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Young's modulus of tungsten at elevated temperatures using

synchronous laser shadow vibrometry

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Abstract:

This paper presents the use of an improved laser shadowgraphy method for measuring the dynamic elastic moduli of tungsten, from room temperature to near melting point. The method is based on measuring the frequency of impulse induced longitudinal vibration of a tungsten filament, subject to joule heating. The natural resonance frequency of the filament is obtained by lock-in synchronous photo-detection of the laser generated filament shadowgraph. The correlation between the filament natural frequency and its temperature lead to the calculation of shear modulus at variable temperatures, the tensile and bulk modului of tungsten. The results were compared to those obtained by laser Doppler vibrometry of a tungsten wire induced by pulsed current technique. Our method permitted a wider measuring temperature range and an easier calculation procedure. The used setup was simple, non-destructive, non-contacting and accurate, enabling low cost vibrometry measurements that help in future synthesis and test of new grades of refractory materials, deployed as plasma facing material in the latest fusion reactor or super alloys in critical applications.

Keywords:

Tungsten, elasticity moduli, elevated temperatures, , shadowgraphy, laser vibrometry, lock-in amplifier, low cost.

Background

As the demand for tungsten and its alloys in engineering and experimental nuclear physics continue to grow, the need for performing more accurate thermo-mechanical testing also increases [1-10]. The most required metallurgic characteristic in this context is the elevated temperature dynamic elasticity [11-13] that helps in developing advanced metallic grads of refractory materials [14-18]. Many technique were developed to measure the dynamic elastic moduli [19-21] but fewer is suitable for elevated temperatures [22-41]. One of the prominent technique used to measure the dynamic young's modulus of tungsten at high stresses and temperatures, is the laser Doppler vibrometry of a wire sample induced by high current pulses [23]. This technique enable measurements in the range from room temperature to $2650 \square C$. A second order parametric equation is used for fitting the experimentally obtained Young's modulus data over the mentioned thermal range on the form:



$$E(T) = a_0 + a_1 T + a_2 T^2 \tag{1}$$

Where a_o , a_1 and a_2 are the regression constants. This result was achieved using a number of sophisticated equipment (such as laser Doppler vibrometer, spectrum analyzer, high-resolution pyrometer...) and through a complex procedure. This procedure is based on calculating *E* at a certain temperature *T* as an equivalent tensile modulus function on the form:

$$E(T) \equiv F(f(T, n, l), r, \rho(T), \nu(T), \xi(\nu))$$
⁽²⁾

Where f is radial frequency of the vibrating wire (depends on wire length l and the vibration mode n), r is its radius, ρ is its material density ν is the Poisson ratio and ξ is the root of Bessel function. Only two parameters in this method were obtained experimentally, those parameters are f and T. the rest are obtained through parameterization of published and reference data, characterizing tungsten. Moreover, T is another implicit function or:

$$T \equiv F^*(\varepsilon_T(R), I(\tau_e), \omega) \tag{3}$$

Where F^* the equivalent temperature function, ε_T is the emissivity of the wire surface at measured temperature (depends on surface roughness *R*), the electric current pulse intensity pulse duration τ_e and repetition rate ω .



Figure 1. Block diagram representing the measurement of the dynamic Young's modulus of a tungsten wire using laser Doppler vibrometry and pulse current heating technique [23]

So many sources of error are involved in this procedure, where the most important are those based on temperature calibration and non-linear thermal distribution along the wire sample, caused by clamps thermal cooling or "end-loss" [42-47]. Table 1. Shows a summary of the error sources in this procedure

