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TRANSFER FROM SPINES OF UNIFORM CROSS SECTIONS USING HPM

WAQAR A. KHAN*, AMIR SHAHZAD**

ABSTRACT

Homotopy perturbation method (HPM) is employed to investigate the effects of temperature dependent thermal conductivity on the dimensionless temperature distribution along spines of arbitrary uniform cross sections (rectangular, square, elliptical and circular) in still ambient air. Thermal performance of each cross section is compared in terms of efficiency based on equal cross sectional area of the spines. It is noticed that elliptical and rectangular cross sections with smaller axis ratios have higher efficiencies and they approach to circular and square cross sections in the limiting case when their axis ratios tend to unity. The effect of Biot number on dimensionless temperature distribution and on efficiency of each cross section is also presented graphically.

KEY WORDS

Spines, Homotopy Perturbation Method, Thermal Conductivity, Spine Efficiency

^{*} Associate Professor, Department of Mechanical Engineering, National University of Sciences and Technology, PNS Jauhar, Karachi, Pakistan.

^{**} Research Associate, Department of Mathematics, COMSATS Institute of Information Technology, Abbottabad, Pakistan.

NOMENCLATURE

A_c	cross sectional area of the spine, m ²
a	semi major axis of elliptical cross section, m
b	width of rectangular cross section or semi minor axis of elliptical cross section, $\mathbf m$
Bi	Biot number = $\frac{h\mathcal{L}}{k_{-}}$
d	diameter of circular cross section, m
E(e)	complete elliptic integral of second kind
e	eccentricity in case of elliptical cross section = $\sqrt{1 - \epsilon_1^2}$
h	heat transfer coefficient, W/m ² · K
k(T)	temperature dependent thermal conductivity, W/m · K
k_a	thermal conductivity at reference temperature, W/m · K
L	length of spine, m
\mathcal{L}	characteristic length of the spine cross-section, m
M	dimensionless spine parameter = $\sqrt{\frac{p h}{k_a A_c} L^2}$
p	perimeter of spine, m
s	side of square cross section, m
T	temperature, K
t	thickness of rectangular cross section, m
\dot{Q}_{spine}	energy conducted into surface at base, W
x	axial distance from the spine base, m

Greek Symbols

Greeк зутос	NS .
β	temperature coefficient
ΔT	temperature difference between base and ambient, K
€	dimensionless temperature coefficient
€1	axis ratio for elliptical cross section $=\frac{b}{a}$
ϵ_2	axis ratio for rectangular cross section $=\frac{t}{t}$
η_{spine}	spine efficiency
θ_0	initial guess
θ	dimensionless temperature = $\frac{T - T_a}{T_b - T_a}$
Ċ	dimensionless axial distance

Subscripts

1	nrst order solution
2	second order solution
a	ambient
b	base
C	circular cross section
E	elliptical cross section
R	rectangular cross section
S	square cross section
w	wall

INTRODUCTION

Heat transfer from a prime surface can be significantly increased by the addition of spines which are attached to the prime surface. These spines are widely used in several engineering applications. Different spine geometries can be found in standard heat transfer text books [1-3]. In this paper HPM is employed to investigate the effects of temperature dependent thermal conductivity on heat transfer from spines of arbitrary constant

cross sections in still ambient air for mixed boundary conditions. Homotopy perturbation method (HPM) was first proposed by He [4] and has been used to solve non-linear equations in heat transfer applications by several authors including Khan and coworkers [5-7].

Zubair et al. [8] studied optimization of circular fins with general power - law profile and temperature dependent thermal conductivity. Chiu and Chen [9] investigated the results for a rectangular fin with variable thermal conductivity using the Adomian decomposition method. He [10, 11] introduced homotopy perturbation method (HPM) whereas Lio [12,13] employed homotopy analysis method (HAM) to solve non-linear equations.

