

VOLTERRA-STIELTJES INTEGRAL EQUATION IN REFLEXIVE BANACH SPACES

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ABSTRACT. Volterra-Stieltjes integral equations have been studied in the space of continuous functions in many papers for example, (see [3]-[7]). Our aim here is to studying the existence of weak solutions to a nonlinear integral equation of Volterra-Stieltjes type in a reflexive Banach space. A special case will be considered.

1. INTRODUCTION AND PRELIMINARIES

Let E be a reflexive Banach space with norm $\| \cdot \|$ and dual E^* . Denote by $C[I, E]$ the Banach space of strongly continuous functions $x : I \rightarrow E$ with sup-norm.

Consider the nonlinear Riemann-Stieltjes integral equation

$$x(t) = p(t) + \int_0^t f(s, x(s)) d_s g(t, s), \quad t \in I = [0, T], \quad (1)$$

This type of equations have been studied by Banaś (see [1]-[6]) and also by some other authors, for example (see [7], [9] and [15]-[17]).

Here, we study the existence of a weak solution $x \in C[I, E]$ in the reflexive Banach space E for the nonlinear Volterra-Stieltjes integral equation (1) where f is assumed to be weakly-weakly continuous.

For the properties of the Stieltjes integral (see Banaś [1]).

Now, we shall present some auxiliary results that will be need in this work. Let E be a Banach space (need not be reflexive) and let $x : [a, b] \rightarrow E$, then

- (1-) $x(\cdot)$ is said to be weakly continuous (measurable) at $t_0 \in [a, b]$ if for every $\phi \in E^*$, $\phi(x(\cdot))$ is continuous (measurable) at t_0 .
- (2-) A function $h : E \rightarrow E$ is said to be weakly sequentially continuous if h maps weakly convergent sequences in E to weakly convergent sequences in E .

If x is weakly continuous on I , then x is strongly measurable and hence weakly measurable (see [14] and [11]). It is evident that in reflexive Banach spaces, if x is

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weakly continuous function on $[a, b]$, then x is weakly Riemann integrable (see [14]). Since the space of all weakly Riemann-Stieltjes integrable functions is not complete, we will restrict our attention to the existence of weak solutions of equation (1) in the space $C[I, E]$.

Definition 1.

Let $f : I \times E \rightarrow E$. Then $f(t, u)$ is said to be weakly-weakly continuous at (t_0, u_0) if given $\epsilon > 0$, $\phi \in E^*$ there exists $\delta > 0$ and a weakly open set U containing u_0 such that

$$|\phi(f(t, u) - f(t_0, u_0))| < \epsilon$$

whenever

$$|t - t_0| < \delta \text{ and } u \in U.$$

Now, we have the following fixed point theorem, due to O'Regan, in the reflexive Banach space (see [18]) and some propositions which will be used in the sequel (see [12]).

Theorem 1. *Let E be a Banach space and let Q be a nonempty, bounded, closed and convex subset of $C[I, E]$ and let $F : Q \rightarrow Q$ be a weakly sequentially continuous and assume that $FQ(t)$ is relatively weakly compact in E for each $t \in I$. Then, F has a fixed point in the set Q .*

Proposition 1. *A convex subset of a normed space E is closed if and only if it is weakly closed.*

Proposition 2. *A subset of a reflexive Banach space is weakly compact if and only if it is closed in the weak topology and bounded in the norm topology.*

Proposition 3. *Let E be a normed space with $y \in E$ and $y \neq 0$. Then there exists a $\phi \in E^*$ with $\|\phi\| = 1$ and $\|y\| = \phi(y)$.*

2. SOLVABILITY OF VOLTERRA-STIELTJES OPERATOR

In this section we discuss the existence of weak solutions of the equation (1) in the reflexive Banach space E .