Table 1. Summary of the error sources in LDV- pulse current heating technique



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The error	Origin of the error	effect on the
		measurements
Radial velocity and radial	Processing errors.	Low
displacement conversion errors.	• Thermal expansion of the wire cross-section.	
High temperature calibration error in	• LDV bad response due to optical saturation at	High
LDV	elevated temperature measurement.	
	• Laser speckle noise. [48, 49]	
Absolute temperature calibration error	• Sample roughness and variable emissivity as a	High
in pyrometer	function of temperature changes.	
	Optical absorption through cavity windows.	
	• Slow response of pyro-detector vs. thermal pulses.	
End-loss cooling error	• Thermal distribution gradient due to thermal	Very high
	cooling of the wire sample through clamps. [43]	
Nonlinear vibration modes and	• Vibrational multi-degree of freedom due to	Moderate
frequency error	nonlinear elasticity distribution along the wire	
	sample in analogy to the thermal gradient.	
	• Friction with the feed through end.	
Linear expansion error	 Variation in the wire sample cross-section. 	Low
Parametric approximation in	Various data for the same material grade.	Low
temperature variant inputs (i.e.		
emissivity, density and Poisson ratio)		

In this work, we reported a method for measuring the elastic moduli of tungsten at elevated temperatures with good accuracy, excluding the error caused by transient heating and thermal gradient. We propose in this contest to change the shape of the sample from straight wire to coiled filament, to make use of the shading factor discovered by Langmuir at the beginning of the last century [47]. He proved that the thermal gradient of the coiled tungsten wire, is lower than that of the straight wire [42]. We believe that such change should also ease the measurement procedure by decreasing the resonance frequency of the sample and excluding the higher vibration modes.

Theory of the measurement

The fundamental transverse vibration frequency of a wire string is calculated from the equation

$$f_{W} = \frac{1}{4l} \sqrt{\frac{E}{\rho}} \tag{4}$$

If the same string wire is reformed and coiled to form a fixed-fixed end compression spring (as seen in figure 2) of wire diameter d, coil diameter D, number of turns N and wire material shear modulus G, then, the frequency of the fundamental longitudinal vibration is given by the equation [50]:

$$f_s = \frac{d}{9ND^2} \sqrt{\frac{G}{\rho}} \tag{5}$$



Figure 2. Changing the symmetry of the sample from (a) String wire with transvers vibration, to (b) Helical coil with longitudinal vibration.

Dividing equation 5 by equation 4 to obtain the frequency ratio for both string and coil symmetry,

$$\frac{f_s}{f_w} = \frac{4dl}{9ND^2} \sqrt{\frac{G}{E}}$$
(6)

But E and G are both related by the Poisson ratio equation given by [51];

$$\nu = \left(\frac{E}{2G}\right) - 1\tag{7}$$

Replacing E and G in equation 6 by their value in equation 7 we obtain:

$$\frac{f_s}{f_w} = \frac{4dl}{9ND^2} \frac{1}{\sqrt{2(v+1)}}$$
(8)

However, the length of the coil wire can be approximated as a sum of the perimeters of N circular turns to obtain:

$$l \approx N\pi D \tag{9}$$

Replacing equation 9 in equation 8 to obtain:

$$\frac{f_s}{f_w} = \frac{4\pi d}{9D} \frac{1}{\sqrt{2(v+1)}}$$
(10)

Let μ representing the spring index of the helical spring like sample

$$\mu = \frac{D}{d} \tag{11}$$

By replacing equation 11 in equation 10 and assuming v = 0.28 to obtain

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$$\frac{f_s}{f_w} = \frac{5}{18} \ \mu^{-1} \tag{12}$$

If we choose $\mu = 4$, we conclude that $f_s = 0.087 f_w$ and the resonance frequency of the spring is at least one order of magnitude lower than the frequency of the equivalent string. This result will ease the measurement as well as it will exclude all sophisticated instruments from the test that will directly yields the shear modulus of the sample as given by the following equation obtained from equation 5:

$$G(T) = \rho(T) \left(\frac{9lD}{\pi d}\right)^2 f_s^2$$
(13)

The density of the sample as a function of temperature is given by the parametric equation [23]:

$$\rho(T) = 19302.9 + 2.3786 \times 10^{-1} T - 2.244 \times 10^{-5} T^2 \qquad kg.^{\circ}C.m^{-3} \qquad (14)$$