Razelos and Imre [14] investigated the effect of variable thermal conductivity and heat transfer coefficient along the trapezoidal profile of an annular fin. They assumed that heat transfer coefficient increases according to a power law with distance from the fin base. Unal [15] developed the closed-form solution for the straight fin having a rectangular profile for the one-dimensional temperature distribution, assuming that the heat transfer coefficient is a power function of the difference between the temperature of the fin and the ambient fluid. Sen and Trinh [16] obtained an exact solution for the performance of the same fin and the heat transfer coefficient given by a power-type temperature dependence. Laor and Kalman [17] presented a theoretical-numerical analysis of longitudinal and annular fins and spines having rectangular, triangular, and parabolic profiles. They analyzed the effect of a temperature-dependent heat transfer coefficient on the fin efficiency and optimum fin dimensions. The heat transfer coefficient used in this analysis was approximated by a power function of the fin and fluid temperature difference.

Assumptions

This study is based on the following assumptions:

- The heat flow and temperature distribution are steady state.
- The spine material is homogeneous and isotropic.
- The heat transfer coefficient is constant and uniform over the entire surface of the spine.
- The temperature of the air surrounding the spine is uniform.
- The temperature at the base is uniform and constant.
- There are no distributed heat sources within the spine.
- 7. The radiation heat transfer is negligible.
- Heat transfer is one-dimensional.
- Thermal contact at the spine base is perfect.

ANALYSIS

Consider a spine of arbitrary uniform cross section (Fig. 1) with cross-sectional area A_c , perimeter p, length L, and temperature dependent thermal conductivity k(T). The area and perimeter for each cross section are given in Table 1. The spine is attached to a prime surface at constant temperature T_b and extends into a fluid at ambient temperature T_a . Heat is removed from the surface and the tip via natural convection only. The dimension of each cross section is determined on the basis of equal cross sectional area. The Biot number is defined as $Bi = \frac{h \mathcal{L}}{k_a}$, where \mathcal{L} is the characteristic length of the spine cross-section. This characteristic length of the spine is defined as the ratio of the cross sectional area to the perimeter, A_c/p , and for different cross sections is presented in Table 1. The Biot number is assumed to be sufficiently small that the temperature across the cross-section is essentially constant.

Steady state heat balance equation for the spine of arbitrary uniform cross section can be written as

$$\frac{d}{dx}\left[k(T)\frac{dT}{dx}\right] = \frac{ph}{A_c}(T - T_a) \qquad (1)$$

with

$$k(T) = k_a[1 + \beta(T - T_a)]$$
 (2)

where h is the uniform convective heat transfer coefficient, k_a is the thermal conductivity at ambient temperature, and the constant β is called the temperature coefficient of thermal conductivity. In dimensionless form, Eq. (1) can be written as

$$\frac{d}{d\zeta}\left[\left(1 + \epsilon\theta\right)\frac{d\theta}{d\zeta}\right] = M^2\theta \qquad (3)$$

where M is the dimensionless spine parameter and it is written as

$$M = \sqrt{\frac{ph}{k_a A_c} L^2}$$
(4)

and the dimensionless variables are

$$\theta = \frac{T - T_a}{T_b - T_a}, \quad \zeta = \frac{x}{L}, \quad \epsilon = \beta \Delta T$$
 (5)

Equation (3) can be separated into linear and non-linear parts

$$\left[\frac{d^2\theta}{d\zeta^2} - M^2\theta\right] + \epsilon \frac{d}{d\zeta} \left(\theta \frac{d\theta}{d\zeta}\right) = 0 \tag{6}$$

This equation can be solved using homotopy perturbation method for the following mixed boundary conditions:

$$\theta(0) = 1$$
 and $\frac{d\theta(1)}{d\zeta} = -Bi\theta(1)$ (7)

