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# TRANSLATION-FACTORABLE SURFACES IN THE 3-DIMENSIONAL EUCLIDEAN AND LORENTZIAN SPACES SATISFYING $\Delta r_i = \lambda_i r_i$

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ABSTRACT. This paper deals with the Translation-Factorable (TF) surfaces in the 3-dimensional Euclidean space and Lorentzian-Minkowski space with the condition  $\Delta r_i = \lambda_i r_i$  where  $\Delta$  denotes the Laplace operator. Our result will be obtained for the complete classification theorems and give an explicit forms of these surfaces.

## 1. INTRODUCTION

In 1983 B-Y Chen introduced the notion of Euclidian immersions of finite type. Basically there are submanifolds whose into  $\mathbb{R}^m$  is constructed by making use of finite number of  $\mathbb{R}^m$ -valued eigenfunctions of their Lapalacian. Many works were done to characterize the classification of submanifolds in terms of finite type. Important results about 2-type spherical closed submanifolds (where spherical means into a sphere) have been obtained see [9].

A well known are the only surfaces in  $\mathbb{R}^3$  satisfying the condition

$$\Delta r = \lambda r \quad \lambda \in \mathbb{R}$$

where  $\Delta$  is the Laplace operator associated with the induced metric. On the other hand Garay [13] determined the complete surfaces of revolution in  $\mathbb{R}^3$  whose component functions are eigenfunctions of their Laplace operator i.e.

$$\Delta r^i = \lambda^i r^i \quad \lambda^i \in \mathbb{R}$$

Later Lopez [16] studied the hypersurfaces in  $\mathbb{R}^{n+1}$  verifing

$$\Delta r = \lambda r \quad A \in \mathbb{R}^{n+1*n+1}$$

Kaimakamis and Papantounion [7] studied surfaces of revolution in the 3-dimensional Lorentz-Minkowski space satisfying the condition

$$\Delta^{II}r = Ar$$

where  $\Delta^{II}$  is the Laplace operator with respect to the second fundamental form and A is a real  $3 \times 3$  array.

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Zoubir and Bekkar [8] classified the surfaces of revolution with non zero Gaussian curvature  $K_G$  in the 3-dimensional Euclidean space  $\mathbf{E}^3$  and Lorentzian-Minkowski spaces under the condition

$$\Delta r^i = \lambda^i r^i, \quad \lambda^i \in \mathbb{R}$$

Baba Hamed, Bekkar and Zoubir [4] determined the translation surfaces in the 3-dimensional Lorentz-Minkowski space  $\mathbf{E}_1^3$ , whose component functions are eigenfunctions of their Laplace operator. Baba Hamed, Bekkar [3] studies the helicoidal surfaces without parabolic points in  $\mathbf{E}_1^3$ , which satisfy the condition

$$\Delta^{II} r_i = \lambda_i r$$

Bekkar and Senoussi [6] studied the factorable surfaces in the 3-dimensional Minkowski space under the condition

$$\Delta r_i = \lambda_i r$$

where  $\lambda_i \in \mathbb{R}$  and  $dr_i$  are the coordinate of the surface. There has been classification of factorable surface in the 3-dimensional Lorentz-Minkowski Euclidian and pseudo-Galilean space. Lopezand and Moruz [17] studied translation and homothetical surfaces with constant minimal homothetical non degenerate surfaces in Euclidian in  $\mathbf{E}_1^3$ 

In this paper we classify the factorable surfaces in the 3-dimensional Euclidian space  $\mathbf{E}^3$  and lorentzian  $\mathbf{E}^3_1$  under the condition

$$\Delta r_i = \lambda_i r_i \tag{1}$$

where  $\lambda_i \in \mathbb{R}$ 

### 2. Preliminaries

Let  $\mathbf{E}^3$  be the 3-dimensional Euclidian space, equipped with the inner product

$$g(X,Y) = x_1y_1 + x_2y_2 + x_3y_3$$

for  $X = (x_1, x_2x_3), Y = (y_1, y_2, y_3) \in \mathbf{E}^3$ Let  $\mathbf{E}_1^3$  be the 3-dimensional Minkowski space, with the scalar product given by

$$g_L = -dx^2 + dy^2 + dz^2$$

where (x, y, z) is a standard rectangular coordinate system of  $\mathbf{E}_1^3$ Let  $r : \mathbf{M}^2 \to \mathbf{E}_1^3$  be an isometric immersion of a surface in the 3-dimensional Lorentzian-Minkowski space.