Once G(T) is obtained, E(T) and K(T) representing the bulk modulus can be easily calculated from the Poisson ratio relations as follows:

$$E(T) = 2G(T) [v(T) + 1]$$
(15)

and

$$K(T) = 2G(T) \frac{[v(T)+1]}{3[1-2v(T)]}$$
(16)

Also, the Poisson ratio of tungsten is obtained from the parametric equation [23]:

$$v(T) = 0.279 + 1.0895 \times 10^{-5} T \tag{17}$$

Using the formalism of exponents [52], the temperature T of incandescent tungsten coil as a function of it electric resistance R is calculated from the equation:

$$\frac{T+273}{T_o+273} = \left(\frac{R}{R_o}\right)^{0.83}$$
(18)

Where T_o and R_o represent the room temperature and room temperature resistance of the sample. If we replace T_o by 27 \square C and R by the voltage difference applied on the sample V divided the current passing through its terminals I we obtain:

$$T = \left[300 \times \left(\frac{V}{IR_o}\right)^{0.83}\right] - 273 \tag{19}$$

Now we are ready to measure the elastic moduli of tungsten as a function of temperature using only current, voltage and frequency readings, under the effect of mechanical impulse excitation. To retrieve natural vibration frequency data for the incandescent coil, we replaced



Doppler vibrometry by laser shadowgraphy, where vibrometry is applied on sample's shadow using a simple optical setup. (Figure 3 shows the block diagram of our proposed method)



Figure 3. block diagram representing the measurement of the dynamic Young's modulus of a tungsten filament using laser shadow-vibrometry and DC current heating technique.

As mentioned before, we introduced an new idea in shadowgraphy, by using synchronous optical detection under lock-in condition. This improvement enable to exclude laser speckles changes in the shadowgraph background from being detected as popcorn noise. the setup is then able to detect very small shifts in dark shadows positions even in the presence of noisy optical background such as artificial lighting and self-incandescence of the sample, with detection sensitivity approaching 60dB. If the filament is placed in the focal plane of the throw lens of focal length D_f , then, the shadowgraph of the filament is projected on the photo-detector at throw distance D_T With magnification factor X given by the equation:

$$X = \frac{D_T - D_f}{D_f} \tag{20}$$

If the filament undergoes a small in-plane position shift due to vibration, then this shift will be magnified at the shadowgraph plan by a factor of X. This method can detect small shifts as 1×10^{-7} m assuming that $X \le 2000 \times$ and knowing that the theoretical limit is in order of 1×10^{-8} m [53]. The amplitude of the lock-in output signal is proportional to the magnitude of laser intensity changes at the object's shadow bright/dark boundaries. In order to maximize the output signal, the laser source intensity should be adjusted to bring the photo-detector below saturation. In addition, it is important to place the detector window center at the boundary between the object's shadow and the background laser illumination at the shadowgraph plane. The resulting vibration pattern after one mechanical pulse that is required to excite the free natural resonance of the filament sample may be illustrated by a damping oscillation pattern as shown in figure 4.



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Figure 4. Free vibration pattern of elastic solids by pulse excitation technique

where the amplitude A of the oscillation at any time t after excitation, is given by the equation:

$$A(t) = Ae^{-t/\tau} \tag{21}$$

 τ is the time interval between A and A/e. This time interval depends on the internal friction of the sample that may represented by the inverse of the oscillation quality factor given by the expression [13];

$$Q^{-1} = \frac{\text{energy dissipated as heat per unit volume over one cyle}}{\text{energy stored per unit volume}}$$
(22)

$$Q^{-1} = \ln \frac{A(T)}{A(\tau)} = T/\pi \,\tau = 1/\pi \,\tau \,f_0 \tag{23}$$

Where. *T* is the period of one oscillation of frequency *f*. Hence, we can obtained Q^{-1} graphically from the impulse excitation pattern of the helical filament sample, the relation between the temperature and the internal friction of tungsten shall be revealed. The frequency spectrum of the resonance pattern may be obtained by fast Fourier transforms (FFT). Finally, our method has several major advantages over the pulsed current method. Table 2. summarizes the major parametric differences between laser Doppler vibrometry method and our laser shadow-vibrometry method for measuring the dynamic Young's modulus of tungsten at elevated temperatures.