Let $f : I \times E \rightarrow E$, $g : I \times I \rightarrow R$ be functions such that:

- (i) $p \in C[I, E]$.
- (ii) $f : I \times E \rightarrow E$ is weakly-weakly continuous function.
- (iii) There exists a constant M such that $\|f(t, x)\| \leq M$.
- (iv) The functions $t \rightarrow g(t, t)$ and $t \rightarrow g(t, 0)$ are continuous on I .
- (v) For all $t_1, t_2 \in I$ such that $t_1 < t_2$ the function $s \rightarrow g(t_2, s) - g(t_1, s)$ is nondecreasing on I .
- (vi) $g(0, s) = 0$ for any $s \in I$.

Remark 1. *Observe that Assumptions (v) and (vi) imply that the function $s \rightarrow g(t, s)$ is nondecreasing on the interval I , for any fixed $t \in I$ (Remark 1 in [6]). Indeed, putting $t_2 = t$, $t_1 = 0$ in (v) and keeping in mind (vi), we obtain the desired conclusion. From this observation, it follows immediately that, for every $t \in I$, the function $s \rightarrow g(t, s)$ is of bounded variation on I .*

Definition 2. *By a weak solution to (1) we mean a function $x \in C[I, E]$ which satisfies the integral equation (1). This is equivalent to finding $x \in C[I, E]$ with*

$$\phi(x(t)) = \phi(p(t) + \int_0^t f(s, x(s)) d_s g(t, s)), \quad t \in I \quad \forall \phi \in E^*.$$

Now we can prove the following theorem.

Theorem 2. *Under the assumptions (i)-(vi), the Volterra-Stieltjes integral equation (1) has at least one weak solution $x \in C[I, E]$.*

Proof. Define the nonlinear Volterra-Stieltjes integral operator A by

$$Ax(t) = p(t) + \int_0^t f(s, x(s)) d_s g(t, s), \quad t \in I.$$

For every $x \in C[I, E]$, $f(\cdot, x(\cdot))$ is weakly continuous ([19]). To see this we equip E and $I \times E$ with weak topology and note that $t \mapsto (t, x(t))$ is continuous as a mapping from I into $I \times E$, then $f(\cdot, x(\cdot))$ is a composition of this mapping with f and thus for each weakly continuous $x : I \rightarrow E$, $f(\cdot, x(\cdot)) : I \rightarrow E$ is weakly continuous, means that $\phi(f(\cdot, x(\cdot)))$ is continuous, for every $\phi \in E^*$, g is of bounded variation. Hence $f(\cdot, x(\cdot))$ is weakly Riemann-Stieltjes integrable on I with respect to $s \rightarrow g(t, s)$. Thus A makes sense.

Now, define the set Q by

$$Q = \{x \in C[I, E] : \|x\|_0 \leq M_0, \|x(t_2) - x(t_1)\| \leq \|p(t_2) - p(t_1)\| + M[|g(t_2, t_2) - g(t_1, t_1)| + |g(t_2, 0) - g(t_1, 0)|], \text{ for all } t_1, t_2 \in I\}.$$

For notational purposes $\|x\|_0 = \sup_{t \in I} \|x(t)\|$.

The remainder of the proof will be given in four steps.

Step 1 : The operator A maps $C[I, E]$ into $C[I, E]$.

Let $t_1, t_2 \in I$, $t_2 > t_1$, without loss of generality, assume $Ax(t_2) - Ax(t_1) \neq 0$

$$\begin{aligned} \|Ax(t_2) - Ax(t_1)\| &\leq |\phi(p(t_2) - p(t_1))| \\ &+ \left| \int_0^{t_2} \phi(f(s, x(s))) d_s g(t_2, s) - \int_0^{t_1} \phi(f(s, x(s))) d_s g(t_1, s) \right| \\ &\leq \|p(t_2) - p(t_1)\| + \left| \int_0^{t_1} \phi(f(s, x(s))) d_s g(t_2, s) \right| \\ &+ \left| \int_{t_1}^{t_2} \phi(f(s, x(s))) d_s g(t_2, s) - \int_0^{t_1} \phi(f(s, x(s))) d_s g(t_1, s) \right| \\ &\leq \|p(t_2) - p(t_1)\| + \left| \int_0^{t_1} \phi(f(s, x(s))) d_s [g(t_2, s) - g(t_1, s)] \right| \\ &+ \left| \int_{t_1}^{t_2} \phi(f(s, x(s))) d_s g(t_2, s) \right| \\ &\leq \|p(t_2) - p(t_1)\| + \int_0^{t_1} |\phi(f(s, x(s)))| d_s \left[\bigvee_{z=0}^s (g(t_2, z) - g(t_1, z)) \right] \\ &+ \int_{t_1}^{t_2} |\phi(f(s, x(s)))| d_s \left[\bigvee_{z=0}^s g(t_2, z) \right] \\ &\leq \|p(t_2) - p(t_1)\| + \int_0^{t_1} |\phi(f(s, x(s)))| d_s [g(t_2, s) - g(t_1, s)] \end{aligned}$$

