\left[L^{-1} R y_{i}(t)-L^{-1} R z_{i}(t)\right]+\left[L^{-1}\left(f_{i}\left(y_{i}\right)\right)-L^{-1}\left(f_{i}\left(z_{i}\right)\right)\right] d \tau\right| \\
& \leq \max _{t \in I}\left|L^{-1} R\left[y_{i}(t)-z_{i}(t)\right]\right|+\max _{t \in I}\left|L^{-1}\left[f_{i}\left(y_{i}\right)-f_{i}\left(z_{i}\right)\right]\right| d \tau \\
& \leq \max _{t \in I}\left|y_{i}(t)-z_{i}(t)\left\|L^{-1} R[1]\left|+C_{i} \max _{t \in I}\right| y_{i}(t)-z_{i}(t)\right\| L^{-1}[1]\right| d \tau \\
& \leq \max _{t \in I}\left|y_{i}(t)-z_{i}(t)\right|\left|\sum_{k=0}^{n-1} a_{k}(t)\right| T^{n-k}+C_{i} T^{n} \max _{t \in I}\left|y_{i}(t)-z_{i}(t)\right| \\
& \leq\left[M T^{n}+C_{i} T^{n}\right]\left\|y_{i}-z_{i}\right\| \\
& \leq T^{n}\left[M+C_{i}\right]\left\|y_{i}-z_{i}\right\|
\end{aligned}
$$

And let $\left|C_{i}\right| \leq C$, then

$$
\begin{aligned}
\left\|F y_{i}-F z_{i}\right\| & \leq T^{m}[M+C]\left\|y_{i}-z_{i}\right\| \\
& \leq \beta\left\|y_{i}-z_{i}\right\|
\end{aligned}
$$

Under the condition, $0<\beta<1$, the mapping $F$ is contraction and hence there exists a unique
solution of the problem (1)-(2) and this completes the proof.

### 3.2. Proof of convergence

## Theorem 2:

The series solution (10) of the problem (1)-(2) using ADM converges if $\left|y_{j, 1}\right|<\infty$ and $0<\beta<1, \beta=T^{T}[M+L]$.

Proof: Define the sequence $\left\{S_{j, n}\right\}$ such that, $S_{j, n}=\sum_{i=0}^{n} y_{j, i}(t)$ is the sequence of partial sums from the series solution $\sum_{i=0}^{\infty} y_{j, i}(t)$ since,

$$
f_{j}(y)=f_{j}\left(\sum_{i=0}^{\infty} y_{j, i}(t)\right)=\sum_{i=0}^{\infty} A_{j, i}\left(y_{0}, y_{1}, \ldots, y_{i}\right)
$$

So,

$$
f\left(S_{j, n}\right)=\sum_{i=0}^{n} A_{j, i}\left(y_{0}, y_{1}, \ldots, y_{i}\right)
$$

Let $S_{j, n}$ and $S_{j, m}$ be two arbitrary partial sums with $n>n$. Now, we are going to prove that $\left\{S_{j, n}\right\}$ is a Cauchy sequence in this Banach space.

$$
\begin{aligned}
\left\|S_{j, n}-S_{j, m}\right\| & =\max _{t \in I}\left|S_{j, n}-S_{j, m}\right|=\max _{t \in I}\left|\sum_{i=m+1}^{n} y_{j, i}(t)\right| \\
& =\max _{t \in I}\left|\sum_{i=m+1}^{n}\left[L^{-1} R y_{j, i}(t)+L^{-1}\left(f_{j}\left(y_{j}\right)\right)\right]\right| \\
& =\max _{t \in I}\left|\left[L^{-1} R \sum_{i=m+1}^{n} y_{j, i}(t)+L^{-1} \sum_{i=m+1}^{n} A_{j, i} d \tau\right]\right| \\
& =\max _{t \in I}\left|\left[L^{-1} R \sum_{i=m}^{n-1} y_{j, i}(t)+L^{-1} \sum_{i=m}^{n-1} A_{j, i} d \tau\right]\right|
\end{aligned}
$$