Table 2. Parametric comparison between laser Doppler vibrometry and laser shadow-vibrometry method

Parameter	Doppler vibrometry method	laser shadowgraphy based- vibrometry method
Tungsten sample form	Wire sample	Coiled sample
Sample mass	$10^{-3} - 10^{-2}$ kg	$10^{-5} - 10^{-4} \text{kg}$
Sample preparation	Intensive	Extensive
Heating current type	Pulsed current	Direct current
Current intensity	10 ³ Amperes	few Amperes
Temperature measurement	Pyrometer	Absolute calibration
Mechanical excitation method	Electric pulse	Mechanical shock
Pulse shape	Non- Gaussian	Gaussian
Frequency detection	Laser Doppler vibrometry	Laser shadow- vibrometry
Detected phenomena	Laser frequency changes	Laser intensity variations
Phenomena causality	wire radial velocity changes	Coil shadow position changes
FFT signal analysis	Complex	Simple
Harmonic autocorrelation test	complex	Simple
Temperature gradient	High	Low



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Frequency range	Ultrasound	Audio
Setup cost	High	Low
Optical noise rejection	Low	Very high
Detector saturation	Very high	Very low
Room temperature elasticity	Only possible	Measurable
Measured parameter	Young's modulus	Shear modulus
Measurements range	Up to 2650 \square c	Up to 3400 \square c
Cooling	Yes	No (due small sample mass)
Power Consumed	High	Low
Sample surface roughness	Essential	Not Essential
Internal friction measurements	Not possible	Possible
Magnitude of Impulse force	Not controllable	Controllable
Direction of impulse force	Not selectable	Selectable
Type of the impulse force	Thermal gradient elastic reaction	Pure mechanical shock
Vibration mode control	Not possible	Possible

Experimental work



Figure 5. Experimental tungsten filament of 12 volt lamp (a) BA15 standard stop & flasher lamp blueprint (b) The basic lamp parts (c) Magnified view of the internal helical filament and its supports.

We designed a simple setup to prove the concept of measurement and to test its accuracy, so we decided to use commercial grade non-sag tungsten (99% purity) as test material basically used in incandescent lamps. We searched then for the best lamp with nearly ideal geometry and power that met our requirements. We selected a cheap P21W12V automotive incandescent lamp previously studied in many works before [54-60]. This lamp still in production and still sold in worldwide market. As shown in Figure 5.a, the selected lamp is compact, lightweight and has a nearly-spherical transparent glass envelope that permits laser shadowgraphy without distortion. It encloses a horizontal single coiled linear helical filament produced by powder metallurgy (Figure 5.b). This filament is clamped to a very thick refractory clamping supports relative to filament wire diameter which insure that their resonance frequency is so much higher than the frequency of the filament by an order of at least two decades. The contact surface area between the tungsten wire and the clamp is very small leading to a high thermal resistance that keeps the support relatively cold with comparison to the incandescent filament (Figure 5.c). The normal operating temperature of the filament is about 2400°C, hence we shall overdrive the lamp and exceeding the operating



voltage to increase the heating current till reaching the near melting temperature of tungsten. Table 3 summarized the basic physical parameters of lamp.

Doom tomporeture perometer	Symbol	Value	TIn:4
Koom temperature parameter	Symbol	value	Unit
Electric resistance	R	0.5	Ω
Wire material resistivity	ρ_e	5.65×10 ⁻⁸	$\Omega \text{ m}^{-1}$
Wire length	l	6×10 ⁻²	m
Wire diameter	d	9×10 ⁻⁵	m
Coil diameter	D	5×10 ⁻⁴	m
Spring index	μ	0.1	-
Coil length	L	6×10 ⁻⁶	m
Wire mass	т	1.1×10 ⁻⁵	kg
Wire material density	ρ	19300	kg / m ⁻³
Wire shear modulus	G	1.6×10^{11}	m^{-1}
Filament natural frequency (longitudinal)	f	<1×10 ³	Hz
Filament tungsten purity	W	99.0	%
Tungsten filament potassium impurities content	K	6	ppm
Lamp mass	М	0.015	kg
Lamp nominal operating voltage	V	12	V
Lamp nominal operating current	Ι	1.45	А
Lamp pressure	Р	≤1	bar
Inert gas type	Ar	-	-