A surface  $\mathbf{M}^2$  is said to be of finite type if every component of its position vector field r can be written as a finite sum of eigenfunction of the Laplace  $\Delta$  of  $\mathbf{M}^2$ , if

$$r = r_0 + \sum_{i=1}^k r_i$$

**Definition 2.1** (4-15). A surface M is a translation surface if it can be parametrized by

$$x(u,v) = (u,v, f(u) + g(v))$$
(2)

**Definition 2.2** (6-18). A surface M is a factorable surface if it can be parameterized by

$$x(u,v) = (u,v,f(u)g(v))$$
 (3)

Next, we define an extended surface in  $\mathbf{E}^3$  using definitions we call it TF-type surface as follows:

**Definition 2.3.** A surface M is a TF-type surface if it can be parameterized by

$$x(u,v) = (u,v,A(f(u) + g(v)) + Bf(u)g(v)),$$
(4)

where A and B are non-zero real numbers.

**Remark 2.4.** In [4], we have if  $A \neq 0$  and B = 0 in, then surface is a translation surface. In [14], we have if A = 0 and  $B \neq 0$ , then surface is a factorable surface.

For vector  $X = (x_1, x_2, x_3)$  and  $Y = (y_1, y_2, y_3)$  in  $\mathbf{E}_1^3$ , the Lorentz scalar product and the cross product are defined by :

$$y_L = -x_1y_1 + x_2y_2 + x_3y_3$$

The Gauss curvature and the mean curvature are:

$$K_G = g_L(\mathbf{N}, \mathbf{N}) \left(\frac{LN - M^2}{EG - F}\right), \quad H = \frac{EN + GL - 2FM}{2|EG - F^2|}$$

Let  $x^i, x^j$  be a local coordinate system of  $\mathbf{M}^2$ . For the array  $(g_{i,j})$  (i, j = 1, 2) consisting of components of the induced metric on  $\mathbf{M}^2$ , we denote by  $(g^{i,j})$  the inverse matrix of the array  $(g_{i,j})$ . Then the Laplacian operator  $\Delta$  on  $\mathbf{M}^2$  is given by:

$$\Delta = \frac{-1}{\sqrt{|D|}} \sum_{i,j} \frac{\partial}{\partial x^i} \left( \sqrt{|D|} g^{i,j} \frac{\partial}{\partial x^j} \right)$$
(5)

A vector V of  $\mathbf{E}_1^3$  is said to be timelike if  $g_L(V, V) < 0$ , spacelike if  $g_L(V, V) > 0$  or V = 0 and lightlike or null if  $g_L(V, V) = 0$  and  $V \neq 0$ . A surface in  $\mathbf{E}_1^3$  is spacelike, timelike or lightlike if the tangent plane at any point is spacelike, timelike or lightlike respectively [19].

### 3. Translation-factorable surfaces in $\mathbf{E}^3$

In this section, we consider surface in  $\mathbf{E}^3$ . Assume that  $\mathbf{M}^2$  is equivalent to

$$r(u,v) = (u,v,f(u)g(v) + f(u) + g(v))$$
(6)

the coefficients of the first fundamental form are:

$$E = (f'g + f')^2 + 1, \quad F = (f'g + f')(fg' + g'), \quad G = (fg' + g')^2 + 1$$
$$\mathbf{N} = \frac{1}{W}(-f'g - f', -fg' - g', 1) \tag{7}$$

the coefficients of the second fundamental form are:

$$L = \frac{f''g + f''}{W}, \quad M = \frac{(f'g + f')(fg' + g')}{W}, \quad N = \frac{fg'' + g'}{W}$$
 where  $W = \sqrt{(f'g + f')^2 + (fg' + g')^2 + 1}$ 

The Laplacian  $\Delta$  of  $\mathbf{M}^2$  is given by:

$$\Delta = \frac{1}{W^2} \left( E \frac{\partial^2}{\partial v^2} + G \frac{\partial^2}{\partial u^2} - 2F \frac{\partial^2}{\partial u \partial v} \right) + \frac{2H}{W} \left( (f'g + f') \frac{\partial}{\partial u} + (fg' + g') \frac{\partial}{\partial v} \right)$$
(8)

