

ON THE EXPONENTIAL STUDY OF SOLUTIONS OF VOLTERRA INTEGRO-DIFFERENTIAL EQUATIONS WITH TIME LAG

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ABSTRACT. We are concerned with three nonlinear Volterra integro-differential equations (NVIDEs) with constant time lag. The variational of parameters inequalities, that is, the boundedness of the solutions, to that (NVIDEs) is investigated by the Lyapunov functionals (LFs). The results obtained here improve and complement a sample of works found in the literature. In fact, the novelty and originality of this article are that it improves and extends earlier results from very simple cases without time lag to the more general and non-linear cases with time lag.

1. INTRODUCTION

Mathematical models by functional differential equations (FDEs), (VIDEs), Volterra integral equations (VIEs), integral equations (IEs) and integro-differential equations (IDEs) have attracted the attention of scientists due to their useful applications to day life problems in various scientific fields like sciences, engineering and many other areas (see Burton [6], Burton and Mahfoud [10], Corduneanu [13], Gripenberg et al. [26], Lakshmikantham and Rama Mohan Rao [38], Peschel and Mende [48], Staffans [59], Wazwaz [76]). Therefore, due to this reality, qualitative properties of solutions of various models of the mentioned equations have been widely investigated by different authors (Adivar and Raffoul [1], Becker ([2], [3], [4]), Burton ([5], [7]), Burton and Haddock [8], Burton and Mahfoud ([9], [11]), Chang and Wang [12], Diamandescu [14], Dung ([15], [16]), Eloe et al. [17], Engler [18], Funakubo et al. [19], Furumochi and Matsuoka [20], Grace and Akin [21], Graef and Tunç [22], Graef et al. [23], Grimmer and Seifert [24], Grimmer and Zeman [25], Grossman and Miller [27], Hara et al. ([28],[29],[30]), Hino and Murakami [31], Islam [32], Islam and Al-Eid [33], Islam and Raffoul ([34], [35]), Jin and Luo [36], Lakshmikantham and Rama Mohan Rao [37], Mahfoud ([39],[40],[41]), Mesmouli et al. [42], Martinez [43], Miller [44], Murakami [45], Ngoc [46], Napoles Valdes [47], Raffoul ([49],[50], [51],[52]), Raffoul and Rai [53], Raffoul and Ren [54], Raffoul and Sanbo

2010 *Mathematics Subject Classification.* 34D05, 34K20, 45J05.

Key words and phrases. Variational of parameters inequality, (NVIDE), first order, (LF)..

Submitted March 19, 2016.

[55], Raffoul and nal [56], Rama Mohana Rao and Raghavendra [57], Rama Mohana Rao and Srinivas [59], Talpalaru [60], Tunç ([61], [62], [63], [64], [65]), Tunç and Ayhan [66], Tunç and Mohammed ([67], [68]), Vanualailai [69], Vanualailai and Nakagiri ([70], [71]), Wang ([72], [73], [74]), Wang et al. [75], Zhang [77], Da Zhang [78]). As distinguished line from these facts, the following article is notable: In 2009, Raffoul [51] considered the (FDE)

$$\frac{dx}{dt}\Phi(t, x(s); 0 \leq s \leq t) := \Phi(t, x(.)), \quad (1)$$

in which x is an n -dimensional vector, Φ is given a continuous function in t and $x(.)$ such that $\Phi(t, 0) = 0$.

A stereotype of (FDE) (1) is the (VIDE) given by

$$\frac{dx}{dt} = h(x) + \int_0^t B(t, s)f(x(s))ds + g(t).$$

Let $t_0 \geq 0$. Then, for each continuous function $\phi : [0, t_0] \rightarrow \mathfrak{R}^n$, at least, there exists a continuous function $x(t) = x(t, t_0, \phi)$ on $[t_0, I]$, which is a solution of (FDE) (1) for $0 \leq t_0 \leq t \leq I$ so that $x(t, t_0, \phi) = \phi$ for $0 \leq t \leq t_0$ (see Raffoul [51]). In [51], Raffoul investigated sufficient conditions to guarantee that all solutions of (FDE) (1) satisfy specific variational of parameters inequalities by means of (LFs), and the author gave examples for illustrations. Indeed, Raffoul [51] considered the below (VIDEs) to show applicability of the obtained results:

$$\frac{dx}{dt} = \sigma(t)x + \int_0^t B(t, s)x(s)ds + g(t), \quad (2)$$

$$\frac{dx}{dt} = \sigma(t)x + \int_0^t B(t, s)x^{\frac{2}{3}}(s)ds + g(t) \quad (3)$$

and

$$\frac{dx}{dt} = \sigma(t)x^3 + \int_0^t B(t, s)x^{\frac{1}{3}}(s)ds + g(t). \quad (4)$$

Motivated by the results of Raffoul [51], which are related to (VIDEs) (2)-(4), in this paper, we consider the following (NVIDEs) with constant time lag:

$$\frac{dx}{dt} = -f(t, x) + \int_{t-\tau}^t H(t, s)K(x(s))ds + F(t), \quad (5)$$

$$\frac{dx}{dt} = -p(t, x) + \int_{t-\tau}^t H(t, s)q^{\frac{2}{3}}(x(s))ds + F(t) \quad (6)$$

and

$$\frac{dx}{dt} = -r^3(t, x) + \int_{t-\tau}^t H(t, s)h^{\frac{1}{3}}(x(s))ds + F(t), \quad (7)$$

respectively, where $x(t) = \phi(t)$, $0 \leq t \leq t_0$, and $\phi(t)$ is a given bounded continuous initial function, $t - \tau \geq 0$, $\tau \in \mathfrak{R}$, $\tau > 0$, fixed constant time lag, $x \in \mathfrak{R}$, $F : \mathfrak{R}^+ \rightarrow \mathfrak{R}$, $\mathfrak{R}^+ = [0, \infty)$, and $f, p, r : \mathfrak{R}^+ \times \mathfrak{R} \rightarrow \mathfrak{R}$ are continuous functions with $f(t, 0) = p(t, 0) = r(t, 0) = 0$, $K, q, h : \mathfrak{R} \rightarrow \mathfrak{R}$ are continuous functions with $K(0) = q(0) = h(0) = 0$, and $H(t, s)$ is a continuous function for $0 \leq s \leq t < \infty$. It is also assumed that the derivatives $\frac{\partial}{\partial x}f(t, x) = f_x(t, x)$, $\frac{\partial}{\partial x}p(t, x) = p_x(t, x)$ and $\frac{\partial}{\partial x}r(t, x) = r_x(t, x)$ exist and are continuous for all (t, x) .

Let us define

$$f_1(t, x) = \begin{cases} \frac{f(t, x)}{x}, & x \neq 0 \\ f_x(t, 0), & x = 0 \end{cases}$$

$$p_1(t, x) = \begin{cases} \frac{p(t, x)}{x}, & x \neq 0 \\ p_x(t, 0), & x = 0 \end{cases}$$

$$r_1(t, x) = \begin{cases} \frac{r(t, x)}{x}, & x \neq 0 \\ r_x(t, 0), & x = 0. \end{cases}$$

Hence, we can write from (NVIDEs) (5)-(7) that

$$x'(t) = f_1(t, x)x + \int_{t-\tau}^t H(t, s)K(x(s))ds + F(t), \quad (8)$$

$$x'(t) = -p_1(t, x)x + \int_{t-\tau}^t H(t, s)q^{\frac{2}{3}}(x(s))ds + F(t) \quad (9)$$

and

$$x'(t) = -r_1^3(t, x)x^3 + \int_{t-\tau}^t H(t, s)h^{\frac{1}{3}}(x(s))ds + F(t), \quad (10)$$

respectively.