Homotopy for Eq. (6) satisfies the equation

$$(1-q)\left[\left(\frac{d^2\theta}{d\zeta^2} - M^2\theta\right) - \left(\frac{d^2\theta_0}{d\zeta^2} - M^2\theta_0\right)\right] + q\left[\epsilon\theta\frac{d^2\theta}{d\zeta^2} + \epsilon\left(\frac{d\theta}{d\zeta}\right)^2\right] = 0 \tag{8}$$

where $q \in [0, 1]$ is an embedding parameter, and θ_0 is the initial guess that can be obtained by solving the linear part of Eq. (6)

$$\frac{d^{2}\theta_{0}}{d\ell^{2}} - M^{2}\theta_{0} = 0 \qquad (9)$$

with boundary conditions

$$\theta_0(0) = 1$$
 and $\frac{d\theta_0(1)}{d\zeta} = -Bi\,\theta_0(1)$ (10)

The solution of Eq. (9) is given by

$$\theta_0 = C_1 e^{-M\zeta} + C_2 e^{M\zeta}$$
(11)

where C_1 and C_2 are the constants of integration and can be determined by using boundary conditions (10).

$$C_{1} = \frac{e^{-M} (M - Bi)}{(M + Bi) e^{M} + e^{-M} (M - Bi)}$$

$$C_{2} = \frac{(M + Bi) e^{M}}{(M + Bi) e^{M} + e^{-M} (M - Bi)}$$
(12)

Assuming that Eq. (8) has a solution of the form

$$\theta(\zeta, q) = \theta_0 + q\theta_1 + q^2\theta_2 + \cdots \qquad (13)$$

By substituting Eq. (13) in Eq. (8) and equating the powers of q, we obtain

$$\frac{d^2\theta_1}{d\zeta^2} - M^2\theta_1 + \epsilon \left[\theta_0 \frac{d^2\theta_0}{d\zeta^2} + \left(\frac{d\theta_0}{d\zeta}\right)^2\right] = 0 \tag{14}$$

The solution of Eq. (14) can be written as

$$\theta_{1}(\zeta) = e^{M\zeta}C_{4} + e^{-M\zeta}C_{3} - \frac{2}{3}\epsilon e^{-2M\zeta}$$

$$\left\{ \frac{e^{-2M}(M - Bi)^{2}e^{4M\zeta}}{[(M + Bi)e^{M} + (M - Bi)e^{-M}]^{2}} + \frac{e^{2M}(M + Bi)^{2}}{[(M + Bi)e^{M} + (M - Bi)e^{-M}]^{2}} \right\}$$
(15)

Using boundary conditions

$$\theta_1(0) = 0$$
 and $\frac{d\theta_1(1)}{d\zeta} = -Bi\,\theta_1(1)$ (16)

the constants C_3 and C_4 can be written as

$$C_{3} = \frac{1}{3 \left[(M - Bi) e^{-M} + (M + Bi) e^{M} \right]^{3}} \left[(6 M^{3} + 6 Bi^{3} - 6 M Bi^{2} - 6 M^{2} Bi) e^{-M} + (2 \epsilon M^{2} - 2 Bi^{3} \epsilon -$$

and

$$C_4 = \frac{1}{3 \left[(M - Bi) e^{-M} + (M + Bi) e^{M} \right]^3} \left[\left(-6 Bi^3 + 6 M^2 Bi - 6 M Bi^2 + 6 M^3 \right) e^{M} + \left(2 \epsilon M^3 - 2 \epsilon M^2 Bi + 3 Bi^3 - 3 M^2 Bi - 3 M Bi^2 - 2 \epsilon M Bi^2 + 2 Bi^3 \epsilon + 3 M^3 \right) e^{-M} + \left(9 M^2 Bi + 9 M Bi^2 + 6 \epsilon M^2 Bi + 6 \epsilon M Bi^2 + 3 Bi^3 + 3 M^3 + 2 \epsilon M^3 + 2 Bi^3 \epsilon \right) e^{3M} - 4 Bi^3 \epsilon + 12 \epsilon M^2 Bi \right]$$
(18)

Similarly, by equating the coefficients of
$$q^2$$
 in Eq. (8), we can write the second order problem as follows:
$$\frac{d^2\theta_2}{d\zeta^2} - M^2\theta_2 + \epsilon\theta_0 \frac{d^2\theta_1}{d\zeta^2} + \epsilon\theta_1 \frac{d^2\theta_0}{d\zeta^2} + 2\epsilon \left(\frac{d\theta_1}{d\zeta}\right) \left(\frac{d\theta_0}{d\zeta}\right) = 0 \tag{19}$$

