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Nonlinear Multiparameter Problems in Banach Space

By

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ABSTRACT

In this paper we study the problems of existence and uniqueness of solution to the nonlinear multiparameter problems of the form

Au +
$$\sum_{j=1}^{n} \lambda_j B_j u = f$$
,

where A, B_j : $X \to X^*$ are mappings from a reflexive Banach space X into its dual space X^* , satisfying certain monotonicity conditions, $f \in X^*$, and λ_j (j=1,2,...,n) are in general complex parameters.

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1. <u>Introduction</u>

In this paper we study the problems of existence and uniqueness of solution to the nonlinear multiparameter problems of the form

$$Au + \sum_{j=1}^{n} \lambda_{j} B_{j}u = f,$$

where A, B_j: $X \rightarrow X^*$ are mappings from a reflexive Banach space X into its dual space X^* , satisfying certain monotonicity conditions, $f \in X^*$, and λ_j (j=1,2,...,n) are in general complex parameters.

Application of the developed theory to the nonlinear Sturm Liouville's problem for ordinary differential equations in \mathbf{L}^p spaces is also given.

The study of multiparameter systems of equations has also been discussed as a straightforward extension to the case of a single multiparameter problem.

Our analysis in this paper is an extension, to the Banach space case, of that given by Amer[3], Amer and Roach[4].

2. Definitions And Basic Results

Let X be a real Banach space, X^* its conjugate space. For y in X^* , x in X, denote the value of y at x by (y,x). If T is a mapping (in general nonlinear) with domaine D(T) in X and range R(T) in X^* . We recall the following definitions.

Definition 2.1. (1) The mapping T: $X \supseteq D(T) \rightarrow X^*$ is said to be monotone if

 $(Tx-Ty,x-y) \geqslant 0$, for all $x,y \in D(T)$.

- (2) We call that T is strictly monotone if (Tx-Ty,x-y)>0, for all $x,y\in D(T)$, $x\neq y$.
- (3) We call that T is strongly monotone if (Tx-Ty,x-y) > c||x-y||, for some c > 0.

<u>Definition 2.2.</u> The mapping $T: X \rightarrow X^*$ with D(T)=X is called coercive from X to X^* iff there exists a continuous function $\alpha: \mathbb{R}^+ \to \mathbb{R}$ with $\alpha(r) \to +\infty$ as $r \to +\infty$ and such that

 $(Tx,x) \geqslant \infty(||x||) ||x||,$ for all $x,y \in D(T)$.

<u>Definition 2.3.</u> The mapping T: $X \ge D(T) \to X^*$ is said to be hemicontinuous if T is continuous on every line segement s of D(T) (with respect to the strong topology on s and the weak topology in the range) i.e. if the function $f : R \rightarrow R$ defined by

 $f(\lambda) = (T(x+\lambda y),z), x,y \in D(T), z \in X, \lambda \in R$ is continuous function of λ .

For the sake of completeness we introduce without proof the following result given by Browder [1], [2]. Theorem 2.1. Let X be a real reflexive Banach space. If T: $X \rightarrow X^*$ is monotone, hemicontinuous and coercive mapping defined on the whole of X, then the range R(T) is all of X^* . Theorem 2.2. If in addition to the assumption of Theorem 2.1. that T is strictly monotone, then the mapping T is bijective.



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3. Main Results

We shall use Theorem 2.1. and Theorem 2.2. for establishing the existence and uniqueness of solution for two-parameter problems of the form

(3.1)
$$(A + \sum_{j=1}^{2} \lambda_{j} B_{j})x = f \in X^{*},$$

where the mapping A, $B_j(j=1,2)$: $X \rightarrow X^*$ are assumed to be strongly monotone and hemicontinuous from X to X^* with domains the whole space X. Extension of the obtained results to the case of n-parameter $(n \geqslant 3)$ is straightforward. Moreover, treating each equation sperately we can extend our results to examine two-parameter systems of the form

$$(A_k + \sum_{s=1}^{2} \lambda_{ks} B_{ks}) x_k = f_k \in X_k^*, x_k \in X_k, k=1,2.$$

Theorem 3.1. Let X be a real reflexive Banach space and assume that the mappings A, $B_j(j=1,2): X \rightarrow X^*$ satisfy the following conditions

(i)
$$D(\bar{A}) = D(B_j) = X, j=1,2.$$

(ii)
$$A(\theta) = B_{j}(\theta) = \theta, \quad j=1,2.$$

(iii) A ,B $_{j}$ (j=1,2) are hemicontinuous mappings from X to X * .

(iv) A, $B_{j}(j=1,2)$ are strongly monotone with constants c,c_{j}

: (j=1,2) respectively.