It is notable from the given information that Raffoul [51] considered one linear and two non-linear (VIDEs) without time lag. However, we pay attention to certain three new (NVIDEs) with constant time lag. In fact, when we choose $f(t, x) = -\sigma(t)x$, $K(x) = x$, $F(t) = g(t)$; $p(t, x) = -\sigma(t)x$, $q^{\frac{2}{3}}(x) = x^{\frac{2}{3}}$, $F(t) = g(t)$, and $r(t, x) = -\sigma^{\frac{1}{3}}(t)x$, $h^{\frac{1}{3}}(x) = x^{\frac{1}{3}}$, $F(t) = g(t)$, respectively, and put zero "0" instead of the term $t - \tau$, then (NVIDEs) (5)-(7) reduce to (VIDE) (2)-(4) investigated by Raffoul [51]. That is, (NVIDEs) (5)-(7) include and extend (VIDEs) (2)-(4) studied by Raffoul [51].

The purpose of this paper is to establish new sufficient conditions to guarantee some new variational of parameters inequalities so that the solutions (NVIDEs) (5)-(7) are bounded. By this way, we would like to do a contribution to the subject and the related literature.

Let $\varphi : [0, t_0] \rightarrow \mathfrak{R}^n$ be a continuous function and define $|\varphi| = \sup\{\|\varphi(s)\| : 0 \leq s \leq t_0\}$.

Definition ([51]). The solutions of (FDE) (1) are said bounded if any solution $x(t, t_0, \varphi)$ of equation (1) fulfills

$$\|x(t, t_0, \eta)\| \leq C(\|\eta\|, t_0), t \geq t_0, \quad (11)$$

where $C : \mathfrak{R}^+ \times \mathfrak{R}^+ \rightarrow \mathfrak{R}^+$, $\mathfrak{R}^+ = [0, \infty)$, C is here two-parameters a positive function, which depends on φ and t_0 , and φ is a given bounded and continuous initial function.

If the C in inequality (11) is independent of t_0 , then it is said that the solutions of (FDE) (1) are uniformly bounded.

Throughout this paper, the below basic theorem is needed for our results, and when we need x represents $x(t)$.

Theorem A ([51]). Assume that $D \subset \mathfrak{R}^n$ contains the origin and there exists a continuously differentiable (LF) $W : [0, \infty) \times D \rightarrow [0, \infty)$ such that the below assumptions hold for all $(t, x) \in [0, \infty) \times D$:

$$(A1) \quad W_1(\|x\|) \leq W(t, x) \leq W_2(\|x\|) + \int_0^t \phi_1(t, s)W_3(|x(s)|)ds,$$

$$(A2) \quad \dot{W}(t, x(\cdot)) \leq -\alpha_1(t)W_4(\|x\|) - \alpha_2(t) \int_0^t \phi_2(t, s)W_5(|x(s)|)ds + F(t)$$

for positive and continuous functions $\alpha_1(t)$, $\alpha_2(t)$ and $F(t)$, where $\phi_1(t, s) \geq 0$ and $\phi_2(t, s) \geq 0$ are scalar valued and continuous functions for $0 \leq s \leq t < \infty$. If the condition

$$(A3) \quad W_2(\|x\|) - W_4(\|x\|) + \int_0^t [\phi_1(t, s)W_3|x(s)| - \phi_2(t, s)W_5|x(s)]ds \leq \gamma$$

holds for some constant $\gamma \geq 0$, then all solutions of (FDE) (1) that start in D satisfy the variational of parameters inequality

$$\|x\| \leq W_1^{-1}\{W(t_0, \|\phi\|) \exp(-\int_{t_0}^t \alpha(s)ds) + \int_{t_0}^t [(\gamma\alpha(u)+F(u)) \exp(-\int_u^t \alpha(s)ds)]du\}$$

for all $t \geq t_0$, where $\alpha(t) = \max\{\alpha_1(t), \alpha_2(t)\}$.

Proof. See Raffoul [51].

2. BOUNDEDNESS OF SOLUTIONS

We introduce some assumptions for (VIDE) (5).

A. Assumptions

Let the below assumptions be true.

(C1) $f(t, 0) = H(0) = 0, f_1(t, x) \geq f_0(t)$ for $t \in \mathbb{R}^+, x \in \mathbb{R}$,

(C2) $\omega(t) = 2f_0(t) - \int_{t-\tau}^t K_0|H(t, s)|ds - \sigma \int_{t-\tau}^\infty K_0|H(u + \tau, t)|du - 1 > 0$,

in which the function f_0 is positive, bounded and continuous,

(C3) $(\sigma - 1)|H(t, s)| \geq \sigma \int_{t-\tau}^\infty |H(u, s)|du, \int_{t-\tau}^t |H(t, s)|ds < \infty$
and $\int_{t-\tau}^\infty |H(u + \tau, t)|du < \infty$

with $0 \leq s \leq t \leq u < \infty$.