Table 2. Physical characteristics of the P21W12V automotive tungsten lamp

The lamp sample is placed in a special mounting stage that permitted to a miniature 5volts solenoid motor plunger (type SF11015) to stroke its glass envelope. Each stroke is a 5ms Gaussian shape mechanical pulse along the filament axe that excite flexure vibration. The base of the lamp is fixed to the body of the stage by hard thermal silicon rubber that isolates the vibration of the lamp from the surroundings. The mounting stage enable precise position adjustment of the sample as well as the solenoid to insure best axial alignment. All mounting components are rigid enough to exclude their ultrasonic flexure resonance frequency from being interfered with that of the filament during measurements.



Figure 6. The sample mounting stage and its components.

If the solenoid plunger axe is perfectly aligned to the filament axe, the filament is forced to oscillate at the desired longitudinal modes only as shown in figure 7. The gap between the plunger and the filament must be adjusted also to yield best results. Later we discovered that the gap width can be reduced till vanishing and the filament still excited by the minimum solenoid plunger displacement. If the axis are misaligned then the filament shows undesired complex modes of vibration that is eventually a mix of both transversal and longitudinal modes.



Figure 7. Generation of filament undesired out-of-plan vibrations caused by the misalignment of the solenoid plunger axe to the filament axe

The sample mounting stage is then placed in a laser shadowgraphy-based vibrometer setup that we built as shown in the illustration of figure 8. This setup included a focusable 100mw semiconductor laser (wavelength = 536nm), electrically modulated with 33 kHz square wave carrier frequency at 90% modulation depth. The laser beam is expanded into linear beam shape by a rod lens (diameter = 5mm). The expanded beam is backlighting a horizontally the tungsten filament sample. The sample receives a mechanical excitation pulses from a from



solenoid motor plunger (stroke time = 5ms). A small focal length convex throw lens (focal length = 20mm) and a pinhole filter (hole diameter = 1mm) are used to generate a shadowgraph for vibrating filament. This shadowgraph is projected 60 cm away on a ground glass screen in which a photo-detector window (Photodiode type BPW21) is piercing the screen surface. The photo-detection of the filament shadow vibrations is synchronized with the laser modulation to detect the sample resonance signal to be recorded by digital storage oscilloscope.



Figure 8. Illustration of the setup basic optical components and instrumentation.

The setup was realized in a lightweight, compact, fast to install and easy to operate layout (figure 9). Most instrumentation were designed and manufactured in the laboratories of the Faculty of Science at Cairo University. The setup was also equipped by a parametric equalizer and an audio amplifier for demonstration of audible filament resonance at different temperatures.



Figure 9. The experimental setup and instrumentation used in this work



It is important to mention that the key of success in our measurement is the good optical alignment so that, the filament must completely illuminated by the laser beam (figure 10a) and the center of resulting shadowgram should be projected appropriately on the detector window (figure 10b).



Figure 10. Close-up showing (a) The optical setup during laser exposure (b) The filament shadowgraph projected on the aiming screen on the photo-detector window.

We started the measurements by heating the filament for at least one hour at temperature of 2400°c to sinter the non-sag filament and to allow minimum dislocation defects. At the moment of sudden heating we will notice a minor change in the filament pitch and axial position on the screen due to thermal expansion as we verified in another work [56]. If the alignment process concur some complications then it is recommended to exclude the pinhole filter for a while till finishing all necessary adjustments. Figure 11 show the importance of pinhole filter to screen the luminosity of the filament at incandescence.



Figure 11. (a) Magnified traveling microscope image of the tungsten filament part subjected to laser shadowgraphy. (b) The screen projected image of the filament part at incandescence without pinhole filter. (c) The shadowgraph of the same part of the filament at incandescence after adding the pinhole filter.