The solution of Eq. (19) with boundary conditions

$$\theta_2(0) = 0$$
 and $\frac{d\theta_2(1)}{d\xi} = -Bi \theta_2(1)$ (20)

is given by

$$\theta_{2}(\zeta) = C_{5}e^{M\zeta} + C_{6}e^{-M\zeta} - \frac{4}{3}\left[-\frac{1}{4}\left(-\frac{1}{2} + M\zeta\right)C_{2}^{2}C_{1}\epsilon e^{4M\zeta} + \frac{1}{4}C_{2}C_{1}^{2}\left(M\zeta + \frac{1}{2}\right)\epsilon e^{2M\zeta} + C_{4}C_{1}e^{M\zeta} - \frac{9}{16}\epsilon C_{2}^{3}e^{6M\zeta} - \frac{9}{16}\epsilon C_{1}^{3} + C_{3}C_{2}e^{5M\zeta}\right]e^{-3M\zeta}\epsilon$$
(21)

where the constants C_1 , C_2 , C_3 , C_4 are given by Eqs. (12, 17, and 18) and C_5 and C_6 are given by

$$C_{5} = -\frac{-1}{12 \left[(M - Bi) e^{-M} + (M + Bi) e^{M} \right]} \left[\left(12 Bi + 2 Bi C_{2} C_{1}^{2} \epsilon^{2} - 12 M - 9 Bi \epsilon^{2} C_{1}^{3} + 9 M \epsilon^{2} C_{1}^{3} - 9 Bi \epsilon^{2} C_{2}^{3} + 9 M \epsilon^{2} C_{2}^{3} + 16 Bi \epsilon C_{4} C_{1} - 16 M \epsilon C_{4} C_{1} + 16 Bi \epsilon C_{3} C_{2} - 16 M \epsilon C_{3} C_{2} - 2 M C_{2} C_{1}^{2} \epsilon^{2} + 2 Bi C_{2}^{2} C_{1} \epsilon^{2} - 2 M C_{2}^{2} C_{1} \epsilon^{2} \right) e^{-M} + \left(32 M \epsilon C_{4} C_{1} - 16 Bi \epsilon C_{4} C_{1} \right) e^{-2M} + \left(4 \epsilon^{2} M^{2} C_{2}^{2} C_{1} + 2 M C_{2}^{2} C_{1} \epsilon^{2} + 4 Bi \epsilon^{2} M C_{2}^{2} C_{1} - 2 Bi C_{2}^{2} C_{1} \epsilon^{2} \right) e^{M} + \left(-4 Bi \epsilon^{2} C_{2} C_{1}^{2} M - 2 M C_{2}^{2} C_{1}^{2} \epsilon^{2} + 4 \epsilon^{2} C_{2} C_{1}^{2} M^{2} - 2 Bi C_{2}^{2} C_{1}^{2} \epsilon^{2} \right) e^{-M} + \left(27 M \epsilon^{2} C_{2}^{3} + 9 Bi \epsilon^{2} C_{2}^{3} \right) e^{3M} + \left(-32 M \epsilon C_{3} C_{2} - 16 Bi \epsilon C_{3} C_{2} \right) e^{2M} + \left(-27 M \epsilon^{2} C_{1}^{3} + 9 Bi \epsilon^{2} C_{1}^{3} \right) e^{-3M} \right]$$

$$(22)$$

and

$$C_6 \ \ = \ \ -\frac{1}{12 \, \left[(M-Bi) \, e^{-M} + (M+Bi) \, e^{M} \right]} \, \left\{ \left[(32 \, M \epsilon \, C_4 \, C_1 - 16 \, Bi \, \epsilon \, C_4 \, C_1) \, e^{-3M} - 9 \, Bi \, \epsilon^2 C_2^{\ 3} - 4 \, C_1 \, e^{-3M} + (M+Bi) \, e^{M} \right] \, \right\} \, .$$