The first outcome of the current work is given below.

Theorem 1. If assumptions (C1)-(C3) hold, then all solutions $x(t)$ of (NVIDE) (5) start in D satisfy the variational of parameters inequality

$$|x| \leq \{\Omega_1(t_0, \|\phi\|) \exp(-\int_{t_0}^t \omega(s)ds) + \int_{t_0}^t [(\gamma\alpha(u) + G(u)) \exp(-\int_u^t \omega(s)ds)]du\} \tag{12}$$

with

$$\omega(t) = \max\{2f_0(t) - \int_{t-\tau}^t K_0|H(t, s)|ds - \sigma \int_{t-\tau}^\infty K_0|H(u + \tau, t)|du - 1, 1\}$$

$\gamma = 0, G(t) = F^2(t)$, and

$$\Omega_1(t_0, \phi) = \phi^2 + \sigma \int_0^{t_0} \int_{t_0-\tau}^\infty K_0|H(u + \tau, s)|du\phi^2(s)ds.$$

Proof. Define a (LF) $\Omega_1 = \Omega_1(t, x(t))$ by

$$\Omega_1 = x^2 + \sigma \int_0^t \int_{t-\tau}^\infty K_0|H(u + \tau, s)|dux^2(s)ds, \tag{13}$$

where $\sigma, K_0 \in \mathbb{R}, K_0 > 0, \sigma > 0$, we fix the constant σ in the proof later.

It can easily be seen from (13) that Ω_1 is positive definite, since

$$\Omega_1(t, 0) = 0 \text{ and } \Omega_1(t, x) \geq x^2.$$

By a clear calculation from (13) and (NVIDEs) (5) and (8), we obtain

$$\begin{aligned}\Omega'_1 &= 2xx' + \sigma x^2 \int_{t-\tau}^{\infty} K_0 |H(u + \tau, t)| du - \sigma \int_0^t K_0 |H(t, s)| x^2(s) ds \\ &= -2f_1(t, x)x^2 + 2x \int_{t-\tau}^t H(t, s)K(x(s))ds + 2xF(t) \\ &\quad + \sigma x^2 \int_{t-\tau}^{\infty} K_0 |H(u + \tau, t)| du - \sigma \int_{t-\tau}^{\infty} K_0 |H(t, s)| x^2(s) ds.\end{aligned}$$

By an elementary inequality together with the assumption $f_1(t, x) \geq f_0(t)$, it can be enable that

$$\begin{aligned}\Omega'_1 &\leq -2f_0(t)x^2 + 2|x| \int_{t-\tau}^t K_0 |H(t, s)| |x(s)| ds \\ &\quad + \sigma x^2 \int_{t-\tau}^{\infty} K_0 |H(u + \tau, t)| du - \sigma \int_{t-\tau}^{\infty} K_0 |H(t, s)| x^2(s) ds \\ &\quad + 2|x||F(t)| \\ &\leq -[2f_0(t) - \int_{t-\tau}^t K_0 |H(t, s)| ds - \sigma \int_{t-\tau}^{\infty} K_0 |H(u + \tau, t)| du - 1]x^2 \\ &\quad + (1 - \sigma)K_0 \int_{t-\tau}^t H(t, s)x^2(s) ds + F^2(t).\end{aligned}$$

Let $G(t) = F^2(t)$ and $\sigma > 1$. Then

$$\Omega'_1 \leq -\omega(t)x^2 - (\sigma - 1)K_0 \int_{t-\tau}^t H(t, s)x^2(s) ds + G(t)$$

by assumption (C2)

Let us take that

$$\begin{aligned}\alpha_1(t) &= \omega(t), \alpha_2(t) = 1, \\ W_1(\cdot) &= W_2(\cdot) = W_4(\cdot) = x^2(t), \\ W_3(\cdot) &= W_5(\cdot) = x^2(s), \\ \phi_1(t, s) &= \sigma \int_{t-\tau}^{\infty} |H(u + \tau, s)| du\end{aligned}$$

and

$$\phi_2(t, s) = (\sigma - 1)K_0 H(t, s).$$

Then we can conclude that all assumptions (A1)-(A3) of Theorem A hold. Hence, one can show that all solutions $x(t)$ of (VIDE) (5) satisfy relation (12).