$$
\begin{aligned}
& =\max _{t \in I} \mid\left[L^{-1} R\left[S_{j, n-1}-S_{j, m-1}\right]+L^{-1}\left[\left(\left(S_{j, n-1}\right)-\not\left(\left(S_{j, m-1}\right)\right] d \tau\right] \mid\right.\right. \\
& \leq \max _{t \in I} L^{-1} R\left|S_{j, n-1}-S_{j, m-1}\right|+L^{-1}\left|\ell\left(S_{j, n-1}\right)-\ell\left(S_{j, m-1}\right)\right| d \tau \\
& \leq \max _{t \in I} L^{-1} R\left|S_{j, n-1}-S_{j, m-1}\right|+L^{-1}\left|\ell\left(S_{j, n-1}\right)-\AA\left(S_{j, m-1}\right)\right| d \tau \\
& \leq\left[M T^{n}+C_{i} T^{n}\right]\left\|S_{j, n-1}-S_{j, m-1}\right\| \\
& \leq \beta\left\|S_{j, n-1}-S_{j, m-1}\right\|
\end{aligned}
$$

Let $n=m+1$ then,

$$
\left\|S_{j, m+1}-S_{j, m}\right\| \leq \beta\left\|S_{j, m}-S_{j, m-1}\right\| \leq \beta^{2}\left\|S_{j, m-1}-S_{j, m-2}\right\| \leq \cdots \leq \beta^{m}\left\|S_{j, 1}-S_{0}\right\|
$$

From the triangle inequality we have,

$$
\begin{aligned}
\left\|S_{i, n}-S_{i, m}\right\| & \leq\left\|S_{j, m+1}-S_{j, m}\right\|+\left\|S_{j, m+2}-S_{j, m+1}\right\|+\cdots+\left\|S_{j, n}-S_{j, n-1}\right\| \\
& \leq\left[\beta^{m}+\beta^{m+1}+\cdots+\beta^{n-1}\right]\left\|S_{j, 1}-S_{j, 0}\right\| \\
& \leq \beta^{m}\left[1+\beta+\cdots+\beta^{n-m-1}\right]\left\|S_{j, 1}-S_{j, 0}\right\| \\
& \leq \beta^{m}\left[\frac{1-\beta^{n-m}}{1-\beta}\right]\left\|y_{j, 1}(t)\right\|
\end{aligned}
$$

Since, $0<\beta<1$, and $n>m$ then, $\left(1-\beta^{n-m}\right) \leq 1$. Consequently,

$$
\begin{aligned}
\left\|S_{j, n}-S_{j, m}\right\| & \leq \frac{\beta^{m}}{1-\beta}\left\|y_{j, 1}(t)\right\| \\
& \leq \frac{\beta^{m}}{1-\beta} \max _{t \in I}\left|y_{j, 1}(t)\right|
\end{aligned}
$$

but, $\left|y_{j, 1}(t)\right|<\infty$ and as $m \rightarrow \infty$ then, $\left\|S_{j, n}-S_{j, m}\right\| \rightarrow 0$ and hence, $\left\{S_{j, n}\right\}$ is a Cauchy sequence in this Banach space so, the series $\sum_{n=0}^{\infty} y_{j, n}(t)$ converges and this completes the proof.

### 3.3. Error analysis

For ADM, we can estimate the maximum absolute truncated error of the Adomian's series solution in the following theorem.

