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SOLVABILITY FOR NONLOCAL PROBLEM OF SECOND-ORDER DIFFERENTIAL EQUATION

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ABSTRACT. Here, we study the existence of a positive nondecreasing solution for the nonlocal problem of the differential equation

$$x^{''}(t) = f(t, x(t)), \ t \in (0, 1)$$
(1)

with the nonlocal condition

$$x(0) = \sum_{k=1}^{n-2} a_k \ x(\tau_k), \ x'(0) = \sum_{j=1}^{m-2} b_j \ x'(\eta_j)$$
(2)

where:

 $\tau_k, \eta_j \in (0,1), \ 0 < \tau_1 < \tau_2 < \dots < \tau_{n-2} < 1 \ \text{ and } \ 0 < \eta_1 < \eta_2 < \dots < \eta_{m-2} < 1.$

As an application, we prove that the existence of the maximal and minimal positive solutions for the nonlocal problem of the differential equation (1)with the nonlocal condition

$$x(0) = \alpha \ x(b), \ x'(0) = \beta \ x'(c).$$
(3)
where $b \in [\tau_1, \ \tau_{n-2}], \ c \in [\eta_1, \ \eta_{m-2}], \ \alpha = \sum_{k=1}^{n-2} a_k \text{ and } \beta = \sum_{j=1}^{m-2} b_j.$

1. INTRODUCTION

The study of initial value problems with nonlocal conditions is of significance, since they have applications in problems in physics and other areas of applied mathematics ([18],[19]).

Problems with non-local conditions have been extensively studied by several authors in the last two decades. The reader is referred examples, to ([1]-[5]), ([8]-[13]) and ([27]-[30]) and references therein.

2. INTEGRAL EQUATION REPRESENTATION

Consider the nonlocal problem (1) and (2). Assume the following assumptions

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- (i) $f: [0,1] \times \mathbb{R}^+ \to \mathbb{R}^+$ is measurable in $t \in [0,1]$ for all $x \in \mathbb{R}^+$ and continuous in $x \in \mathbb{R}^+$ for almost all $t \in [0,1]$. (ii) There exists an integrable function $m \in L^1[0,1]$ such that $f(t,x) \leq m(t)$.

- (iii) $\int_0^1 m(s) \, ds \le M$. (iv) $\sum_{k=1}^{n-2} a_k < 1$, $\sum_{j=1}^{m-2} b_j < 1$.

Lemma 1. The solution of the nonlocal problem (1)-(2) can be expressed by the integral equation

$$\begin{aligned} x(t) &= AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) \\ &+ Bt\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ \int_0^t (t - s) f(s, x(s)) ds, \end{aligned}$$

where $A = \left(1 - \sum_{k=1}^{n-2} a_k\right)^{-1}$ and $B = \left(1 - \sum_{j=1}^{m-2} b_j\right)^{-1}$.

Proof. Integrating equation (1), we obtain

$$x'(t) = x'(0) + \int_0^t f(s, x(s)) ds.$$
(4)

Let $t = \eta_j$ in (4), we get

$$\begin{aligned} x'(\eta_j) &= x'(0) + \int_0^{\eta_j} f(s, x(s)) ds, \\ \sum_{j=1}^{m-2} b_j x'(\eta_j) &= x'(0) \sum_{j=1}^{m-2} b_j + \sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds, \end{aligned}$$

and

$$x'(0) = x'(0) \sum_{j=1}^{m-2} b_j + \sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds,$$

$$\left(1 - \sum_{j=1}^{m-2} b_j\right) x'(0) = \sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds,$$

$$x'(0) = B \sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds,$$
(5)

where $B = \left(1 - \sum_{j=1}^{m-2} b_j \right)^{-1}$.