B. Assumpitons

Let α_1 be a positive constant such that the following assumptions hold.

$$\text{(D1)} \quad p(t, 0) = q(0) = 0, p_1(t, x) \geq \alpha(t), t \in \mathbb{R}^+, x \in \mathbb{R}, |q(x)| \leq \alpha_1^{\frac{1}{2}} |x|, \\ 0 < \alpha_1 < 1,$$

$$\text{(D2)} \quad 2\alpha(t) - \int_{t-\tau}^t |H(t, s)| ds - \int_{t-\tau}^{\infty} |H(u + t, s)| du - 1 > 0,$$

in which the function α is positive, bounded and continuous,

$$\text{(D3)} \quad \int_{t-\tau}^t |H(t, s)| ds < \infty, \int_{t-\tau}^{\infty} |H(u + \tau, t)| du < \infty \text{ and } \frac{1}{3} \int_{t-\tau}^{\infty} |H(t, s)| ds \geq \int_{t-\tau}^{\infty} |H(u + \tau, s)| du$$

with $0 \leq s \leq t \leq u < \infty$.

The second outcome of the current work is given below.

Theorem 2. If assumptions (D1)-(D3) hold, then all solutions of (NVIDE) (6) start in D satisfy the variational of parameters inequality

$$|x| \leq \{\Omega_2(t_0, \|\phi\|)\} \exp\left(-\int_{t_0}^t \beta(s)ds\right) + \int_{t_0}^t [(\gamma\alpha(u) + G(u)) \exp\left(-\int_u^t \omega(s)ds\right)]du\}$$

with

$$\beta(t) = \max\{2\alpha_1(t) - \int_{t-\tau}^t K_0|H(t, s)|ds - \lambda \int_{t-\tau}^{\infty} K_0|H(u + \tau, t)|du - 1, 1\}$$

$$\gamma = 0, G(t) = F^2(t), \text{ and}$$

$$\Omega_2(t_0, \phi) = \phi^2 + \lambda \int_0^{t_0} \int_{t_0-\tau}^{\infty} K_0|H(u + \tau, s)|du\phi^2(s)ds.$$

Proof. We describe a (LF) $\Omega_2 = \Omega_2(t, x(t))$ by

$$\Omega_2 = x^2 + \lambda \int_0^t \int_{t-\tau}^{\infty} |H(u + \tau, s)|dux^2(s)ds, \quad (14)$$

where $\lambda \in \mathfrak{R}, \lambda > 0$, we fix the constant in the proof.

It is clear from (14) that Ω_2 is positive definite, since

$$\Omega_2(t, 0) = 0 \text{ and } \Omega_2(t, x) \geq x^2.$$

An easy computation from (14) and (NVIDEs) (6) and (9) shows that

$$\begin{aligned} \Omega_2' &= 2xx' + \lambda x^2 \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \lambda \int_0^t |H(t, s)|x^2(s)ds \\ &= -2p_1(t, x)x^2 + 2x \int_{t-\tau}^t H(t, s)q^{\frac{2}{3}}(x(s))ds + 2xF(t) \\ &\quad + \lambda x^2 \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \lambda \int_{t-\tau}^{\infty} |H(t, s)|x^2(s)ds. \end{aligned}$$

An elementary inequality together with the assumption $p_1(t, x) \geq \alpha(t)$ make enable that

$$\begin{aligned} \Omega_2' &\leq -2\alpha(t)x^2 + x^2 \int_{t-\tau}^t |H(t, s)|x^2(s)ds + \int_{t-\tau}^t |H(t, s)|q^{\frac{4}{3}}(x(s))ds \\ &\quad + \lambda x^2 \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \lambda \int_{t-\tau}^{\infty} |H(t, s)|x^2(s)ds \\ &\quad + x^2 + F^2(t). \end{aligned}$$

Consider the term

$$\int_{t-\tau}^t |H(t, s)|q^{\frac{4}{3}}(x(s))ds, \quad (15)$$

which is involved in (15).