Theorem 3: The maximum absolute truncation error of the series solution (10) to the problem (1)-(2) is estimated to be,

$$
\max _{t \in J}\left|y_{j}(t)-\sum_{i=0}^{m} y_{j, i}(t)\right| \leq \frac{\beta^{m}}{1-\beta} \max _{t \in I}\left|y_{j, 1}(t)\right|
$$

Proof: From Theorem 2 we have,

$$
\left\|S_{j, n}-S_{j, m}\right\| \leq \frac{\beta^{m}}{1-\beta} \max _{t \in I}\left|y_{j, 1}(t)\right|
$$

But, $S_{j, n}=\sum_{i=0}^{n} y_{j, i}(t)$ as $n \rightarrow \infty$ then, $S_{j, n} \rightarrow y_{j}(t)$ so,

$$
\left\|y_{j}(t)-S_{j, m}\right\| \leq \frac{\beta^{m}}{1-\beta} \max _{t \in I}\left|y_{j, 1}(t)\right|
$$

Therefore, the maximum absolute truncation error in the interval ${ }^{1}$ is,

$$
\max _{t \in I}\left|y_{j}(t)-\sum_{j=0}^{m} y_{j, i}(t)\right| \leq \frac{\beta^{m}}{1-\beta} \max _{t \in I}\left|y_{j, 1}(t)\right|
$$

And this completes the proof.

## 4. Numerical Examples

Example 1: Consider the following linear system of ODEs,

$$
\begin{align*}
\frac{d y_{1}}{d t} & =2 t-t^{3}+y_{2} \\
\frac{d y_{2}}{d t} & =3 y_{1} \\
\frac{d y_{3}}{d t} & =4 y_{2} \tag{12}
\end{align*}
$$

Subject to the initial conditions,

$$
y_{1}(0)=y_{2}(0)=y_{3}(0)=0,
$$

Which has the exact solution $y_{1}(t)=t^{2}, y_{2}(t)=t^{3}$ and $y_{3}(t)=t^{4}$.
Applying ADM to the system (12) we have,

$$
\begin{equation*}
y_{1,0}=t^{2}-\frac{t^{4}}{4}, \quad y_{1, j+1}=\int_{0}^{t} y_{2, j}(\tau) d \tau \tag{13}
\end{equation*}
$$

$$
\begin{align*}
& y_{2,0}=0, \quad y_{2, j+1}=3 \int_{0}^{t} y_{1, j}(\tau) d \tau,  \tag{14}\\
& y_{3,0}=0, \quad y_{3, j+1}=4 \int_{0}^{t} y_{2, j}(\tau) d \tau . \tag{15}
\end{align*}
$$

Using the relations (13)-(15), the first three-terms of the series solution are,

$$
\begin{gather*}
y_{1}=t^{2}-\frac{t^{4}}{4}-\frac{1}{40} t^{4}\left(-10+t^{2}\right)+\cdots  \tag{16}\\
y_{2}=t^{3}-\frac{3 t^{5}}{20}+\cdots  \tag{17}\\
y_{3}=t^{4}-\frac{t^{6}}{10}+\cdots \tag{18}
\end{gather*}
$$

Figures 1.a-1.c show a comparison between the exact and ADM solutions of $y_{1}, y_{2}$ and $y_{3}$ $(n=50)$.



Figure 1.b: ADM and Exact Sol. y2


Figure 2.c: ADM and Exact Sol. y3
Example 2: Consider the following nonlinear system of ODEs,

$$
\begin{align*}
& \frac{d^{2} y_{1}}{d t^{2}}=2-t^{9}+y_{2}^{3} \\
& \frac{d^{2} y_{2}}{d t^{2}}=6 t-t^{8}+y_{1}^{4} \tag{19}
\end{align*}
$$

## Subject to the initial conditions,

$$
y_{1}(0)=y_{1}^{\prime}(0)=y_{2}(0)=y_{2}^{\prime}(0)=0,
$$

Which has the exact solution $y_{1}(t)=t^{2}$ and $y_{2}(t)=t^{3}$.
Applying ADM to the system (19) we have,

$$
\begin{align*}
& y_{1,0}=t^{2}-\frac{t^{11}}{110}, \quad y_{1, j+1}=\int_{0}^{t} \int_{0}^{t} A_{1, j}(\tau) d \tau d \tau, \\
& y_{2,0}=t^{3}-\frac{t^{10}}{90}, \quad y_{2, j+1}=\int_{0}^{t} \int_{0}^{t} A_{2, j}(\tau) d \tau d \tau . \tag{20}
\end{align*}
$$