$$\begin{split} 9\,Bi\,\epsilon^{2}C_{1}{}^{3} + 12\,Bi + 2\,M\,C_{2}\,C_{1}{}^{2}\epsilon^{2} + 2\,M\,C_{2}{}^{2}C_{1}\,\epsilon^{2} + 16\,Bi\,\epsilon\,C_{3}\,C_{2} + 12\,M - 9\,M\,\epsilon^{2}C_{1}{}^{3} \\ + 2\,Bi\,C_{2}\,C_{1}{}^{2}\epsilon^{2} + 16\,M\,\epsilon\,C_{4}\,C_{1} + 16\,Bi\,\epsilon\,C_{4}\,C_{1} + 16\,M\,\epsilon\,C_{3}\,C_{2} - 9\,M\,\epsilon^{2}C_{2}{}^{3} + 2\\ Bi\,C_{2}{}^{2}C_{1}\,\epsilon^{2}\big]\,e^{M} + \big(4\,\epsilon^{2}M^{2}C_{2}{}^{2}_{-}CI + 2\,M\,C_{2}{}^{2}C_{1}\,\epsilon^{2} + 4\,Bi\,\epsilon^{2}M\,C_{2}{}^{2}C_{1} - 2\,Bi\,C_{2}{}^{2}C_{1}\,\epsilon^{2}\big)\,e^{M} + \\ \big(-4\,Bi\,\epsilon^{2}C_{2}\,C_{1}{}^{2}M - 2\,M\,C_{2}\,C_{1}{}^{2}\epsilon^{2} + 4\,\epsilon^{2}C_{2}\,C_{1}{}^{2}M^{2} - 2\,Bi\,C_{2}\,C_{1}{}^{2}\epsilon^{2}\big)\,e^{-M} + \\ \big(27\,M\,\epsilon^{2}C_{2}{}^{3} + 9\,Bi\,\epsilon^{2}C_{2}{}^{3}\big)\,e^{3M} + \big(-32\,M\,\epsilon\,C_{3}\,C_{2} - 16\,Bi\,\epsilon\,C_{3}\,C_{2}\big)\,e^{2M} + \\ \big(-27\,M\,\epsilon^{2}C_{1}{}^{3} + 9\,Bi\,\epsilon^{2}C_{1}{}^{3}\big)\,e^{-3\,M}\big\} \end{split} \tag{23}$$

The dimensionless temperature distribution, therefore, can be written as

$$\theta(\zeta) = \lim_{q \to 1} \left(\theta_0 + q\theta_1 + q^2\theta_2 + \cdots \right)$$

$$= \frac{3}{4} e^{-3M\zeta} \epsilon^2 C_1^3 + \left(C_4 + C_5 - \frac{1}{3} \epsilon^2 \zeta C_2 M C_1^2 + C_1 - \frac{1}{6} \epsilon^2 C_1^2 C_2 \right) e^{-M\zeta} +$$

$$\left(C_3 + C_2 + \frac{1}{3} \epsilon^2 \zeta \Box C_2^2 M C_1 + C_6 - \frac{1}{6} \epsilon^2 C_2^2 C_1 \right) e^{M\zeta} + \left(-\frac{2}{3} \epsilon C_1^2 - \frac{4}{3} \epsilon C_4 C_1 \right)$$

$$e^{-2M\zeta} + \left(-\frac{4}{3} \epsilon C_3 C_2 - \frac{2}{3} \epsilon C_2^2 \right) e^{2M\zeta} + \frac{3}{4} e^{3M\zeta} \epsilon^2 C_2^3$$
(24)