Let $a = \frac{3}{2}$ and $b = 3$. By using the Young's inequality,

$$mn \leq a^{-1}m^a + b^{-1}n^b, a^{-1} + b^{-1} = 1,$$

and assumption (D1), we get

$$\begin{aligned} \int_{t-\tau}^t |H(t,s)|q^{\frac{4}{3}}(x(s))ds &= \int_{t-\tau}^t |H(t,s)|^{\frac{1}{3}}|H(t,s)|^{\frac{2}{3}}q^{\frac{4}{3}}(x(s))ds \\ &\leq \frac{1}{3} \int_{t-\tau}^t |H(t,s)|ds + \frac{2}{3} \int_{t-\tau}^t |H(t,s)|q^2(x(s))ds \\ &\leq \frac{1}{3} \int_{t-\tau}^t |H(t,s)|ds + \frac{2}{3}\alpha_1 \int_{t-\tau}^t |H(t,s)|x^2(s)ds. \end{aligned}$$

On gathering the former inequality into (15), we have

$$\begin{aligned} \Omega'_2 &\leq -[2\alpha(t) - \int_{t-\tau}^t |H(t,s)|ds - \lambda \int_{t_0-\tau}^{\infty} |H(u+t,s)|du]x^2 \\ &\quad + \frac{1}{3} \int_{t-\tau}^t |H(t,s)|ds + \frac{2}{3}\alpha_1 \int_{t-\tau}^t |H(t,s)|x^2(s)ds \\ &\quad - \lambda \int_{t-\tau}^{\infty} |H(t,s)|x^2(s)ds + x^2 + F^2(t). \end{aligned}$$

Let $\lambda = 1$, $G(t) = F^2(t)$ and $L = \frac{1}{3} \int_{t-\tau}^t |H(t,s)|ds$. Hence

$$\begin{aligned} \Omega'_2 &\leq -[2\alpha(t) - \int_{t-\tau}^t |H(t,s)|ds - \int_{t_0-\tau}^{\infty} |H(u+t,s)|du - 1]x^2 \\ &\quad + (-1 + \frac{2}{3}\alpha_1) \int_{t-\tau}^t |H(t,s)|x^2(s)ds + G(t). \end{aligned}$$

The former inequality together with (D2) yields that

$$\begin{aligned} \Omega'_2 &\leq -[2\alpha(t) - \int_{t-\tau}^t |H(t,s)|ds - \int_{t-\tau}^{\infty} |H(u+t,s)|du - 1]x^2 \\ &\quad + (-1 + \frac{2}{3}\alpha_1) \int_{t-\tau}^t |H(t,s)|x^2(s)ds + G(t) + L. \end{aligned}$$

Let

$$\beta(t) = \max\{2\alpha(t) - \int_{t-\tau}^t |H(t,s)|ds - \int_{t-\tau}^{\infty} |H(u+t,s)|du - 1, 1\}.$$

Then

$$\Omega'_2 \leq -\beta(t)x^2 - (1 - \frac{2}{3}\alpha_1) \int_{t-\tau}^t |H(t,s)|x^2(s)ds + G(t).$$

When we choose

$$\begin{aligned} \alpha_1(t) &= \beta(t), \alpha_2(t) = 1 - \frac{2}{3}\alpha_1, \\ W_1(\cdot) &= W_2(\cdot) = W_4(\cdot) = x^2(t), \\ W_3(\cdot) &= W_5(\cdot) = x^2(s), \\ \phi_1(t,s) &= \lambda \int_{t-\tau}^{\infty} |H(u+\tau,s)|du \end{aligned}$$

and

$$\phi_2(t,s) = H(t,s),$$

then we can conclude that all assumptions (A1)-(A3) of Theorem A hold. Hence, one can easily conclude that all solutions $x(t)$ of (NVIDE) (6) satisfy the desired result.