Integrating equation (4), we obtain

$$x(t) = x(0) + x'(0) t + \int_0^t (t-s)f(s,x(s))ds.$$
(6)

Let $t = \tau_k$ in (6), we get

$$x(\tau_k) = x(0) + x'(0) \tau_k + \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds,$$

$$\sum_{k=1}^{n-2} a_k x(\tau_k) = x(0) \sum_{k=1}^{n-2} a_k + x'(0) \sum_{k=1}^{n-2} a_k \tau_k + \sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds,$$

and

$$x(0) = x(0) \sum_{k=1}^{n-2} a_k + x'(0) \sum_{k=1}^{n-2} a_k \tau_k + \sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds,$$

$$\left(1 - \sum_{k=1}^{n-2} a_k\right) x(0) = x'(0) \sum_{k=1}^{n-2} a_k \tau_k + \sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds,$$

$$x(0) = Ax'(0) \sum_{k=1}^{n-2} a_k \tau_k + A \sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds$$
(7)

where $A = \left(1 - \sum_{k=1}^{n-2} a_k\right)^{-1}$. Substitute from (5) into (7), we deduce that

$$x(0) = AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) + A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right).$$
(8)

Substitute from (5) and (8) into (6), we get

$$\begin{aligned} x(t) &= AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) \\ &+ Bt\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ \int_0^t (t - s) f(s, x(s)) ds, \end{aligned}$$
(9)

which proves that the solution of the nonlocal problem (1)-(2) can be expressed by the integral equation (9).

3. EXISTENCE OF SOLUTION

Now, we study the existence of a solution of the nonlocal problem (1)-(2).

Theorem 1. Let the assumptions (i)-(iv) be satisfied. Then the nonlocal problem (1)-(2) has at least one solution $x \in C[0,1]$.

proof. Define the subset $Q_r \subset C[0,1]$ by $Q_r = \{x \in I\!\!R : |x(t)| \le r\}$. Clearly the set Q_r , is nonempty, closed and convex. Let H be an operator defined by

$$(Hx)(t) = AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) + A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) + B t\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) + \int_0^t (t - s) f(s, x(s)) ds.$$

Now, let $x \in Q_r$ then

$$\begin{aligned} |(Hx)(t)| &\leq AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} |f(s, x(s))| ds\right) \\ &+ A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) |f(s, x(s))| ds\right) + B t\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} |f(s, x(s))| ds\right) \\ &+ \int_0^t (t - s) |f(s, x(s))| ds. \\ &\leq AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^1 m(s) ds\right) + A\left(\sum_{k=1}^{n-2} a_k \int_0^1 m(s) ds\right) \\ &+ B\left(\sum_{j=1}^{m-2} b_j \int_0^1 m(s) ds\right) + \int_0^1 m(s) ds, \\ &\leq AB\left(\sum_{k=1}^{n-2} a_k\right) \left(\sum_{j=1}^{m-2} b_j\right) M + A\left(\sum_{k=1}^{n-2} a_k\right) M + B\left(\sum_{j=1}^{m-2} b_j\right) M + M \\ &= r, \end{aligned}$$

where r = (ABCD + AC + BD + 1)M, $C = \sum_{k=1}^{n-2} a_k$ and $D = \sum_{j=1}^{m-2} b_j$. Then $\{Hx(t)\}$ is uniformly bounded in Q_r . Also, for $t_1, t_2 \in [0,1]~$ such that $~t_1 < t_2$, we have

$$(Hx)(t_2) - (Hx)(t_1) = B(t_2 - t_1) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds \right) + \int_0^{t_2} (t_2 - s) f(s, x(s)) ds - \int_0^{t_1} (t_1 - s) f(s, x(s)) ds, = B(t_2 - t_1) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds \right) + \int_0^{t_1} (t_2 - t_1) f(s, x(s)) ds + \int_{t_1}^{t_2} (t_2 - s) f(s, x(s)) ds.$$

Then

$$\begin{aligned} |(Hx)(t_2) - (Hx)(t_1)| &\leq B|t_2 - t_1| \left(\sum_{j=1}^{m-2} b_j \int_0^1 m(s) ds \right) \\ &+ |t_2 - t_1| \int_0^1 m(s) ds + \int_{t_1}^{t_2} (t_2 - s) m(s) ds \\ &= BD|t_2 - t_1|M + |t_2 - t_1|M + \int_{t_1}^{t_2} (t_2 - s) m(s) ds. \end{aligned}$$

Therefore $\{Hx(t)\}\$ is equi-continuous. By Arzela-Ascolis Theorem $\{Hx(t)\}\$ is relatively compact.