 $\Delta u = \lambda_1 u; \ \Delta v = \lambda_2 v; \ \Delta (f(u)g(v) + f(u) + g(v)) = \lambda_3 (f(u)g(v) + f(u) + g(v))$ (9) By using (1), (7) we get:

$$2(f'g + f')H = W\lambda_1 u \tag{10}$$

$$2(fg' + g')H = W\lambda_2 v \tag{11}$$

$$2H = -W\lambda_3(fg + f + g) \tag{12}$$

Next, we explore the classification of the Translation-Factorable surfaces  $\mathbf{M}^2$  satisfying (1)

- Case 1: Let  $\lambda_3 \neq 0$ .
- (i) If fg + f + g = 0, then H = 0
- (ii) If  $fg + f + g \neq 0$  we have:

 $(k_1)$  If  $\lambda_1 = 0$  and  $\lambda_2 \neq 0$ , equations (10) and (11) imply that:

$$f(u) = a \in \mathbb{R} - \{-1\}, \quad g' \neq 0 \quad and \quad H = \frac{(a+1)g''}{2W^3}$$

The system of equations (10), (11) and (12) becomes

$$(1+a)^2 g' g'' = \lambda_2 v ((a+1)^2 g'^2 + 1)^2$$
(13)

$$(1+a)g'' = -\lambda_3(ag+a+g)((a+1)^2g'^2+1)^2$$
(14)

Equation (14) is equivalent to

$$g(v) = \frac{1}{(a+1)} \left( -a \pm \sqrt{\frac{-\lambda_2 v^2 + a^2 \lambda_3}{\lambda_3}} \right) \qquad (-1 < -\lambda_2 v^2 + a^2 \lambda_3 < 0)$$

Hence, the surface  $\mathbf{M}^2$  can be expressed by

$$r\left(u,v,\pm\sqrt{\frac{-\lambda_2v^2+a^2\lambda_3}{\lambda_3}}\right) \qquad (-1<-\lambda_2v^2+a^2\lambda_3<0)$$

 $(k_2)$  If  $\lambda_2 = 0$  and  $\lambda_1 \neq 0$ . Equations (10) and (11) imply that:

$$f(u) = c \in \mathbb{R} - \{-1\}, \quad g' \neq 0 \quad and \quad H = \frac{(c+1)f''}{2W^3}$$

The system of equations (10), (11) and (12), in this case takes the form

$$(1+c)^2 f' f'' = \lambda_2 u ((c+1)^2 f'^2 + 1)^2$$
(15)

$$(1+c)f'' = -\lambda_3(cf+c+f)((c+1)^2f'^2+1)^2$$
(16)

Equation (16) is equivalent to

$$f(u) = \frac{1}{(a+1)} \left( -a \pm \sqrt{\frac{-\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}} \right) \qquad (-1 < -\lambda_2 u^2 + a^2 \lambda_3 < 0)$$

Hence, the surface  $\mathbf{M}^2$  can be expressed by:

$$r\left(u,v,\pm\sqrt{\frac{-\lambda_2u^2+a^2\lambda_3}{\lambda_3}}\right) \qquad (-1<-\lambda_2u^2+a^2\lambda_3<0)$$

 $(k_3)$  If  $\lambda_1 \neq 0$  and  $\lambda_2 \neq 0$ . Equations (10) and (11) imply that:

 $f' \neq 0$  and  $g' \neq 0$ 

We multiply Equation (10) by fg' + g' and Equation (10) by f'g + f', we obtain:

$$\frac{(f+1)}{f'}\lambda_1 u = \frac{(g+1)}{g'}\lambda_2 v = e, \quad e \in \mathbb{R}^*$$
(17)

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Equations (10) and (12) imply that:

$$\lambda_1 u = -\lambda_3 (fg + f + g)(f'g + f) \tag{18}$$

equations (17) and (18) imply that:

$$-\lambda_3 (fg + f + g)^2 = e \tag{19}$$

The functions f and g are constants, hence there are no Translation-Factorable surfaces in this cases satisfying (1)

 $(k_4)$  If  $\lambda_1 = 0$  and  $\lambda_2 = 0$  equations (10) and (11) imply that:

$$f' = 0 \qquad and \qquad g' = 0$$

Hence  $\lambda_3 = 0$ . Therefore, there are no Translation-Factorable surfaces in this cases satisfying (1)