Spine Efficiency

The efficiency of the spine is defined as the ratio of the actual heat transfer rate to the ideal heat transfer rate from the spine if the entire spine were at the base temperature and is given by

$$\eta_f = \frac{\dot{Q}_{spine}}{\dot{Q}_{spine,max}}$$
(25)

where \dot{Q}_{spine} can be obtained by evaluating the energy conducted into the surface at the base and can be written as

$$\dot{Q}_{spine} = -k(T)A_c \left. \frac{dT}{dx} \right|_{x=0}$$

$$= -\frac{k_a A_c}{\mathcal{L}} (T_b - T_a) (1 + \epsilon \theta) \left. \frac{d\theta}{d\zeta} \right|_{\zeta=0}$$
(26)

and $\dot{Q}_{spine,max}$ can be obtained by evaluating the energy convected from the spine surface to the surrounding medium and can be written as

$$\dot{Q}_{spine,max} = h (A_s + A_c) (T_b - T_a) \qquad (27)$$

where A_s is the surface area of the spine. Assuming unit length of the spine, Eq. (25) can be written as

$$\eta_{spine} = -\frac{1}{M^{2}(1+\mathcal{L})} (1+\epsilon\theta) \frac{d\theta}{d\zeta}\Big|_{\zeta=0} \\
= -\frac{1}{144M(1+\mathcal{L})} (12+12\epsilon C_{1}e^{M}+12\epsilon C_{2}e^{-M}+12\epsilon C_{4}e^{M}+12\epsilon C_{3}e^{-M}-8\epsilon^{2}C_{1}{}^{2}e^{2M} \\
-8\epsilon^{2}C_{2}{}^{2}e^{-2M}-4\epsilon^{3}MC_{2}{}^{2}C_{1}e^{-M}+4\epsilon^{3}MC_{2}C_{1}{}^{2}e^{M}+12\epsilon e^{-M}C_{6}+12\epsilon C_{5}e^{M} \\
-2\epsilon^{3}C_{2}{}^{2}C_{1}e^{-M}-16\epsilon^{2}C_{3}C_{2}e^{-2M}-2\epsilon^{3}C_{2}C_{1}{}^{2}e^{M}-16\epsilon^{2}C_{4}C_{1}e^{2M}+9\epsilon^{3}C_{1}{}^{3}e^{3M} \\
+9\epsilon^{3}C_{2}{}^{3}e^{-3M}) (2\epsilon^{2}C_{2}C_{1}{}^{2}+12C_{5}+12C_{1}+12C_{4}-2\epsilon^{2}C_{2}{}^{2}C_{1}-12C_{2}-12C_{3}-12C_{6} \\
-32\epsilon C_{4}C_{1}-16\epsilon C_{1}{}^{2}+16\epsilon C_{2}{}^{2}+32\epsilon C_{3}C_{2}-27\epsilon^{2}C_{2}{}^{3}+27\epsilon^{2}C_{1}{}^{3}) \tag{28}$$

where the constants C_1 through C_6 can be determined from Eqs. (12, 17, 18, 22, and 23).

RESULTS AND DISCUSSION

The spine performance parameter M for each spine is based on the performance parameter of circular spine

under the same environment and same thermal conditions. These performance parameters for each spine are presented in Table 1.

The effect of temperature dependent thermal conductivity and Biot number on dimensionless temperature distribution is shown in Fig. 2. As expected, the temperature decreases along the spine in each case for every cross section. The temperature at the tip of a circular spine is highest in each case and it decreases with the increase in Biot number, whereas the temperature for the elliptical cross section is minimum. The effect of temperature dependent thermal conductivity on temperature increases along the spine. It increases with the increase in the temperature dependent parameter ϵ .

The performance of each spine for different Biot numbers is compared in Fig. 3. For smaller axis ratios ϵ_1 and ϵ_2 , the efficiencies of rectangular and elliptical cross sections are highest and approaches to square and circular cross sections with increase in axis ratios. The increase in thermal conductivity lowers the efficiency of each cross section for a fixed Biot number. It is also noticed that the efficiency of each cross section increases with the increase in Biot number. This is mainly due to the fact that for the same length and material of the spine, Biot number depends directly on the heat transfer coefficient h, that increases the heat transfer and hence the efficiency of each cross section.