$$\begin{aligned}
& + \int_{t_1}^{t_2} |\phi(f(s, x(s)))| d_s g(t_2, s) \\
& \leq \|p(t_2) - p(t_1)\| + M \int_0^{t_1} d_s [g(t_2, s) - g(t_1, s)] + M \int_{t_1}^{t_2} d_s g(t_2, s) \\
& \leq \|p(t_2) - p(t_1)\| + M \left\{ \int_0^{t_1} d_s [g(t_2, s) - g(t_1, s)] + \int_{t_1}^{t_2} d_s g(t_2, s) \right\} \\
& \leq \|p(t_2) - p(t_1)\| + \\
& + M \{ [g(t_2, t_1) - g(t_1, t_1)] - [g(t_2, 0) - g(t_1, 0)] + [g(t_2, t_2) - g(t_2, t_1)] \} \\
& \leq \|p(t_2) - p(t_1)\| + \\
& + M \{ g(t_2, t_1) - g(t_1, t_1) - g(t_2, 0) + g(t_1, 0) + g(t_2, t_2) - g(t_2, t_1) \} \\
& \leq \|p(t_2) - p(t_1)\| + M \{ [g(t_2, t_2) - g(t_1, t_1)] - [g(t_2, 0) - g(t_1, 0)] \} \\
& \leq \|p(t_2) - p(t_1)\| + M \{ |g(t_2, t_2) - g(t_1, t_1)| + |g(t_2, 0) - g(t_1, 0)| \}.
\end{aligned}$$

Hence

$$\|Ax(t_2) - Ax(t_1)\| \leq \|p(t_2) - p(t_1)\| + M \{ |g(t_2, t_2) - g(t_1, t_1)| + |g(t_2, 0) - g(t_1, 0)| \}, \quad (2)$$

and so $Ax \in C[I, E]$.

Step 2 : The operator A maps Q into Q .

Take $x \in Q$, note that the inequality (2) shows that AQ is norm continuous. Then by using Proposition 3 we get

$$\begin{aligned}
\|Ax(t)\| & = \phi(Ax(t)) \leq |\phi(p(t))| + \left| \phi \left(\int_0^t f(s, x(s)) d_s g(t, s) \right) \right| \\
& \leq \|p\|_0 + \int_0^t |\phi(f(s, x(s)))| d_s \left(\bigvee_{z=0}^s g(t, z) \right) \\
& \leq \|p\|_0 + M \int_0^t d_s \left(\bigvee_{z=0}^s g(t, z) \right) \\
& \leq \|p\|_0 + M \int_0^t d_s g(t, s) \\
& \leq \|p\|_0 + M [g(t, t) - g(t, 0)] \\
& \leq \|p\|_0 + M [|g(t, t)| + |g(t, 0)|] \\
& \leq \|p\|_0 + M \left[\sup_{t \in I} |g(t, t)| + \sup_{t \in I} |g(t, 0)| \right] \\
& \leq \|p\|_0 + M [k_1 + k_2] = M_0,
\end{aligned}$$

where $k_1 = \sup_{t \in I} |g(t, t)|$; $k_2 = \sup_{t \in I} |g(t, 0)|$.

Then

$$\|Ax\|_0 = \sup_{t \in I} \|Ax(t)\| \leq M_0.$$

Hence, $Ax \in Q$ and $AQ \subset Q$ which prove that $A : Q \rightarrow Q$, and AQ is bounded in $C[I, E]$.