Case 2: Let  $\lambda_3 = 0$ . Then, the equation (12) gives rise to H = 0 which means that the surfaces are minimal. We get also by the equations (10) and (11):  $\lambda_1 = \lambda_2 = 0$  Finally:

**Theorem 3.1.** Let  $\mathbf{M}^2$  be a Translation-Factorable (TF) given by (6) in  $\mathbf{E}^3$ . Then  $\mathbf{M}^2$  satisfies  $\Delta r_i = \lambda_i r_i$ , (i=1;2;3) if and only if the following statements hold (1)  $\mathbf{M}^2$  has zero mean curvature

(2)  $\mathbf{M}^2$  is parameterized as

$$\left(u, v, \pm \sqrt{\frac{-\lambda_2 v^2 + a^2 \lambda_3}{\lambda_3}}\right) \qquad (-1 < -\lambda_2 v^2 + a^2 \lambda_3 < 0)$$

(3)  $\mathbf{M}^2$  is parameterized as

$$\left(u, v, \pm \sqrt{\frac{-\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}}\right) \qquad (-1 < -\lambda_2 u^2 + a^2 \lambda_3 < 0)$$

**Translation-Factorable surfaces in E**<sup>3</sup><sub>1</sub>. In this section, we consider surfaces in  $\mathbf{E}^3_1$  and we investigate the classification of the Translation-Factorable satisfying (1). We distinguish  $EG - F^2 > 0$  or  $EG - F^2 < 0$ .

Suppose that  $\mathbf{M}^2$  is given by (6), the coefficients of the first and second fundamental forms are:

$$E = (f'g + f')^2 - 1; \qquad F = (f'g + f')(fg' + g'); \qquad G = 1 + (fg' + g)^2$$
(20)

and

$$L = \frac{f''g + f''}{W}; \quad M = \frac{(f'g + f)(fg' + g')}{W}; \quad N = \frac{fg'' + g''}{W}$$

The mean curvature H is

$$H = 1/2W^{-3}H_1$$

Where  $H_1 = (1 + (fg' + g')^2)(f''g + f'') + (f'g + f')^2 - 1)(fg'' + g'') - 2(f + 1)(g + 1)f'^2g'^2$ 

Spacelike Translation-Factorable surfaces in  $\mathbf{E}_1^3$ . We investigate the spacelike translation and factorable surfaces in  $\mathbf{E}_1^3$ .

If we use (5), the Laplacian  $\Delta$  of  $\mathbf{M}^2$  is given by:

$$\Delta = \frac{1}{W^2} \left( E \frac{\partial^2}{\partial v^2} + G \frac{\partial^2}{\partial u^2} - 2F \frac{\partial^2}{\partial u \partial v} \right) - \frac{2H}{W} \left( (fg' + g') \frac{\partial}{\partial v} - (f'g + f') \frac{\partial}{\partial u} \right)$$
(21)

where  $W = \sqrt{EG - F^2}$ .

Assume that  $EG - F^2 = (f'g + f')^2 - (fg' + g')^2 - 1 > 0$ , the metric of  $\mathbf{M}^2$  is spacelike.

Then using (1), (20) and (21) we have:

$$W^{-4}(f'g + f')H_1 = \lambda_1 u$$
(22)

$$W^{-4}(fg'+g')H_1 = -\lambda_2 v$$
(23)

$$W^{-4}H_1 = \lambda_3(fg + f + g)$$
 (24)

First, we examine the classification of the spacelike Translation-Factorable surfaces  $\mathbf{M}^2$  satisfying (1).

Case 1: Let  $\lambda_3 = 0$ , then, the equation (24) gives rise to  $H_1 = 0$  meaning that the surface are minimal. We get also by the equations (22) and (23)  $\lambda_1 = \lambda_2 = 0$ . Case 2: Let  $\lambda_3 \neq 0$ , then  $H_1 \neq 0$  and hence we have necessarily by equation (22)  $\lambda_1 \neq 0$ .

i) If  $\lambda_2 = 0$  we get (23), so  $g(v) = a, a \in \mathbb{R} - \{-1\}$ 

In this case, the system of equations (22),(23) and (24) takes the form:

$$(a+1)^2 f' f'' = \lambda_1 u ((a+1)^2 f'^2 - 1)^2$$
(25)

$$(a+1)f'' = \lambda_3(af+f+a)((a+1)^2f'^2-1)^2$$
(26)