SUMMARY AND CONCLUSIONS

Homotopy perturbation method (HPM) is successfully employed to investigate the effects of temperature dependent thermal conductivity and Biot number on the dimensionless temperature distribution and efficiency of spines of arbitrary uniform cross sections (rectangular, square, elliptical and circular) in still ambient air. For fair comparison of different cross sections, calculations are performed for equal cross sectional areas. It is observed that

- 1. Temperature at the tip of each cross section increases with increase in thermal conductivity
- Temperature at the tip decreases with the increase in Biot number
- Efficiency of circular cross section is lowest while the efficiencies of elliptical and rectangular sections are highest for smaller axis ratios.
- 4. In the limiting case, when the axis ratios ε₁, ε₂ → 1, the efficiency of the rectangular cross section approaches to that of square and the efficiency of elliptical cross section approaches to that of circular.

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Table 1: Parameters for different cross sections of spines

Parameters	Cross Sections				
	Rectangular	Circular	Square	Elliptical	
L	$\frac{\sqrt{\pi \epsilon_2}}{(1 + \epsilon_2)} \mathcal{L}_C$	$\mathcal{L}_C = d/4$	$\frac{\sqrt{\pi}}{2} \mathcal{L}_C$	$\frac{\pi \sqrt{\epsilon_1}}{2E(e)}\mathcal{L}_C$	
A_c	tb	$\pi d^2/4$	s^2	$\pi a b$	
p	2(b+t)	πd	4s	4 a E(e)	

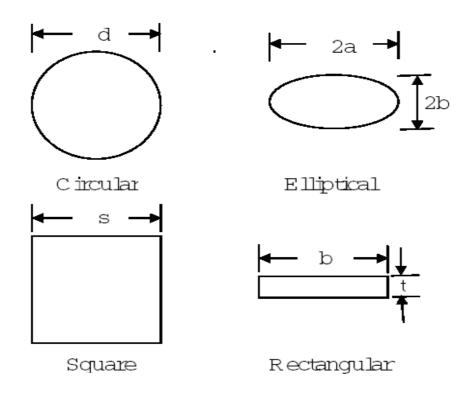


Figure 1: Cross Sections of Spines.

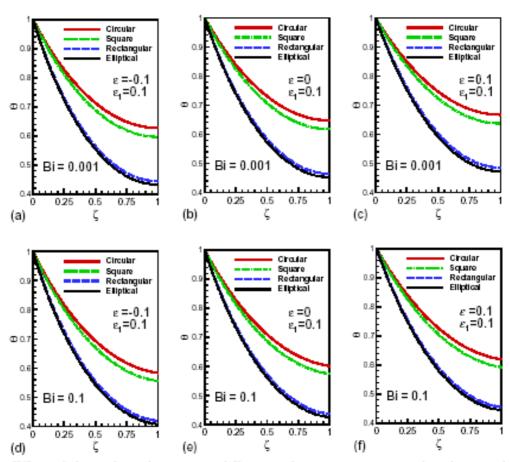


Figure 2: Effect of thermal conductivity and Biot number on temperature distribution along spines.

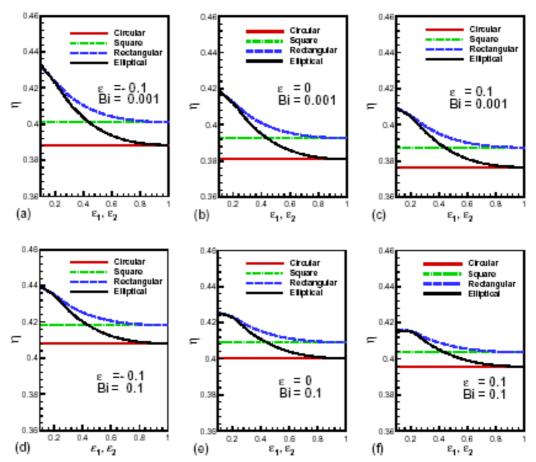


Figure 3: Effect of thermal conductivity and Biot number on efficiency of spines.