Since all conditions of Schauder fixed point theorem are hold, then H has a fixed point in Q_r which proves that the existence of at least one solution $x \in C[0, 1]$ of the integral equation (9).

To complete the proof, we prove that the integral equation (9) satisfies the nonlocal problem (1)-(2).

Differentiating (9), we get

$$x'(t) = B\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) + \int_0^t f(s, x(s)) ds$$
(10)

and

$$x''(t) = f(t, x(t)).$$

Let $t = \tau_k$ in (9), we get

$$\begin{aligned} x(\tau_k) &= AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) \\ &+ B \tau_k \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ \int_0^t (\tau_k - s) f(s, x(s)) ds. \end{aligned}$$
$$\begin{aligned} \sum_{k=1}^{n-2} a_k x(\tau_k) &= AB\left(\sum_{k=1}^{n-2} a_k\right) \left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ A\left(\sum_{k=1}^{n-2} a_k\right) \left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) \\ &+ B\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \\ &+ \sum_{k=1}^{n-2} a_k \int_0^t (\tau_k - s) f(s, x(s)) ds. \end{aligned}$$

$$\sum_{k=1}^{n-2} a_k x(\tau_k) = AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) \left(\sum_{k=1}^{n-2} a_k + \frac{1}{A}\right) + A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right) \left(\sum_{k=1}^{n-2} a_k + \frac{1}{A}\right),$$

but
$$\left(\sum_{k=1}^{n-2} a_k + \frac{1}{A}\right) = 1$$
. Then

$$\sum_{k=1}^{n-2} a_k x(\tau_k) = AB\left(\sum_{k=1}^{n-2} a_k \tau_k\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right)$$

$$+ A\left(\sum_{k=1}^{n-2} a_k \int_0^{\tau_k} (\tau_k - s) f(s, x(s)) ds\right)$$

$$= x(0).$$

Let $t = \eta_j$ in (10), we obtain

$$x'(\eta_j) = B\left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right) + \int_0^{\eta_j} f(s, x(s)) ds$$

$$\sum_{j=1}^{m-2} b_j x'(\eta_j) = B\left(\sum_{j=1}^{m-2} b_j\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right)$$

+
$$\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds$$

=
$$B\left(\sum_{j=1}^{m-2} b_j + \frac{1}{B}\right) \left(\sum_{j=1}^{m-2} b_j \int_0^{\eta_j} f(s, x(s)) ds\right)$$

=
$$x'(0).$$

This completes the proof.

Corollary 1. The solution x(t) of the nonlocal problem (1)-(2) is positive and nondecreasing.

As a particular case of Theorem 1, we have the following corollary.

Corollary 2. The nonlocal problem

$$x''(t) = f(t, x(t)), \ t \in (0, 1)$$
 (11)

with the nonlocal condition

$$x(0) = \alpha x(b) , x'(0) = \beta x'(c)$$
 (12)

has at least one positive nondecreasing solution in the form

$$\begin{aligned} x(t) &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,x(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,x(s))ds \\ &+ \frac{\beta t}{(1-\beta)} \int_0^c f(s,x(s))ds + \int_0^t (t-s)f(s,x(s))ds. \end{aligned}$$
(13)

4. Maximal and minimal solutions

Definition.

let q(t) be a solution of (13). Then q is said to be a maximal solution of (13) if every solution x(t) of (13) satisfies the inequality x(t) < q(t).

A minimal solution s(t) can be defined by similar way by reversing the above inequality i.e. x(t) > s(t).