Then for every $f \in X^*$ and $\lambda_1, \lambda_2 \in R$ satisfying

(3.2)
$$(c^{i} + \sum_{j=1}^{2} \lambda_{j} c_{j}) > 0$$

equation (3.1) has one and only one solution $x \in X$.

Proof. Define a mapping T: $X \to X^*$ by

$$Tx = (A + \sum_{j=1}^{2} \lambda_j B_j)x.$$

We have by (i), $T(\theta) = \theta$.

. By condition (i), (iii) it follows that

$$D(T) = D(A) \bigcap_{j=1}^{2} D(B_{j}) = X,$$

and T is hemicontinuous from X to X^* . Assume that λ_j (j=1,2) are chosen such that (3.2) holds, then

$$(Tx-Ty,x-y) = (Ax-Ay,x-y) + \sum_{j=1}^{2} \lambda_{j} (B_{j}x-B_{j}y,x-y)$$

$$\Rightarrow (c + \sum_{j=1}^{2} \lambda_{j} c_{j}) ||x-y||, \text{ for all } x,y \in D(T).$$

Therefore, T is strongly monotone and hence strictly monotone mapping from X to X^* . Furthermore, we have from (ii), (iv)

$$(\mathbf{T}\mathbf{x},\mathbf{x}) = (\mathbf{A}\mathbf{x} - \mathbf{A}\boldsymbol{\theta}, \mathbf{x} - \boldsymbol{\theta}) + \sum_{j=1}^{2} \lambda_{j} (\mathbf{B}_{j}\mathbf{x} - \mathbf{B}_{j}\boldsymbol{\theta}, \mathbf{x} - \boldsymbol{\theta})$$

$$\geqslant (\mathbf{c} + \sum_{j=1}^{2} \lambda_{j} \mathbf{c}_{j}) \|\mathbf{x}\|.$$

If we define a function $\infty: \mathbb{R}^+ \to \mathbb{R}^+$ by

$$\propto (||x||) = (c + \sum_{j=1}^{2} \lambda_j c_j) ||x||,$$

then, T is coercive from X to X*. Therefore by Theorem 2.1. and 2.2. applied to the mapping T we have the required result.

Remark 3.1. (1) Theorem 3.1. still valid if the constants

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c, $c_{j}(j=1,2)$ are only assumed to be real numbers.

(2) If the strong monotonicity of A is replaced by only monotonicity assumption, then Theorem 3.1. still holds provided that (3.2) is replaced by the condition

$$(3.3) \qquad \qquad \sum_{j=1}^{2} \lambda_{j} c_{j} > 0.$$

- (3) If all the mappings A, B_j (j=1,2) are supposed to be strictly monotone then, Theorem 3.1. still valid provided that λ_1 , $\lambda_2 > 0$.
- (4) If all the mappings A, $B_j(j=1,2)$ are assumed to be monotone, then we still have existence of solution of equation (3.1) provided λ_1 , $\lambda_2 \geqslant 0$ while uniqueness of solution is not guaranteed, since in this case the mapping T is no longer strictly monotone.
- (5) Assumption (ii) of Theorem 3.1. can be dropped without affecting the result of the theorem, by defining the mappings

A,
$$B_{j}(j=1,2) : X \rightarrow X^{*}$$
 by
$$Ax = Ax - A\theta,$$

$$B_{j}x = B_{j}x - B_{j}\theta, \quad (j=1,2).$$

4. Practical Example

Consider the two-parameter Strum Liouville's problem for ordinary differntial equation of the form

(4.1)
$$(-|\dot{y}(x)|^{p-2}\dot{y}(x)) + \sum_{j=1}^{2} \lambda_{j} a_{j}(x)|y(x)|^{p-2}y(x)=f, x \in [a,b]$$

Subject to the homogeneous boundary condition

$$(4.2)$$
 $y(b) = y(a) = 0,$

where $\geqslant 2$, $\lambda_j \in \mathbb{R}$, a_j , $f \in C[a,b]$, j=1,2.

Let

$$(v,u) = \int_{a}^{b} u(x) v(x) dx$$

be the natural pairing between u in $X=L^p[a,b]$ and v in $X^*=L^q[a,b]$ with q=p/(p-1) and define the mappings

A,
$$B_j(j=1,2) : X \rightarrow X^*$$
 as follows

$$Au = (-|u(x)|^{p-2}u(x)),$$

$$B_{j}u = a_{j}(x)|u(x)|^{p-2}u(x), \quad (j=1,2).$$

For each u, v & X we have

$$(Au-Av,u-v) = \int_{a}^{b} -(|u(x)|^{p-2}u(x)-|v(x)|^{p-2}v(x)) (u(x)-v(x)) dx$$

Thus integ rating by parts we get

$$(Au-Av,u-v) = \int_{a}^{b} (|u(x)|^{p-2}u(x)-|v(x)|^{p-2}v(x)) (u(x)-v(x)) dx$$

$$= \int_{a}^{b} (|u'(x)|^{p-1} \operatorname{sgn} u'(x) - |v'(x)|^{p-1} \operatorname{sgn} v'(x)) (u'(x) - v'(x)) dx$$

Using the inequality

$$(x-y) (|x+u|^{r-1} sgn(x+u)-|y+u|^{r-1} sgn(y+u)) > |x-y|/2^r$$
 [5].