Using the relations (20), the first two-terms of the series solution are,

$$
\begin{align*}
& y_{1}=t^{2}-\frac{t^{18}}{9180}+\frac{t^{2}}{162000}-\frac{t^{32}}{723168000}+\cdots,  \tag{21}\\
& y_{2}=t^{3}-\frac{t^{19}}{9405}+\frac{t^{28}}{1524600}-\frac{t^{37}}{443223000}+\frac{t^{46}}{303068700000}+\cdots . \tag{22}
\end{align*}
$$

Figures 2.a and 2.b show ADM solution of $y_{1}, y_{2} \quad(n=5)$.


Figure 2.a: ADM and Exact Sol. y1


Figure 2.b: ADM and Exact Sol. y2

## References

1) K. S. Miller, and B. Ross, (1993), An Introduction to the Fractional Calculus and Fractional Differential Equations, Wiley-Interscience, New York.
2) I. Podlubny, (1999), Fractional Differential Equations, Academic Press, New York.
3) A. A. Kilbas, H. M. Srivastava, and J. J. Trujillo, (2006), Theory and Applications of Fractional differential equations, Elsevier, New York.
4) Sh. A. Abd El-Salam, and A. M. A. El-Sayed, (2007), On the stability of some fractional-order nonautonomous systems, Electronic Journal of Qualitative Theory of Differential Equations, 6, 1-14.
5) A. M. A. El-Sayed, and Sh.A. Abd El-Salam, (2008), On the stability of a fractional-order differential equation with nonlocal initial condition, Electronic Journal of Qualitative Theory of Differential Equations, 29, 1-8.
6) D. J. Evans, and K. R. Raslan, (2005), The Adomian decomposition method for solving delay differential equation, International Journal of Computer Mathematics, (UK), 82, 49-54.
7) Najeeb Alam Khan, Oyoon Abdul Razzaq, Asmat Ara, and Fatima Riaz (2016), Numerical Solution of System of Fractional Differential Equations in Imprecise Environment, DOI: 10.5772/64150.
8) Abdon Atangana, and Ernestine Alabaraoye (2013), Solving a system of fractional partial differential equations arising in the model of HIV infection of CD4+ cells and attractor one-dimensional Keller-Segel equations, Advances in Difference Equations, 94, 1-14.
9) Hasanen A. Hammad, and Manuel De la Sen (2021), Tripled fixed point techniques for solving system of tripled-fractional differential equations, AIMS Mathematics 6 (3) 2330-2343.
10) S. Z. Rida, and A. A. M. Arafa (2011), New Method for Solving Linear Fractional Differential Equations, International Journal of Differential Equations,1-8. doi:10.1155/2011/814132.
11) Daraghmeh, A., Qatanani, N. and Saadeh, A. (2020) Numerical Solution of Fractional Differential Equations. Applied Mathematics, 11, 1100-1115. doi: 10.4236/am.2020.1111074.
12) G. Adomian, (1995), Solving Frontier Problems of Physics: The Decomposition Method, Kluwer.
13) G. Adomian, (1983), Stochastic System, Academic press.
14) G. Adomian, (1986), Nonlinear Stochastic Operator Equations, Academic press, San Diego.
15) G. Adomian, (1989), Nonlinear Stochastic Systems: Theory and Applications to Physics, Kluwer.
16) K. Abbaoui, and Y. Cherruault, (1994), Convergence of Adomian's method applied to differential equations, Computers Math. Applic., 28, 103-109.
17) Y. Cherruault, G. Adomian, K. Abbaoui, and R. Rach, (1995), Further remarks on convergence of decomposition method, International J. of Bio-Medical Computing., 38, 89-93.
18) N. T. Shawaghfeh, (2002), Analytical approximate solution for nonlinear fractional differential equations, J. Appl. Math. Comput., 131, 517-529.
19) I. L. El-kalla, (2008), Convergence of the Adomian method applied to a class of nonlinear integral equations, Applied Mathematics Letters, 21, 372-376.