Using equation (26)

$$f(u) = \frac{1}{(a+1)} \left( -a \pm \sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}} \right) \quad which \quad such \quad that \ \lambda_2 u^2 + a^2 \lambda_3 < 1$$

So the parametrization of the surfaces can be written in the form:

$$r(u,v) = \left(u,v,\pm\sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}}\right)$$

ii) If  $\lambda_2 \neq 0$  we can rewrite the system as follow:

$$\begin{cases} \lambda_2 v(fg+g+f) = -a(fg'+g')\\ \lambda_1 u(fg+g+f) = a(f'g+f') \end{cases}$$
(27)

Equation (21) and (22)  $(a \neq -1)$  imply that:

$$\lambda_1 u = \lambda_3 (fg + f + g)(f'g + f') \tag{28}$$

From (27) and (28) we obtain:

$$a = \lambda_3 (fg + f + g)^2$$

Therefore the functions f and g are constants assuming that there are no Translation-Factorable surfaces in this case satisfying (1). Thus, we can give the following result:

**Theorem 3.2.** Let  $\mathbf{M}^2$  be a spacelike Translation-Factorable (TF) given by (6) in  $\mathbf{E}_1^3$ . Then  $\mathbf{M}^2$  satisfies  $\Delta r_i = \lambda_i r_i$ , (i=1;2;3) if and only if the following statements hold

(1)  $\mathbf{M}^2$  has zero mean curvature

(2)  $\mathbf{M}^2$  is parameterized as

$$r(u,v) = \left(u, v, \pm \sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}}\right) \quad (0 < \lambda_2 u^2 + a^2 \lambda_3 < 1)$$

Timelike Translation-Factorable surfaces in  $\mathbf{E}_1^3$ . In this section, we deal with the spacelike translation-factorable surfaces in  $\mathbf{E}_1^3$ . If we use (5), the Laplacian  $\Delta$  of  $\mathbf{M}^2$  is given by:

$$\Delta = \frac{1}{W^2} \left( E \frac{\partial^2}{\partial v^2} + G \frac{\partial^2}{\partial u^2} - 2F \frac{\partial^2}{\partial u \partial v} \right) - \frac{2H}{W} \left( (fg' + g') \frac{\partial}{\partial v} - (f'g + f') \frac{\partial}{\partial u} \right)$$
(29)

where  $W = \sqrt{F^2 - EG}$ .

Assuming that  $EG - F^2 = (f'g + f')^2 - (fg' + g')^2 - 1 < 0$ , the metric of  $\mathbf{M}^2$  is timelike.

Then using (29) and (20) we get

$$\begin{cases} \Delta(u) = -W^{-4}(f'g + f')H_1 \\ \Delta(v) = W^{-4}(fg' + g')H_1 \\ \Delta(fg + f + g) = -W^{-4}H_1 \end{cases}$$
(30)

hence

$$\Delta r = W^{-4} H_1(-f'g + f', fg' + g', -1) \tag{31}$$

By (1) and (30) we obtain the following system of differential equations

$$W^{-4}(f'g + f')H_1 = -\lambda_1 u {32}$$

$$W^{-4}(fg' + g')H_1 = \lambda_2 v \tag{33}$$

$$W^{-4}H_1 = \lambda_3(fg + f + g)$$
(34)

We explore the classification of the timelike Translation-Factorable surfaces  $\mathbf{M}^2$  satisfying (1.1).

Case 1: Let  $\lambda_3 = 0$ , then, the equation (35) gives rise to  $H_1 = 0$ , which means that the surfaces are minimal. We have also by the equations (33) and (34)  $\lambda_1 = \lambda_2 = 0$ . Cases 2: Let  $\lambda_3 \neq 0$ .