We now state some assumptions on the functions appearing in (NVIDE) (7).

C.Assumptions

We accept the following assumptions hold.

(H1) $r(t, 0) = h(0) = 0, r_1(t, x) \geq \vartheta(t) > 0, |h(x)| \leq \delta^{\frac{1}{4}}|x|, 0 < \delta < 1, t \in \mathfrak{R}^+, x \in \mathfrak{R}$,

(H2) $\gamma(t) = 2\vartheta^3(t) - \frac{1}{2} \int_{t-\tau}^t |H(t, s)| ds - \mu \int_{t-\tau}^{\infty} |H(u + \tau, t)| du - \frac{1}{2} > 0$ with $0 \leq s \leq t \leq u < \infty$, where γ is a positive function, which is bounded and continuous,

(H3) $\int_{t-\tau}^t |H(t, s)|^{\frac{1}{2}} ds < \infty, \int_{t-\tau}^{\infty} |H(u + \tau, t)| du < \infty$

and

$$\frac{5}{6} |H(t, s)| \geq \int_t^{\infty} |H(u, s)| du.$$

Set

$$D = \{x \in \mathfrak{R} : \|x\| \geq 1\}.$$

Let $\phi(t)$ be an initial function. We also suppose that this function is bounded and continuous, and $\|\phi\| = 1$ for $0 \leq t \leq t_0$.

The last outcome of the current work is given below.

Theorem 3. If assumptions (H1)-(H3) hold, then all solutions of (NVIDE) (7) initiating in D satisfy the inequality

$$\|x\| \leq W^{-1} \{ \Omega_3(t_0, \|\phi\|) \exp(-\int_{t_0}^t \gamma(u) du) + \int_{t_0}^t [(\alpha\gamma(u) + F(u)) \exp(-\int_u^t \gamma(s) ds)] du \},$$

for all $t \geq t_0$, where $\gamma(t) = \max\{\gamma_1(t), \gamma_2(t)\}$.

Remark. It is worth mentioning that in Theorem 3, W is a continuous function from \mathfrak{R}^+ to \mathfrak{R}^+ with $W(0) = 0, W(s) > 0$ if $s > 0$ and W is strictly increasing, and it is called a wedge.

Proof. We describe a (LF) $\Omega_3 = \Omega_3(t, x(t))$ by

$$\Omega_3 = x^2 + \mu \int_0^t \int_{t-\tau}^{\infty} |H(u + \tau, s)| du x^4(s) ds, \quad (16)$$

where $\mu \in \mathfrak{R}, \mu > 0$, we fix that constant in the proof.

We have from (16) that

$$\Omega_3(t, 0) = 0 \text{ and } \Omega_3(t, x) \leq x^2.$$

Thus, we see that the (LF) Ω_3 is positive definite.

Differentiating the (LF) Ω_3 with respect to t , along solutions of (NVIDE) (7), we obtain from (16) and (NVIDE) (7) that

$$\begin{aligned} \Omega_3' &= 2xx' + \mu x^4 \int_{t-\tau}^{\infty} |H(u + \tau, t)| du - \mu \int_0^t |H(t, s)| x^4(s) ds \\ &= -2r_1(t, x)x^4 + 2x \int_{t-\tau}^t H(t, s) h^{\frac{1}{3}}(x(s)) ds + 2xF(t) \\ &\quad + \mu x^4 \int_{t-\tau}^{\infty} |H(u + \tau, t)| du - \mu \int_{t-\tau}^t |H(t, s)| x^4(s) ds. \end{aligned}$$

By the use of the inequality $2|x(t)||x(s)|^{\frac{1}{3}} \leq x^2(t) + x^{\frac{2}{3}}(s)$ and the assumption $r_1(t, x) \geq \vartheta(t) > 0$, we get

$$\begin{aligned} \Omega'_3 &\leq -2\vartheta(t)x^4 + \int_{t-\tau}^t |H(t, s)|[x^2(t) + h^{\frac{2}{3}}(x(s))ds] + (x^2(t) + F^2(t)) \\ &\quad + \mu x^4 \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \mu \int_{t-\tau}^t |H(t, s)|x^4(s)ds \\ &= -2\vartheta^3(t)x^4 + \int_{t-\tau}^t |H(t, s)|x^2(t)ds + \int_{t-\tau}^t h^{\frac{2}{3}}(x(s))ds \\ &\quad + x^2 + F^2(t) + \mu x^4 \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \mu \int_{t-\tau}^t |H(t, s)|x^4(s)ds. \end{aligned} \quad (17)$$