Step 3 : $AQ(t)$ is relatively weakly compact in E .

Note that Q is nonempty, closed, convex and uniformly bounded subset of $C[I, E]$ and AQ is bounded in norm. According to propositions 1 and 2, AQ is relatively weakly compact in $C[I, E]$ implies $AQ(t)$ is relatively weakly compact in E , for each $t \in I$.

Step 4 : The operator A is weakly sequentially continuous.

Let $\{x_n(t)\}$ be sequence in Q weakly convergent to $x(t)$ in E , since Q is closed we have $x \in Q$. Fix $t \in I$, since f satisfies (ii), then we have $f(t, x_n(t))$ converges weakly to $f(t, x(t))$. By the Lebesgue dominated convergence theorem (see assumption (iii)) for Pettis integral ([13]), we have for each $\phi \in E^*$. $s \in I$

$$\begin{aligned} \phi\left(\int_0^t f(s, x_n(s)) d_s h(t, s)\right) &= \int_0^t \phi(f(s, x_n(s))) d_s g(t, s) \\ &\rightarrow \int_0^t \phi(f(s, x(s))) d_s g(t, s), \quad \forall \phi \in E^*, t \in I. \end{aligned}$$

i.e. $\phi(Ax_n(t)) \rightarrow \phi(Ax(t))$, $\forall t \in I$, $Ax_n(t)$ converging weakly to $Ax(t)$ in E . Thus, A is weakly sequentially continuous on Q .

Since all conditions of Theorem 1 are satisfied, then the operator A has at least one fixed point $x \in Q$ and the nonlinear Stieltjes integral equation (1) has at least one weak solution. ■

Corollary 1. Under the assumptions of Theorem 2 (with $g(t, s) = g(s)$), the Volterra-Stieltjes integral equation

$$x(t) = p(t) + \int_0^t f(s, x(s)) dg(s),$$

has a weak solution $x \in C[I, E]$.

Now, let $r > 0$ be given and define the set

$$B_r = \{x \in C[I, E], x(t) \in E : \|x\|_0 \leq r\}.$$

Lemma 1.

Let $f : I \times B_r \rightarrow E$ be weakly-weakly continuous, then

- For each $t \in I$, $f(t, \cdot)$ is weakly continuous, hence weakly sequentially continuous (see [8]),
- For each weakly continuous $x : I \rightarrow B_r$, $f(\cdot, x(\cdot))$ is weakly continuous on I (see [21]),
- f is norm bounded, i.e., there exists an M_r such that $\|f(t, x)\| \leq M_r$ for all $(t, x) \in I \times B_r$ (see [20]).

Now we have the following Theorem.

Theorem 3. Under the assumptions (i) and (iv)-(vi), if $f : I \times B_r \rightarrow E$ is weakly-weakly continuous and $M_r < r$, where M_r is defined as in Lemma 1, then the Volterra-Stieltjes integral equation (1) has at least one weak solution $x \in C[I, E]$.

Proof. Define the nonlinear Volterra-Stieltjes integral operator A by

$$Ax(t) = p(t) + \int_0^t f(s, x(s)) d_s g(t, s), \quad t \in I.$$

For any $x \in C[I, E]$, we have $f(\cdot, x(\cdot))$ is weakly continuous on I (Lemma 1), then $\phi(f(\cdot, x(\cdot)))$ is continuous on I for every $\phi \in E^*$ and hence $\phi(f(\cdot, x(\cdot)))$ is Riemann-Stieltjes integrable on I with respect to $s \rightarrow g(t, s)$. Thus A makes sense.

Now, define the set Q by

$$Q = \{x \in B_r, \|x(t_2) - x(t_1)\| \leq \|p(t_2) - p(t_1)\| + \\ + M_r \{|g(t_2, t_2) - g(t_1, t_1)| + |g(t_2, 0) - g(t_1, 0)|\}, \text{ for all } t_1, t_2 \in I\}.$$

For notational purposes $\|x\|_0 = \sup_{t \in I} \|x(t)\|$.

The rest of proof runs as in proof of Theorem 2.

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