The following lemma will be used later.

Lemma 2.

Let x, y are continuous functions on [0, 1], satisfying

$$\begin{aligned} x(t) &\leq \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,x(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,x(s))ds \\ &+ \frac{\beta t}{(1-\beta)} \int_0^c f(s,x(s))ds + \int_0^t (t-s)f(s,x(s))ds, \end{aligned}$$

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$$y(t) \geq \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,y(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,y(s))ds \\ + \frac{\beta t}{(1-\beta)} \int_0^c f(s,y(s))ds + \int_0^t (t-s)f(s,y(s))ds$$

and one of them is strict. If f(t, x) is monotonic nondecreasing in x, then

$$x(t) < y(t), t > 0$$
 (14)

proof. Let the conclusion (14) be false, then there exists t_1 such that

$$x(t_1) = y(t_1), t_1 > 0$$

and

$$x(t) < y(t), \ 0 < t \le t_1.$$

From the monotonicity of f in x, we get

$$\begin{aligned} x(t_1) &\leq \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,x(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,x(s))ds \\ &+ \frac{\beta t_1}{(1-\beta)} \int_0^c f(s,x(s))ds + \int_0^{t_1} (t_1-s)f(s,x(s))ds \\ &< \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,y(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,y(s))ds \\ &+ \frac{\beta t_1}{(1-\beta)} \int_0^c f(s,y(s))ds + \int_0^{t_1} (t_1-s)f(s,y(s))ds \\ &< y(t_1), \end{aligned}$$

which contradicts the fact that $x(t_1) = y(t_1)$, then x(t) < y(t).

For the existence of the maximal and minimal solutions we have the following theorem,

Theorem 2.

Let the assumptions of Theorem 1 be satisfied. If f is a nondecreasing in x on [0, 1]. Then there exist maximal and minimal solutions of the integral equation (13).

proof. Firstly we shall prove the existence of the maximal solution of (13). Let $\epsilon > 0$ be given and consider the integral equation

$$x_{\epsilon}(t) = \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} f_{\epsilon}(s, x_{\epsilon}(s)) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s) f_{\epsilon}(s, x_{\epsilon}(s)) ds + \frac{\beta t}{(1-\beta)} \int_{0}^{c} f_{\epsilon}(s, x_{\epsilon}(s)) ds + \int_{0}^{t} (t-s) f_{\epsilon}(s, x_{\epsilon}(s)) ds, \ t \in [0,1]$$
(15)

where $f_{\epsilon}(t, x_{\epsilon}(t)) = f(t, x_{\epsilon}(t)) + \epsilon$.

Clearly the function $f_{\epsilon}(t, x_{\epsilon}(t))$ satisfies assumptions (i)-(ii) of Theorem 1 and therefore equation (15) has at least a positive solution $x_{\epsilon}(t) \in C[0, 1]$.

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let ϵ_1 and ϵ_2 be such that $0 < \epsilon_2 < \epsilon_1 \le \epsilon$. Then

$$\begin{aligned} x_{\epsilon_{2}}(t) &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} f_{\epsilon_{2}}(s, x_{\epsilon_{2}}(s)) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s) f_{\epsilon_{2}}(s, x_{\epsilon_{2}}(s)) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_{0}^{c} f_{\epsilon_{2}}(s, x_{\epsilon_{2}}(s)) ds + \int_{0}^{t} (t-s) f_{\epsilon_{2}}(s, x_{\epsilon_{2}}(s)) ds \\ &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon_{2}}(s)) + \epsilon_{2}) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s)(f(s, x_{\epsilon_{2}}(s)) + \epsilon_{2}) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon_{2}}(s)) + \epsilon_{2}) ds + \int_{0}^{t} (t-s)(f(s, x_{\epsilon_{2}}(s)) + \epsilon_{2}) ds, \end{aligned}$$
(16)