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we get

$$(Au-Av,u-v) \ge \int_{a}^{b} |u(x)-v(x)||^{p} 2^{p-1} dx$$

= $||u(x)-v(x)||^{p} 2^{p-1} > 0$

Therefore, A is strictly monotone mapping from X to X^* .

Similarly, we can prove that $B_{j}(j=1,2)$ is a strictly monotone

mapping from X to X* when assuming that

$$c_j = \min a_j(x) > 0.$$

Hence, equation (4.1) with the boundary condition (4.2) reduces to an equation of the form

Au +
$$\sum_{j=1}^{2} \lambda_j B_j u = f \in X^*$$
,

which by Remark 3.1. (3) has for every element $f \in X^*$ exactly one solution $u \in X$ provided that $\lambda_1, \lambda_2 > 0$.

5 . Concerning The Complex Case

Now we extend the result of Theorem 3.1. by allowing the Banach space X as well as the parameters λ_1 , λ_2 to be complex. To this end we introduce the following generalized definitions.

Let X be a complex Banach space, X^* its conjugate space with pairing between y in X^* and x in X denoted by (y,x) and let $T: X \rightarrow X^*$ be the mapping with domain $D(T) \subseteq X$. We denote by Re(y,x) and Im(y,x) the real and imaginary parts of (y,x), respectively.



Del mition 5.1. (1) The mapping T: $X \ge D(T) \rightarrow X^*$ is said to be monotone if

Re(Tx-Ty,x-y)> 0, for all $x,y \in D(T)$.

(2) T is said to be strictly monotone if Re(Tx-Ty,x-y)>0, for all x,y \in D(T), x \neq y.

(3) We call that T is strongly monotone if Re(Tx-Ty,x-y)> c ||x-y||, for some c > 0.

<u>Definition 5.2.</u> The mapping $T: X \rightarrow X^*$ with domain the whole space X is called coercive from X to X iff there exists a continuous function $\alpha: \mathbb{R}^+ \to \mathbb{R}$ with $\alpha(r) \to +\infty$ as $r \to +\infty$ and such that

 $Re(Tx,x) \geqslant \propto (||x||) ||x||$, for all $x \in X$.

We are now able to state the following theorem Theorem 5.1. Let X be a complex reflexive Banach space. . Let $T:X \to X^*$ be a monotone, coercive and hemicontinuous mapping from X to X^* , then the range of T is the whole space X^* If in addition T is strictly monotone, then T is one-to-one. Theorem 3.1. can also be extended to the following theorem Theorem 5.2. Let X be a complex reflexive Banach space, and let A, $B_{j}(j=1,2): X \rightarrow X^{*}$ be mappings such that

(i) $D(\bar{A}) = D(B_j) = X$, (j=1,2).

(ii) $A(\theta) = B_{j}(\theta) = \theta$, (j=1,2).

(iii) A is hemicontinuous from X to X^* .

(iv) A, $B_j(j=1,2)$ are strongly monotone from X to X^* with constants c, $c_j(j=1,2)$ respectively.



(v) $B_j(j=1,2)$ satisfies a Lipschitz condition from X to X* with a Lipschitz constants $L_j(j=1,2)$.

Then for every given element f C X the equation

(5.1) Ax +
$$\sum_{j=1}^{2} \lambda_j B_j x = f \in X^*, x \in X, \lambda_1, \lambda_2 \in C$$

has a unique solution $x_0 \in X$ provided that $\lambda_j = \xi_j + i \gamma_j \in C$, j=1,2. are such that

(5.2)
$$c + \sum_{j=1}^{2} (c_j \xi_j - L_j \gamma_j) > 0, \xi_j > 0, j=1,2.$$

Remark 5.1. $(\frac{1}{2})$ If $\lambda_j(j=1,2) \in \mathbb{R}$, then the requirement that the mapping $B_j(j=1,2)$ should satisfy Lipschitz condition can be relaxed to requiring that $B_j(j=1,2)$ should be hemicontinuous from X to X^* . The assertion of Theorem 5.2. then remains valid provided that condition (5.2) is replaced by the condition

$$c + \sum_{j=1}^{2} \lambda_{j} c_{j} > 0.$$

(ii) If the mapping B_j (j=1,2) are assumed to be linear, then the requirement of Theorem 5.2. that B_j (j=1,2) should satisfy a Lipschitz condition reduces to requiring that B_j (j=1,2) should be bounded in X.

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