Let $a = 2, b = 2$ and $a = 6, b = \frac{6}{5}$ respectively. From the Young's inequality,

$$mn \leq \frac{1}{a}m^a + \frac{1}{b}n^b, \frac{1}{a} + \frac{1}{b} = 1$$

and assumption (H1), we get the following relations, respectively:

$$\begin{aligned} \int_{t-\tau}^t |H(t, s)|x^2(t)ds &= \int_{t-\tau}^t |H(t, s)|^{\frac{1}{2}}|H(t, s)|^{\frac{1}{2}}x^2(t)ds \\ &\leq \frac{1}{2} \int_{t-\tau}^t |H(t, s)|^{\frac{3}{2}}ds + \frac{1}{2} \int_{t-\tau}^t |H(t, s)|^{\frac{1}{2}}x^4(t)ds \end{aligned}$$

and

$$\begin{aligned} \int_{t-\tau}^t |H(t, s)|h^{\frac{2}{3}}(x(s))ds &= \int_{t-\tau}^t |H(t, s)|^{\frac{5}{6}}|H(t, s)|^{\frac{1}{6}}h^{\frac{2}{3}}(x(s))ds \\ &\leq \frac{5}{6} \int_{t-\tau}^t |H(t, s)|ds + \frac{\delta}{6} \int_{t-\tau}^t |H(t, s)|x^4(s)ds. \end{aligned}$$

In addition, we have

$$x^2 \leq \frac{1}{2}x^4 + \frac{1}{2}.$$

Substituting the previous inequalities into (17), we obtain

$$\begin{aligned} \Omega'_3 &\leq -[2\vartheta^3(t) - \frac{1}{2} \int_{t-\tau}^t |H(t, s)|^{\frac{1}{2}}ds - \mu \int_{t-\tau}^{\infty} |H(u + \tau, t)|du - \frac{1}{2}]x^4 \\ &\quad + \frac{1}{2} \int_{t-\tau}^t |H(t, s)|^{\frac{3}{2}}ds + \frac{5}{6} \int_{t-\tau}^t |H(t, s)|ds \\ &\quad + (\frac{\delta}{6} - \mu) \int_{t-\tau}^t |H(t, s)|x^4(s)ds + 1 + F^2(t). \end{aligned}$$

Let

$$\begin{aligned} G(t) &= F^2(t), \frac{5}{6}|H(t, s)| \geq \int_t^{\infty} |H(u, s)|du, \\ \mu &= \delta, L = \frac{1}{2} \int_{t-\tau}^t |H(t, s)|^{\frac{3}{2}}ds + \frac{5}{6} \int_{t-\tau}^t |H(t, s)|ds \end{aligned}$$

and

$$\rho(t) = \max\{\gamma(t), 1\}.$$

Thereafter, using assumption (H2) of Theorem 3, we conclude that

$$\Omega'_3 \leq -\rho(t)x^4.$$

The remaining of the proof can be done by following a similar way that shown in the proof of Theorem 1 or 2. Therefore, we omit the details.

3. CONCLUSION

We investigate three (NVIDEs) with constant time lag. Three variational of parameters inequalities are obtained so that the all solutions of the considered (NVIDEs) remain bounded. We benefited from the (LFs). The obtained results have a contribution to the related literature, and they improve and extend the results in [51] from the cases of without time lag to that general non-linear cases with time lag. The obtained results are compared with that found in [51] and that in the references of this paper.

4. ACKNOWLEDGEMENT

The authors of this paper would like to express their sincere appreciations to the main editor and the anonymous referees for their valuable comments and suggestions which have led to an improvement in the presentation of the paper.

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