$$\begin{aligned} x_{\epsilon_1}(t) &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c (f(s, x_{\epsilon_1}(s)) + \epsilon_1) ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)(f(s, x_{\epsilon_1}(s)) + \epsilon_1) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_0^c (f(s, x_{\epsilon_1}(s)) + \epsilon_1) ds + \int_0^t (t-s)(f(s, x_{\epsilon_1}(s)) + \epsilon_1) ds, \end{aligned}$$

$$x_{\epsilon_{1}}(t) > \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon_{1}}(s)) + \epsilon_{2}) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s)(f(s, x_{\epsilon_{1}}(s)) + \epsilon_{2}) ds + \frac{\beta t}{(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon_{1}}(s)) + \epsilon_{2}) ds + \int_{0}^{t} (t-s)(f(s, x_{\epsilon_{1}}(s)) + \epsilon_{2}) ds.$$
(17)

Applying Lemma 2 on (16) and (17), we have

$$x_{\epsilon_2}(t) < x_{\epsilon_1}(t) \text{ for } t \in [0,1].$$

As shown before the family of functions $x_{\epsilon}(t)$ is equi-continuous and uniformly bounded. Hence by Arzela-Ascolis Theorem, there exists a decreasing sequence ϵ_n such that $\epsilon_n \to 0$ as $n \to \infty$, and $\lim_{n\to\infty} x_{\epsilon_n}(t)$ exists uniformly in [0, 1]. Denote this limit by q, then from the continuity of the function $f_{\epsilon}(t, x_{\epsilon})$ in the second argument, we get

$$q(t) = \lim_{n \to \infty} x_{\epsilon_n}(t) = \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,q(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,q(s))ds + \frac{\beta t}{(1-\beta)} \int_0^c f(s,q(s))ds + \int_0^t (t-s)f(s,q(s))ds,$$
(18)

which implies that q is a solution of (13).

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Finally, we shall show that q is the maximal solution of (13). To do that, let x_{ϵ} be any solution of (13). Then

$$\begin{aligned} x_{\epsilon}(t) &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} f_{\epsilon}(s, x_{\epsilon}(s)) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s) f_{\epsilon}(s, x_{\epsilon}(s)) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_{0}^{c} f_{\epsilon}(s, x_{\epsilon}(s)) ds + \int_{0}^{t} (t-s) f_{\epsilon}(s, x_{\epsilon}(s)) ds \\ &= \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon}(s)) + \epsilon) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s) (f(s, x_{\epsilon}(s)) + \epsilon) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_{0}^{c} (f(s, x_{\epsilon}(s)) + \epsilon) ds + \int_{0}^{t} (t-s) (f(s, x_{\epsilon}(s)) + \epsilon) ds \\ &> \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_{0}^{c} f(s, x_{\epsilon}(s)) ds + \frac{\alpha}{(1-\alpha)} \int_{0}^{b} (b-s) f(s, x_{\epsilon}(s)) ds \\ &+ \frac{\beta t}{(1-\beta)} \int_{0}^{c} f(s, x_{\epsilon}(s)) ds + \int_{0}^{t} (t-s) f(s, x_{\epsilon}(s)) ds. \end{aligned}$$
(19)

And for any solution x(t) of (13), we have

$$x(t) = \frac{\alpha \beta b}{(1-\alpha)(1-\beta)} \int_0^c f(s,x(s))ds + \frac{\alpha}{(1-\alpha)} \int_0^b (b-s)f(s,x(s))ds + \frac{\beta t}{(1-\beta)} \int_0^c f(s,x(s))ds + \int_0^t (t-s)f(s,x(s))ds.$$
(20)

Applying Lemma 2, we get

$$x(t) < x_{\epsilon}(t) \text{ for } t \in [0, 1],$$

from the uniqueness of the maximal solution, it is clear that $x_{\epsilon}(t)$ tends to q(t) uniformly in $t \in [0, 1]$ as $\epsilon_n \to 0$.

By similar way as done above we can prove the existence of the minimal solution of (13).

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