We restarted heating the filament slowly and gradually on a 50 or 100 mA increment. Each time we activated the solenoid and recorded the yielded impulse pattern by the storage oscilloscope till reaching the melting point and the lamp burned-out then. If the burnout profile [61] didn't include filament breakdown and showed only support melting as shown in figure 12, then the measurement must be repeated with another lamp brand with thicker support stems to ensure attaining the tungsten melting temperature.



Figure 12. Close-up showing different type of filament lamp samples burnout near melting temperature of tungsten.

All vibration patterns were analyzed by standard Microsoft Office Excel 2010 FFT analysis tool with resolution of 1024 channels to obtain the frequency spectrum of the filament at each temperature.

Results and Discussion

As seen in figure 13a, the vibration pattern of the tungsten filament at room temperature shows a very long damping time that lasts for several seconds. The time constant is 1.25 s, the quality factor of the oscillation is 3333 and hence, the internal friction is approximately 0.0003. The dominant oscillation wave form as seen in figure 13b, is sinusoidal which means that the oscillation mode is purely simple longitudinal.



Figure 13. Oscilloscope picture for the filament impulse vibration pattern at room temperature after a 5ms solenoid plunger pulse at different time scales (a) the damping pattern at 500ms /division. (b) The oscillation waveform at center amplitude at 1ms /division.

the vibration pattern of the tungsten filament near melting temperature shows a very short damping time that lasts for a fraction of second as seen in figure 14. The time constant is 0.1s, the quality factor of the oscillation dropped to 129.8 and hence, the internal friction increased to 0.0077 which is 25 times greater than that of room temperature The dominant oscillation wave form as seen in figure 14b, isn't any more sinusoidal which means that the oscillation mode my contain higher harmonics or different modes.



Figure 14. Oscilloscope picture for the filament impulse vibration pattern at 3300 °C after a 5ms solenoid plunger pulse at different time scales (a) the damping pattern at 500ms /division. (b) The oscillation waveform at 1ms /division.

If we study the frequency spectrum of the filament impulse response at room temperature as shown in figure 15a, we notice a single longitudinal vibration at 833Hz (denoted 1) and its symmetric complement at 27HZ that arises because of the double side band signal (DSB) pattern. All symmetric complements are ignored. As the filament temperature continue to increase, it began to lose its stiffness and it may sag under the effect of gravity. At this limit the excitation pulse induces several transversal modes of vibration. Figure 15b shows the filament impulse response at near melting temperature of tungsten, where the main longitudinal frequency mode (denoted 1) was decreased in magnitude and similarly in frequency to 411Hz. Several strong transversal modes tested by autocorrelation (denoted 2, 3, 4) are also present.



Figure 15. Symmetric DSB FFT spectrogram for (a) Room temperature impulse pattern of the filament. (b) Near melting temperature impulse pattern of the filament.

Now, If we plot the applied voltage versus the filament current data as shown in figure 16a we notice a very smooth curve leading to the calculation of filament temperature by using equation 19. Then we can plot the main longitudinal frequency versus filament current as



shown in figure 16b, to obtain the filament resonance frequency versus its temperature as shown in figure 17a.



Figure 16. Filament current versus (a) The applied voltage across filament terminals (b) Filament natural frequency.

Tests revealed that the elastic moduli of tungsten decrease as the temperature of the sample increases till the molting point on three steps. At first a slow decrease in elasticity moduli in the temperature range from room to 1000°C is observed, followed by an accelerated decrease till 2600°C, then suddenly drops to 20% of its initial value just below melting point. The reason behind this behavior may be ought to α and β crystalline phase transition of tungsten occurring at the edges of thermal slope inflections. Both Young and bulk moduli tends to intercept at melting point. This could be explained easily in light of symmetry anisotropy caused by crystalline zones melting.



Figure 17. Filament temperature versus (a) Filament natural frequency. (b) The elasticity moduli of the filament non-sag tungsten.