i) If fg + f + g = 0, then  $H_1 = 0$ 

ii) If 
$$fg + f + g \neq 0$$
, in this case we have:

a) If  $\lambda_1 = 0$  and  $\lambda_2 \neq 0$  equations (33) and (34) imply that:

$$f' = 0, \quad g' \neq 0, \quad and \ g'' \neq 0$$

It follows that  $f(u) = a, a \in \mathbb{R} - \{-1\}$  and g'(v) is a non constant function. The system (33), (34) and (35) is reduced to be equivalent to

$$-(a+1)^2 g' g'' = \lambda_2 v ((a+1)^2 g'^2 + 1)^2$$
(35)

$$(a+1)g'' = \lambda_3(ag+g+a)((a+1)^2f'^2+1)^2$$
(36)

Equation (36) implies

$$g(v) = \frac{1}{(a+1)} \left( -a \pm \sqrt{\frac{-\lambda_2 v^2 + a^2 \lambda_3}{\lambda_3}} \right) \quad which \ such \ that \ 0 < -\lambda_2 v^2 + a^2 \lambda_3 < 1$$

So the parametrization of the surfaces can be written in the form:

$$r(u,v) = \left(u, v, \pm \sqrt{\frac{-\lambda_2 v^2 + a^2 \lambda_3}{\lambda_3}}\right) \quad which \ such \ that \ 0 < -\lambda_2 v^2 + a^2 \lambda_3 < 1$$

ii) If  $\lambda_2 = 0$  and  $-\lambda_2 v^2 + a^2 \lambda_3 \neq 0$  then

$$g' = 0, \qquad f' \neq 0, \qquad f'' \neq 0$$

The system (33), (34) and (35) is reduce equivalently to

$$-(a+1)^2 g' g'' = \lambda_1 u ((a+1)^2 g'^2 + 1)^2$$
(37)

$$-(a+1)f'' = \lambda_3(af+f+a)(1-(a+1)^2f'^2)^2$$
(38)

Hence

$$f(u) = \frac{1}{(a+1)} \left( -a \pm \sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{2\lambda_3}} \right) \quad which \ such \ that \ 0 < \lambda_2 u^2 + a^2 \lambda_3 < 1$$

So the parametrization of the surfaces can be written in the form

$$r(u,v) = \left(u,v,\pm\sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}}\right) \quad which \ such \ that \ \lambda_2 u^2 + a^2 \lambda_3 < 1$$

c) If  $\lambda_1 = \lambda_2 = 0$  we have:

i) If f' = g' = 0 imply  $H_1 = 0$ . From (35) we obtain  $\lambda_3 = 0$  which is a contradiction. ii) If f' = 0 and  $g' \neq 0$ , then (34) gives g = 0, which is a contradiction. iii) If  $f' \neq 0$  and g' = 0, then (33) gives g = 0, which is a contradiction. 3) If  $\lambda_1 \neq 0$  and  $\lambda_2 \neq 0$ , then

$$f' \neq 0 \qquad g' \neq 0$$

We multiply Equation (33) by g'f + g' and (34) by f'g + f', and we obtain:

$$\begin{cases} \lambda_2 v(fg+g+f) = a(fg'+g')\\ \lambda_1 u(fg+g+f) = -a(f'g+f') \end{cases}$$
(39)

Equation (33) and (33)  $(a \neq -1)$  imply

$$\lambda_1 u = \lambda_3 (fg + f + g)(f'g + f') \tag{40}$$

From (39) and (40) we obtain:

$$-a = \lambda_3 (fg + f + g)^2$$

The functions f and g are constants and hence there are no Translation-Factorable surfaces in this case satisfying (1). Thus we can give the following result:

**Theorem 3.3.** Let  $\mathbf{M}^2$  be a timelike Translation-Factorable (TF) given by (6) in  $\mathbf{E}_1^3$ . Then  $\mathbf{M}^2$  satisfies  $\Delta r_i = \lambda_i r_i$ , (i=1;2;3) if and only if the following statements hold

(1)  $\mathbf{M}^2$  has zero mean curvature

(2)  $\mathbf{M}^2$  is parameterized as

$$r(u,v) = \left(u,v,\pm\sqrt{\frac{-\lambda_2v^2 + a^2\lambda_3}{\lambda_3}}\right) \quad (0 < -\lambda_2v^2 + a^2\lambda_3 < 1)$$

(3)  $\mathbf{M}^2$  is parameterized as

$$r(u,v) = \left(u,v,\pm\sqrt{\frac{\lambda_2 u^2 + a^2 \lambda_3}{\lambda_3}}\right) \quad (0 < \lambda_2 u^2 + a^2 \lambda_3 < 1)$$

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