A remarkable enhancement and decreased of end-loss thermal gradient along the filament length L , is noticed after exceeding a temperature of 800° C as revealed by direct filament



photography shown in figure 18. Simultaneously, both the natural frequency of the filament and its vibration damping pattern time constant is decreased as the temperature increased as illustrated in the same figure. This decrease is due to the increase in tungsten internal friction as function of temperature [28] which may be described in a separated work.

Temperature	Incandescence	Frequency	Pattern
27 °C		837 Hz	
500 °C		820 Hz	
600 °C		815 Hz	
700 °C		808 Hz	
800 °C		805 Hz	
900 °C		797 Hz	
1000 °C		792 Hz	
1400 °C		762 Hz	
1800 °C		715 Hz	
2200 °C		646 Hz	
2600 °C		606 Hz	
3000 °C		470 Hz	
3300 °C		400 Hz	

Figure 18. Tungsten filament linear incandescence, natural frequency and impulse damping resonance pattern at different temperatures

Figure19. represents the normalized tungsten filament resistance versus the normalized resonance frequency showing a second order best fit curve. At near melting point the filament resistance is twenty times its room temperature value and the Young's modulus is one fifth its initial value and Hence the elasticity of tungsten is increased five folds at this extent.



Figure 19. Normalized regression of (a) Tungsten filament resistance versus Young's modulus (b) Tungsten filament natural frequency versus Young's modulus.

Figure 21a shows the tungsten elasticity moduli as a function of temperature obtained by our work and compared to data calculated using the results of reference [23]



Figure 20. (a) Elasticity moduli of tungsten obtained in this work compared to those calculated according to the result of reference [23] (b) Deviation percent of the young's modulus results from those of reference [23].

We found that, instead of equation 1, our experimental dynamic Young's modulus results may be better represented by a third order best-fit parametric equation on the form:

$$E(T) = a_0 + a_1 T + a_2 T^2 + a_3 T^3$$
(24)

Where T ranges from 27°C to 3400°C covering the whole range from room temperature to near melting point of tungsten. The value the regression constants a_o , a_1 , a_2 and a_3 are given in Table 4.



Table 4. Comparison between the coefficients of parametric regression equations for the Young's modulus experimental data obtained by laser Doppler vibrometry and laser shadowgraphy- based vibrometry.

Regression coefficients	a_0	<i>a</i> ₁	<i>a</i> ₂	<i>a</i> ₃
For the results of reference [] in the range from 27-2650°C	391.448×10^{11}	-1.3160×10^{7}	-1.4838×10^{4}	0
For the results of the present work in the range from 27-3400°C	4.31117×10^{11}	-3.3174×10^{7}	-1.2315×10^4	-2.4877

Conclusion

Changing the symmetry of the tungsten sample from wire string to helical coil in impulse excitation technique, enhances the dynamic elasticity moduli measurements. This enhancement is due to the minimization of temperature gradient over the sample length and decrease the end-loss. Similarly, changing the sample heating method from pulsed current to direct current also eases the measurement and exclude pyrometry from the measurement procedure. The use of shadowgraphy based vibrometry assisted by lock-in photo-detection technique enable low cost measurements, while increasing sample temperature to near melting point. Experimental tests on commercial grade non-sag tungsten filament of P21W lamp, leads to an exclusive third order parametric equation describing the Young's modulus of tungsten from 27°C to 3400°C measured for the first time. The obtained data is compared to those obtained by laser Doppler vibrometry and pulsed current heating method up to 2650°C. An agreement between the yield of both method with only 15% maximum deviation due to the effect of sample impurities on thermo-elastic behavior in our sample and the high thermal gradient of the reference sample. The main finding of our work is, the 5 folds decrease in tungsten Young's modulus was noticed near tungsten melting point as well as the 25 folds increase in internal friction. The method described in this work may be used as noncontact in-plan vibrometry tool for studying vibration of incandescent objects, unlimited by their surface emissivity or roughness. This method may help in the future synthesis and test of new grade of refractory materials, deployed as plasma facing material in the latest fusion reactor or super alloys in critical applications subject to extreme temperature.

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